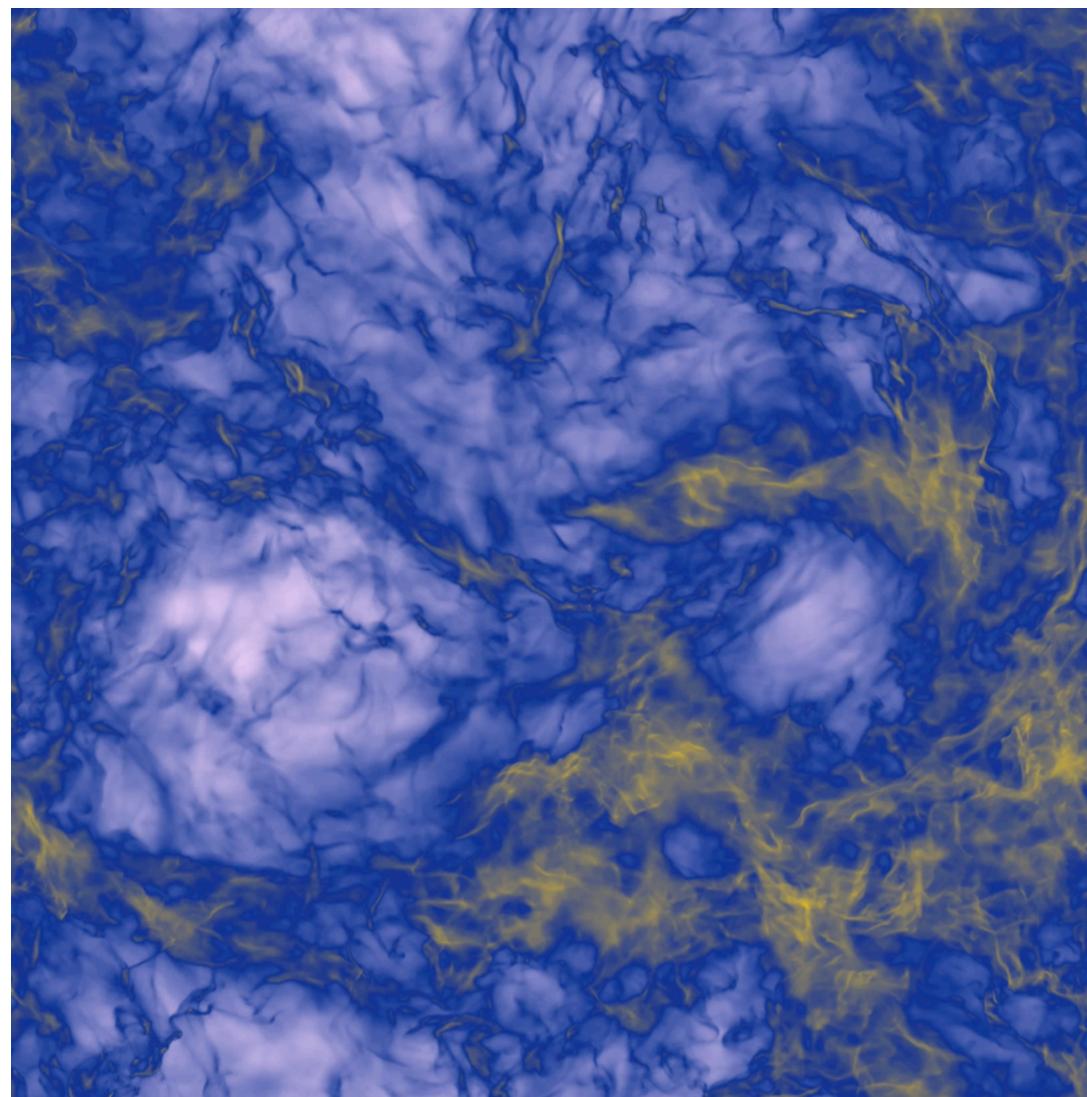
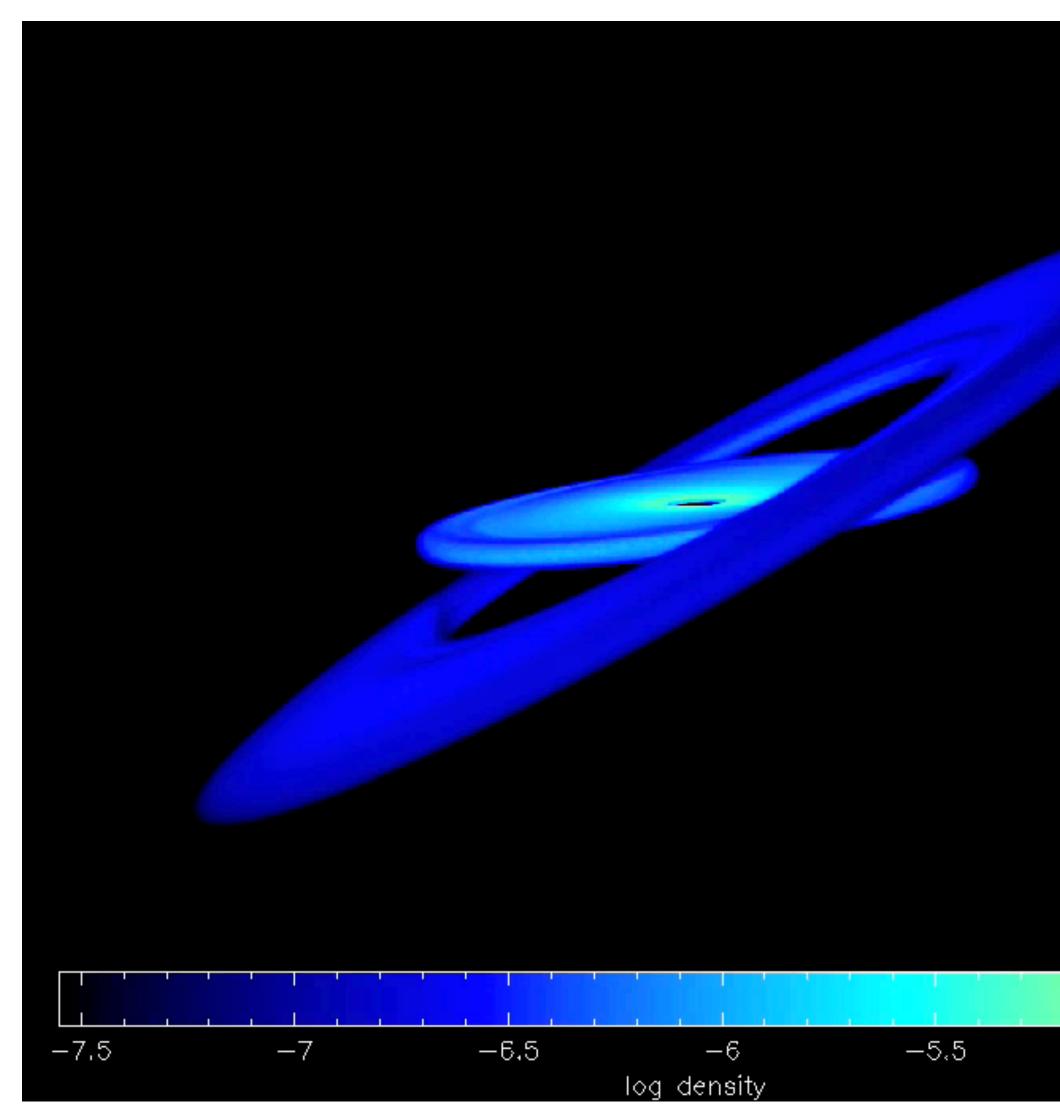
SPH methods for astrophysical fluid dynamics

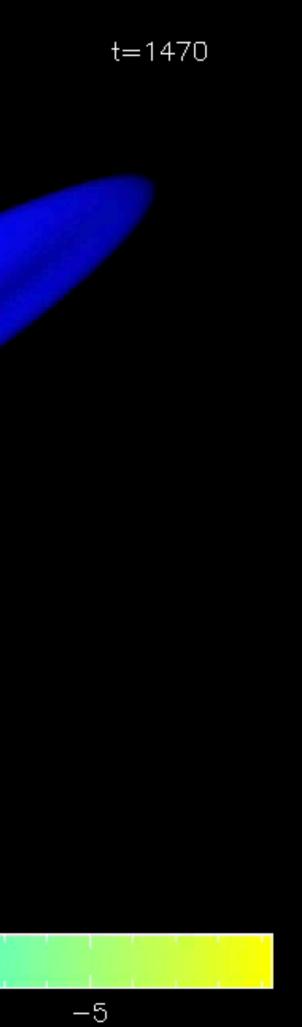
Giuseppe Lodato - Università degli Studi di Milano



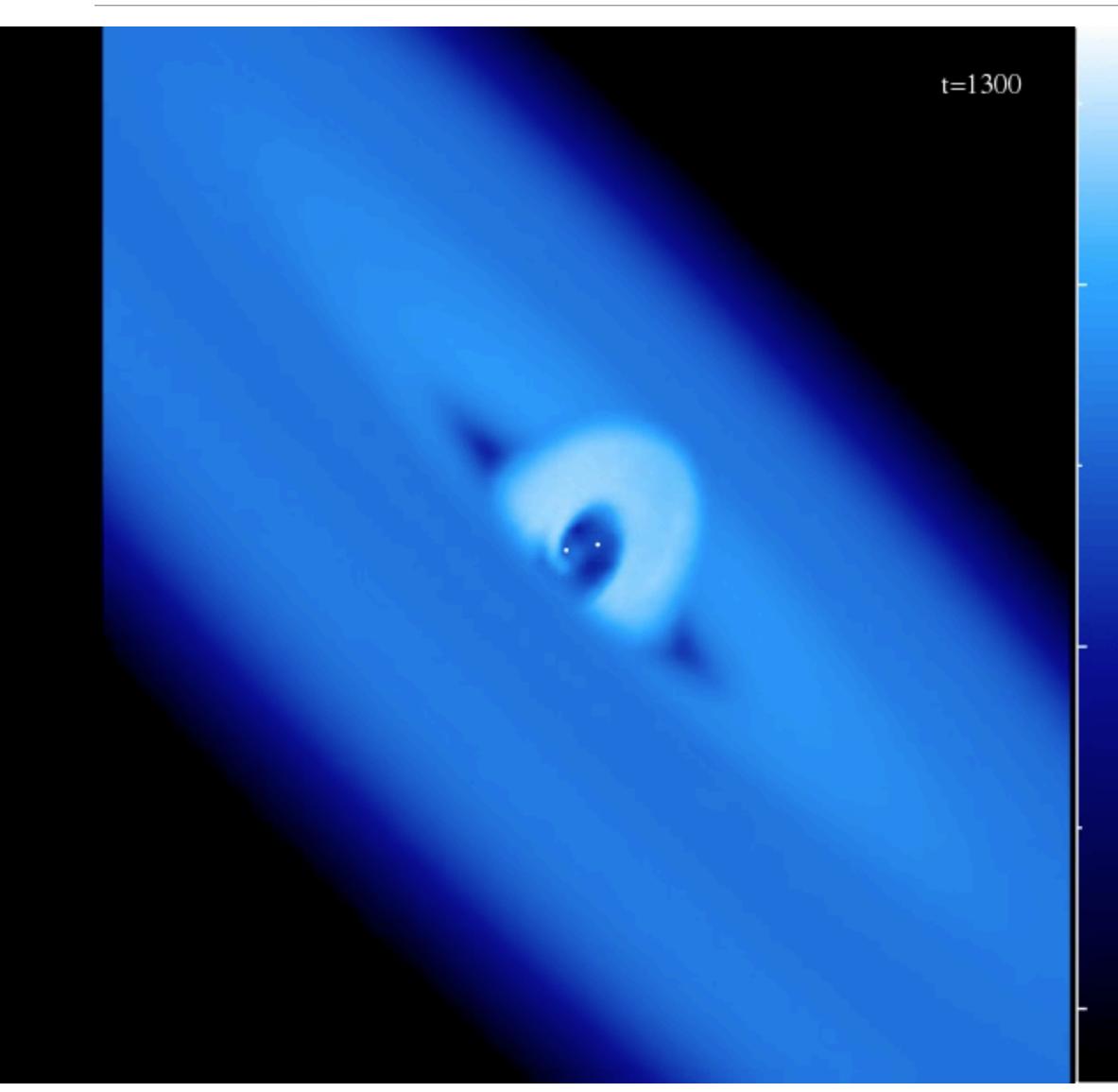


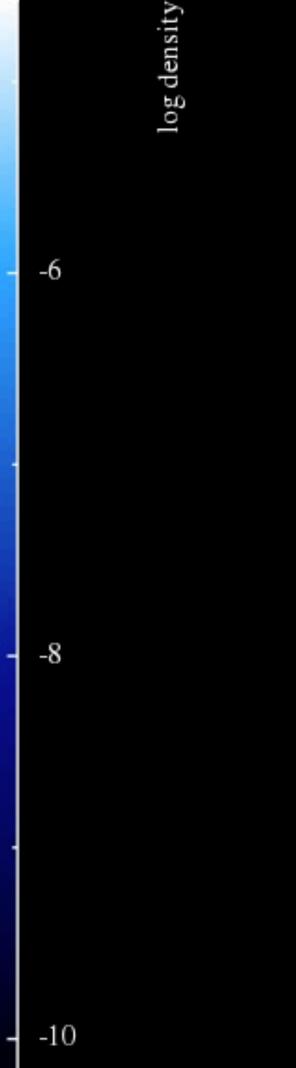
Supersonic turbulence in a box (Price & Federrath 2010)





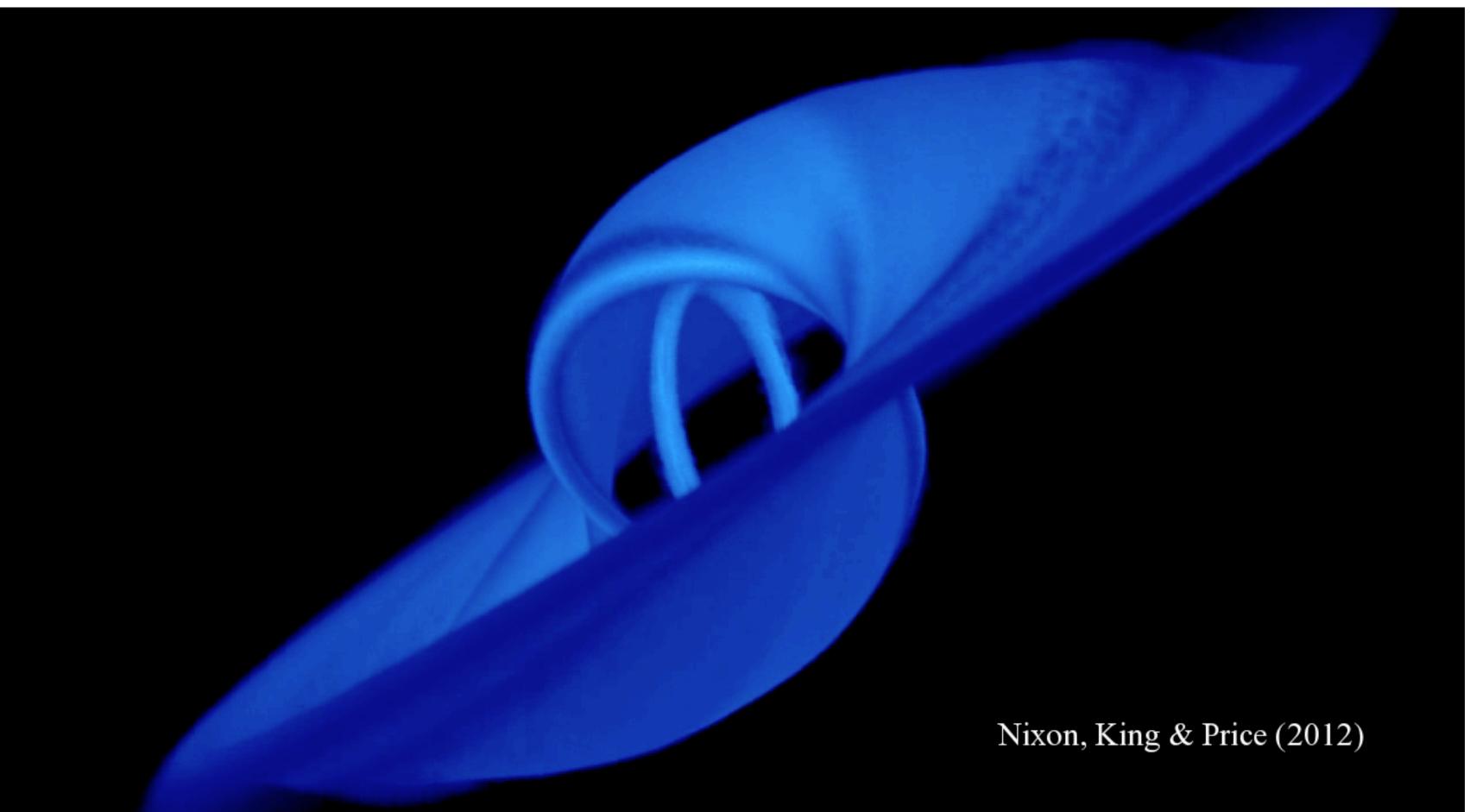
Disc breaks Lodato & Price 2010





Disc breaks around binary stars (Facchini, Lodato & Price 2013)





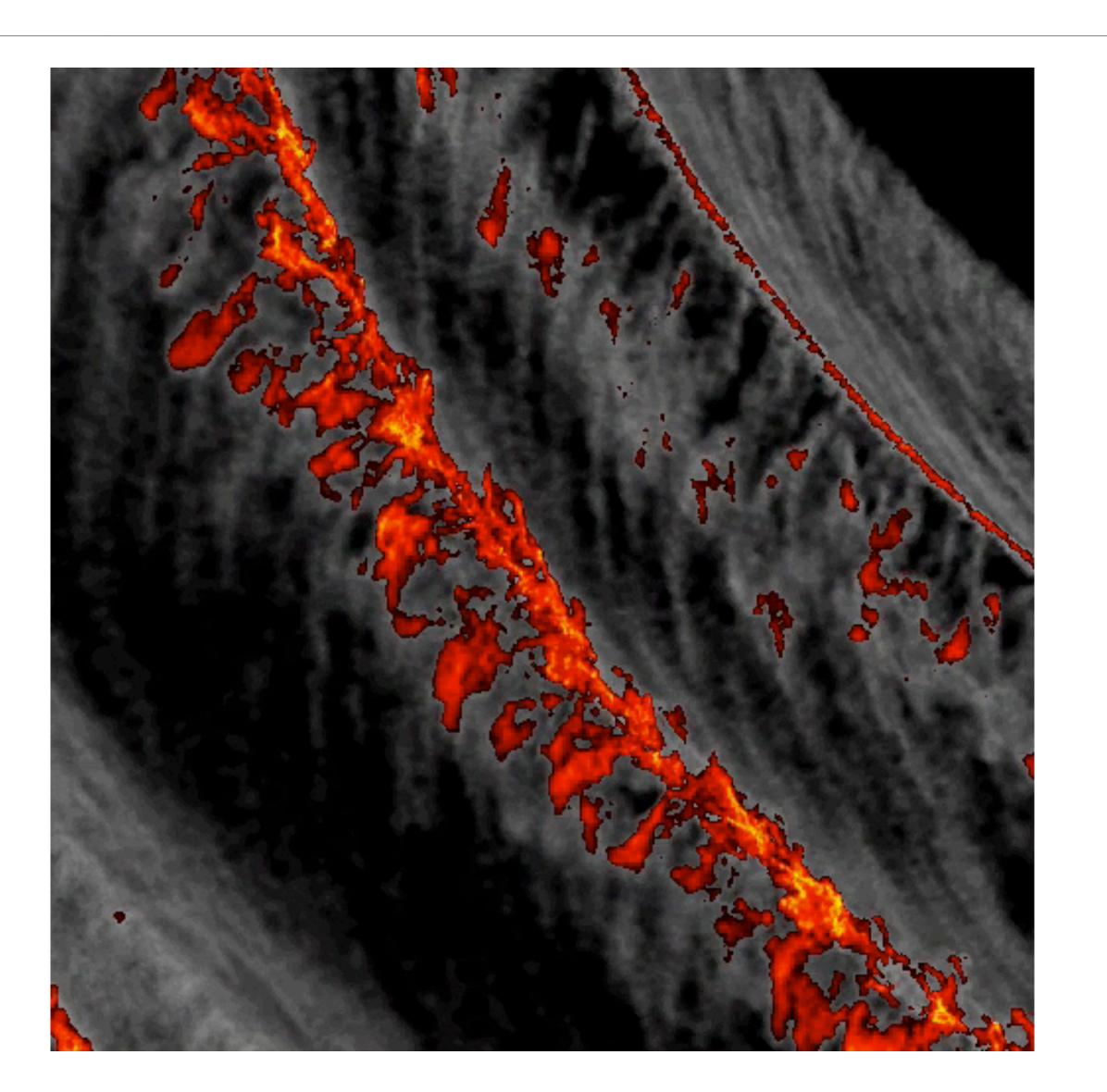
Lense-Thirring precession around spinning black holes

Disc breaks around black holes

(Nixon, King & Price (2012)





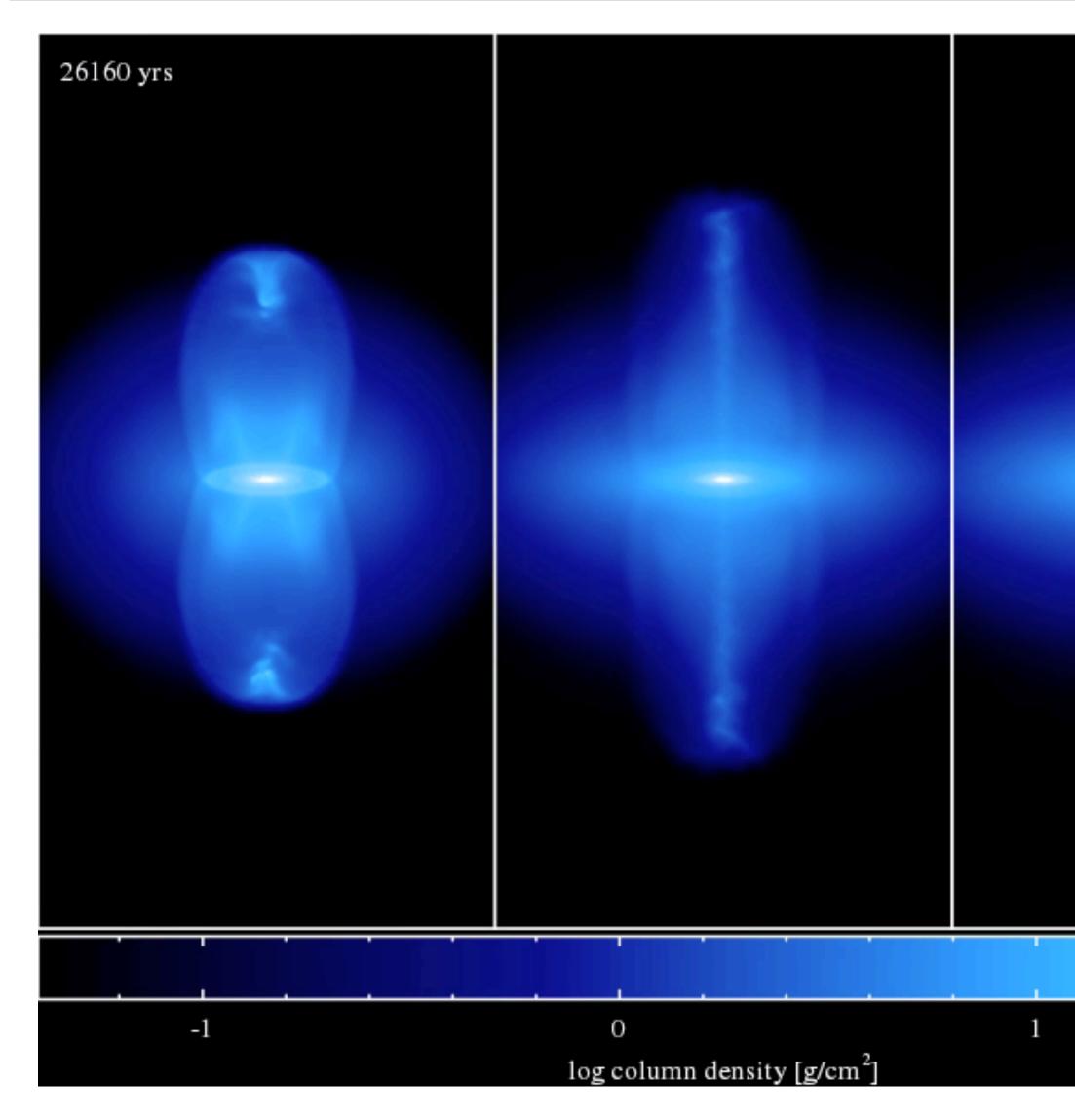


Two fluids simulations

Molecular cloud formation in the galaxy

(Dobbs, Price, Pringle)



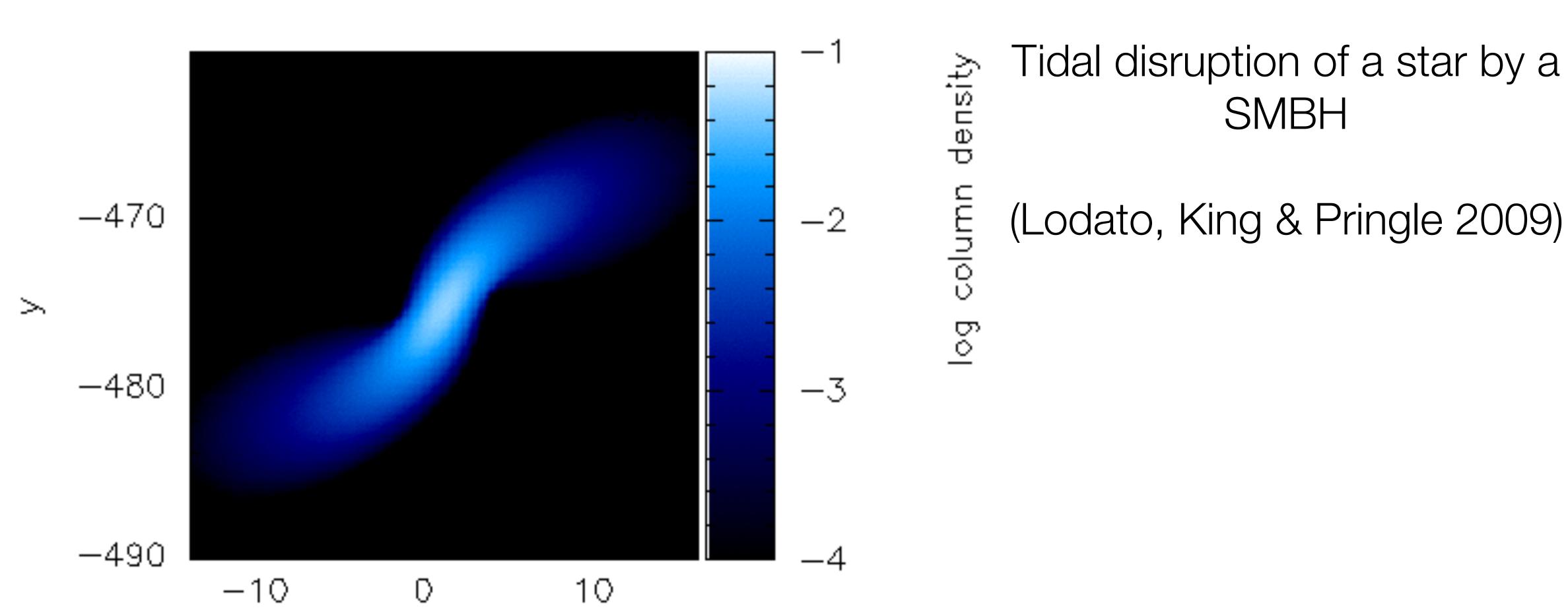


MHD included



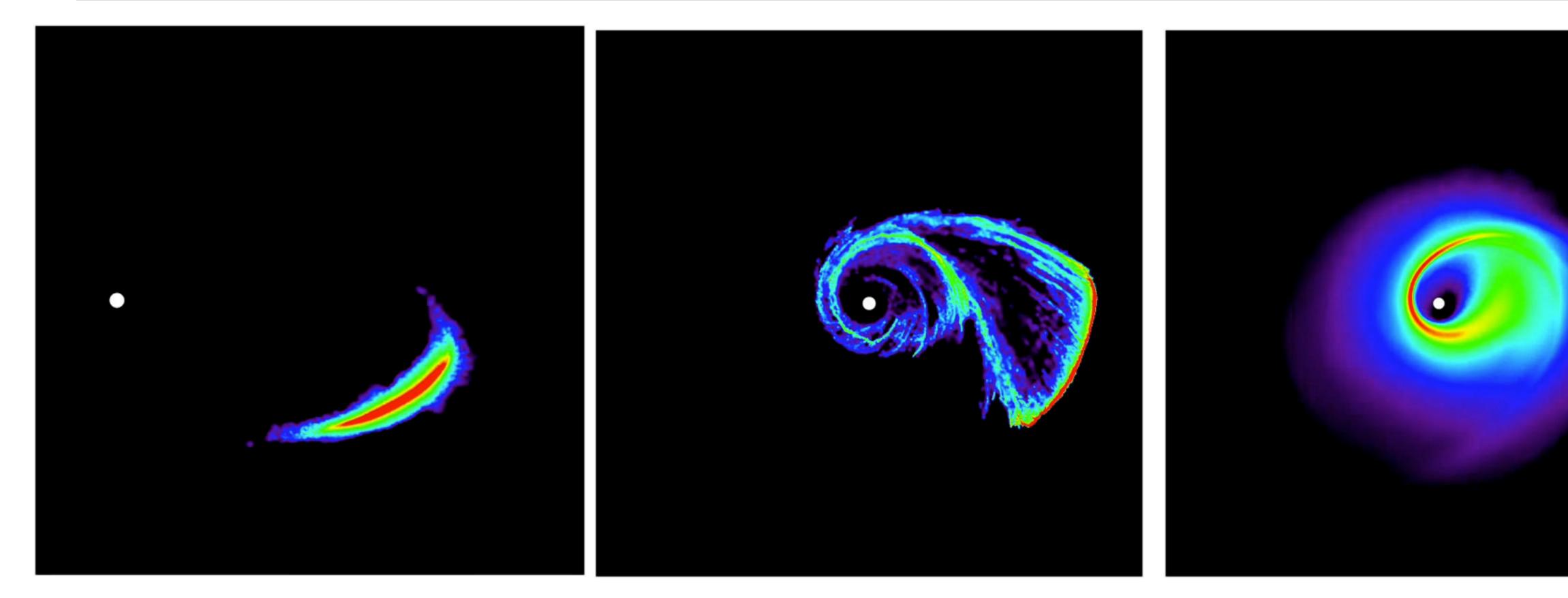
Jet formation during star formation

(Price, Tricco, Bate, 2012)







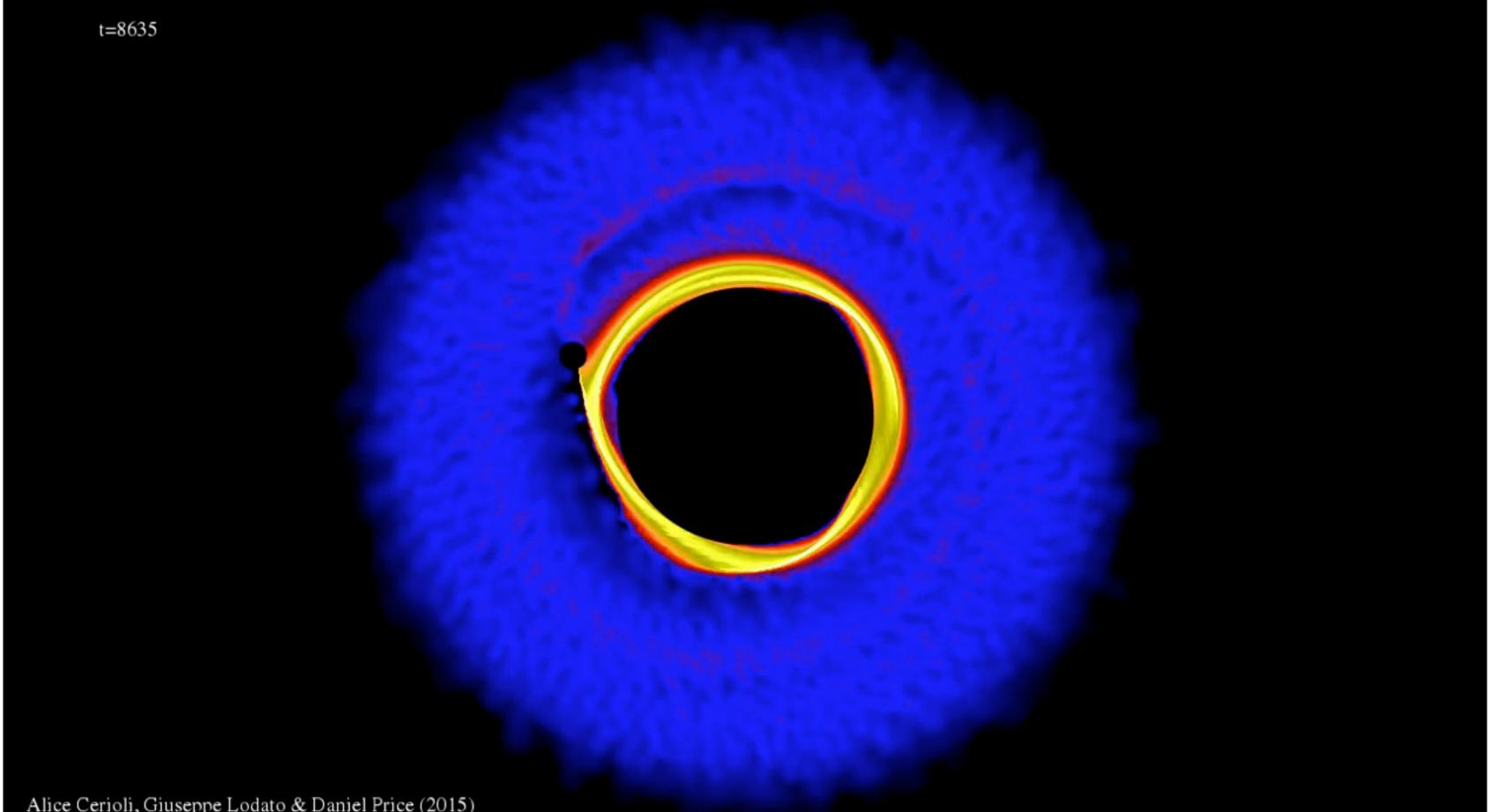


Einstein's precession in the potential

Tidal disruption of a star by a SMBH: disc formation

Bonnerot, Rossi, Lodato & Price (2016)



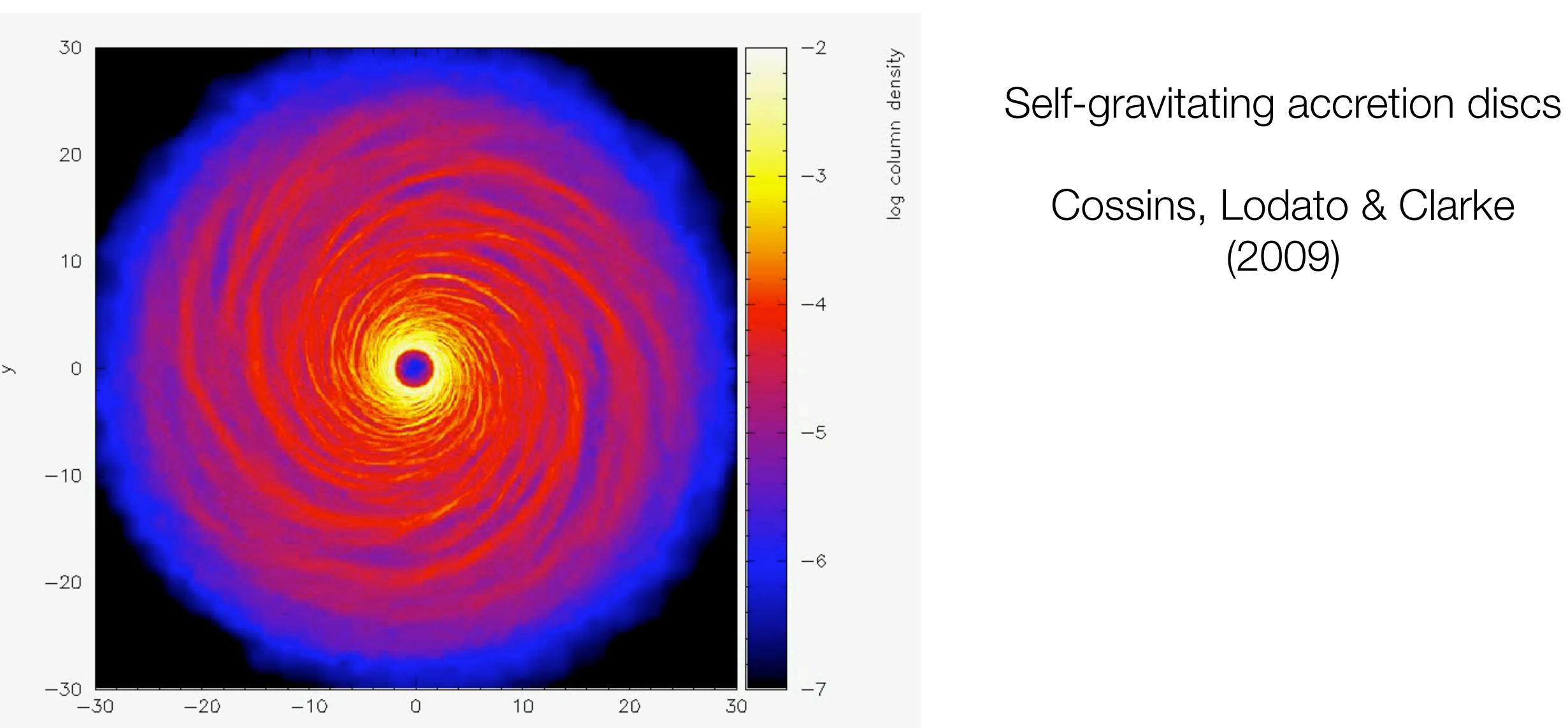


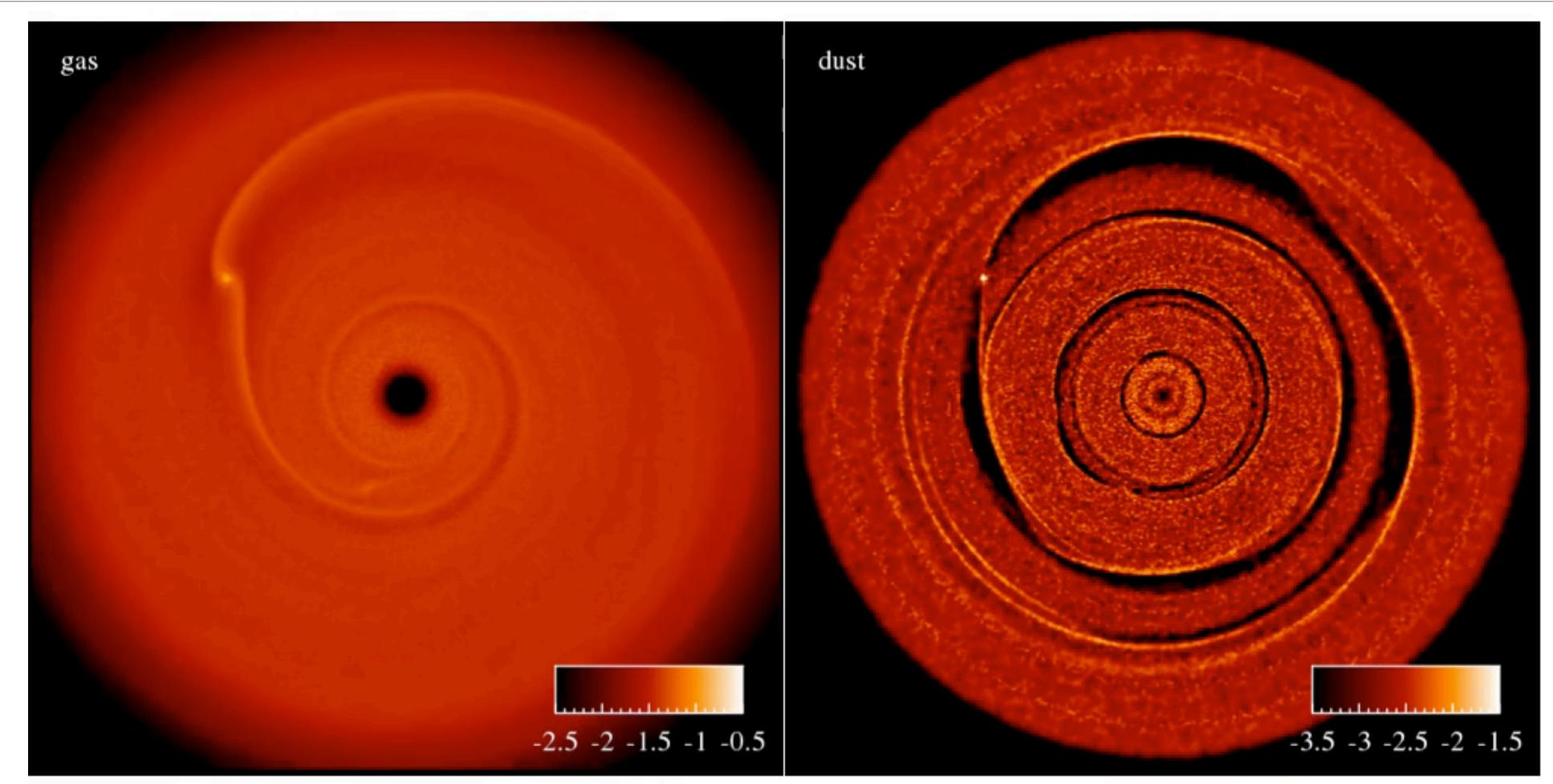
Alice Cerioli, Giuseppe Lodato & Daniel Price (2015)

Electromagnetic counterparts to gravitational waves Cerioli, Lodato & Price (2016)

Gravitational wave induceddecay of the binary







Coupled dust-gas dynamics in protostellar discs Dipierro et al (2015)

Summary

- **SPH** basics •
- Advanced SPH
- A few applications to protostellar disc dynamics in the ALMA era

Grid-based codes vs SPH

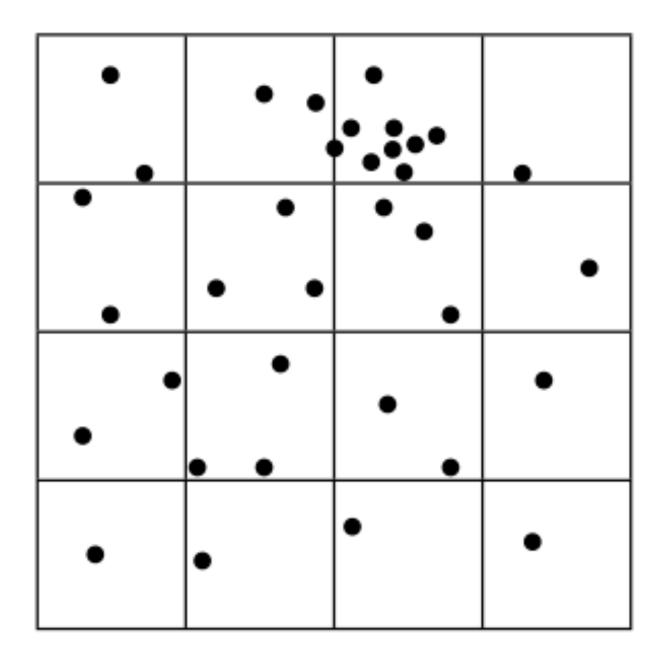
- **spatial grid** -- inherently Eulerian
 - Very well developed techniques (high order, low dissipation,...)
 - Easy to deal with boundary conditions ullet
 - The grid dictates a symmetry to the problem X •
- Lagrangian
 - Resolution follows density easy to obtain large dynamical range
 - Galilean invariance 🗸
 - conditions X

Traditionally, numerical methods for hydrodynamics are based on **discretization on a**

Main idea for SPH: discretization in mass -- discrete fluid elements: inherently

• Difficult to handle shocks, difficult to include MHD, difficult to implement boundary

point masses

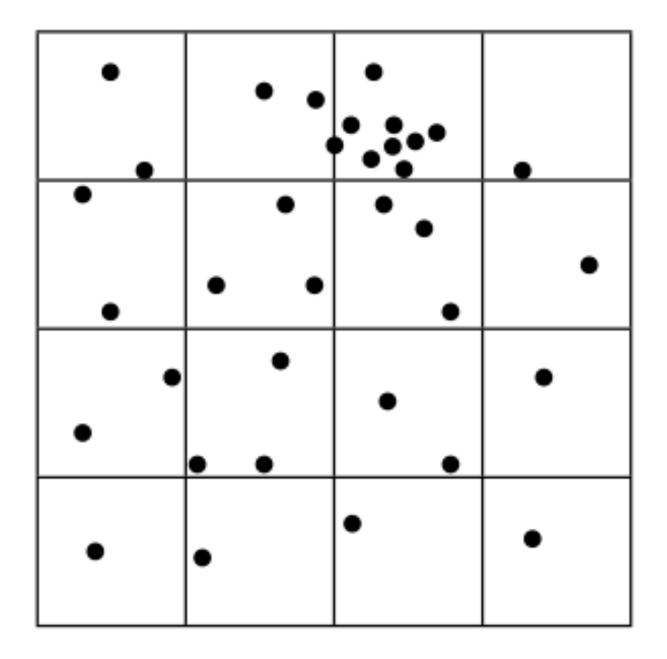


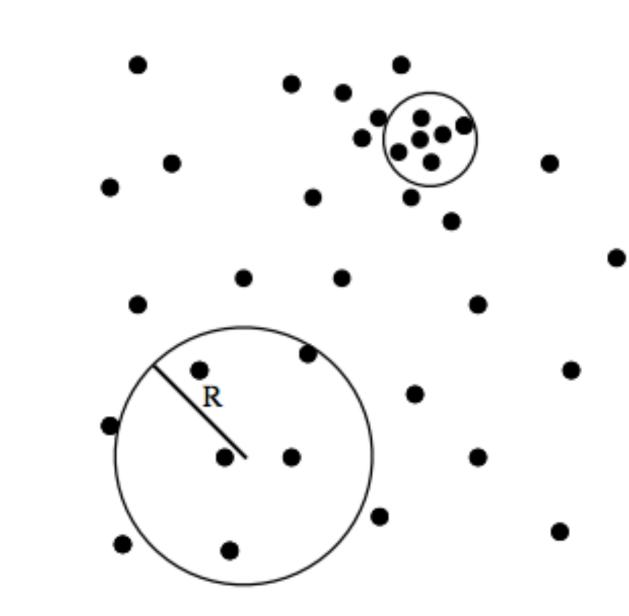


Fundamental idea behind SPH: how to compute density from a collection of

Method 1: construct a mesh around the points, then sum particles within cell and divide by cell volume

 Fundamental idea behind SPH: hov point masses

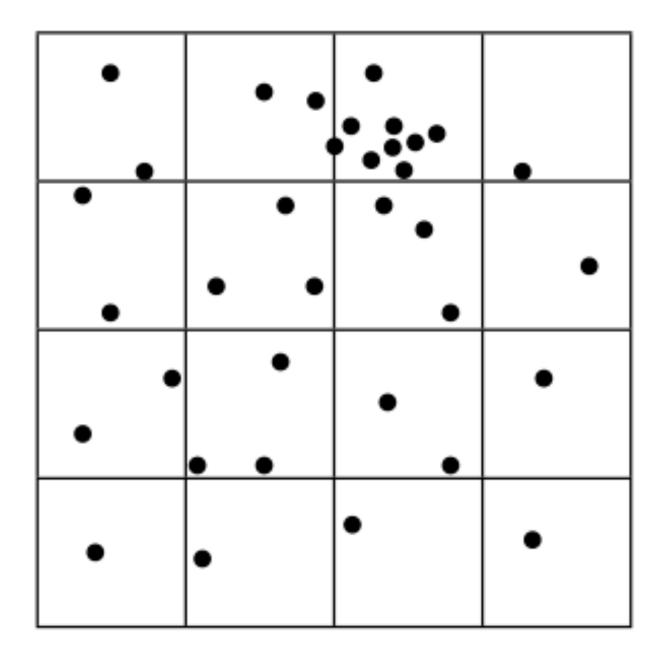


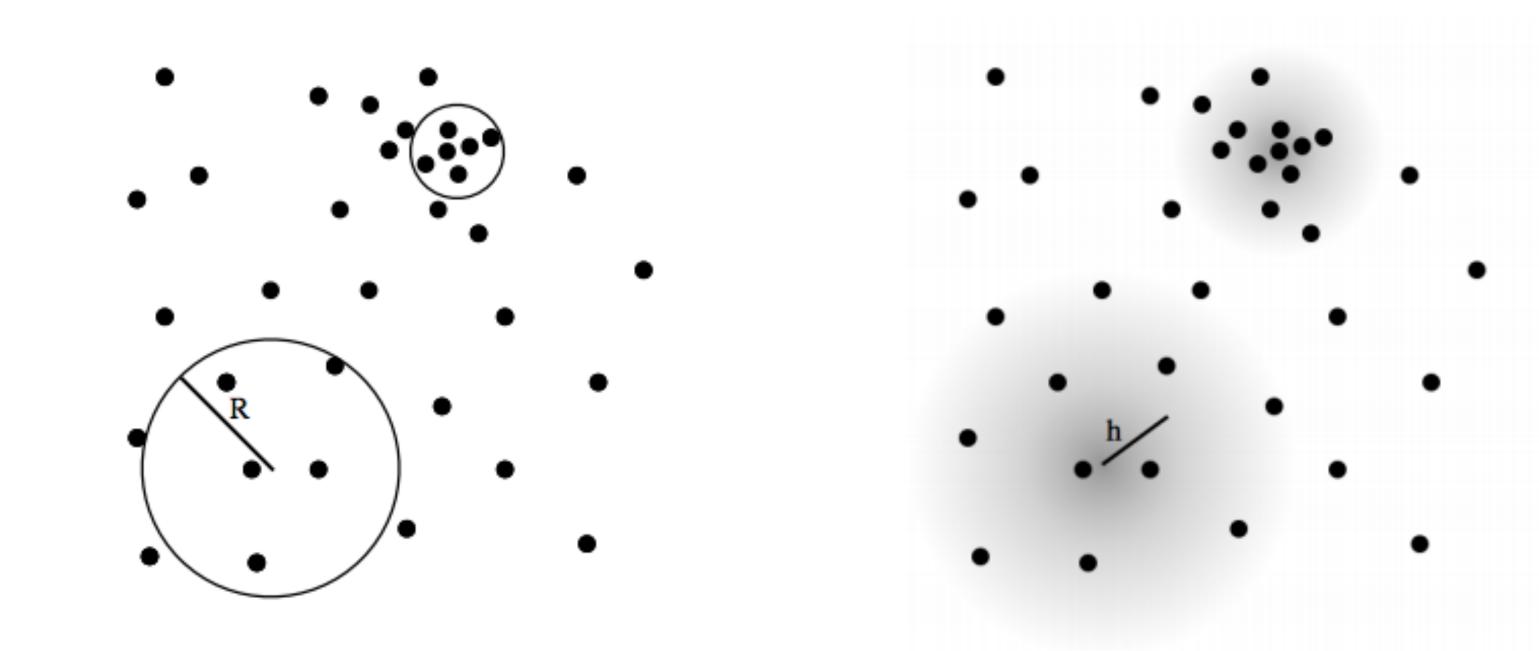


Fundamental idea behind SPH: how to compute density from a collection of

Method 2: construct local sample volumes, then sum particles within volume and divide by volume

point masses





Fundamental idea behind SPH: how to compute density from a collection of

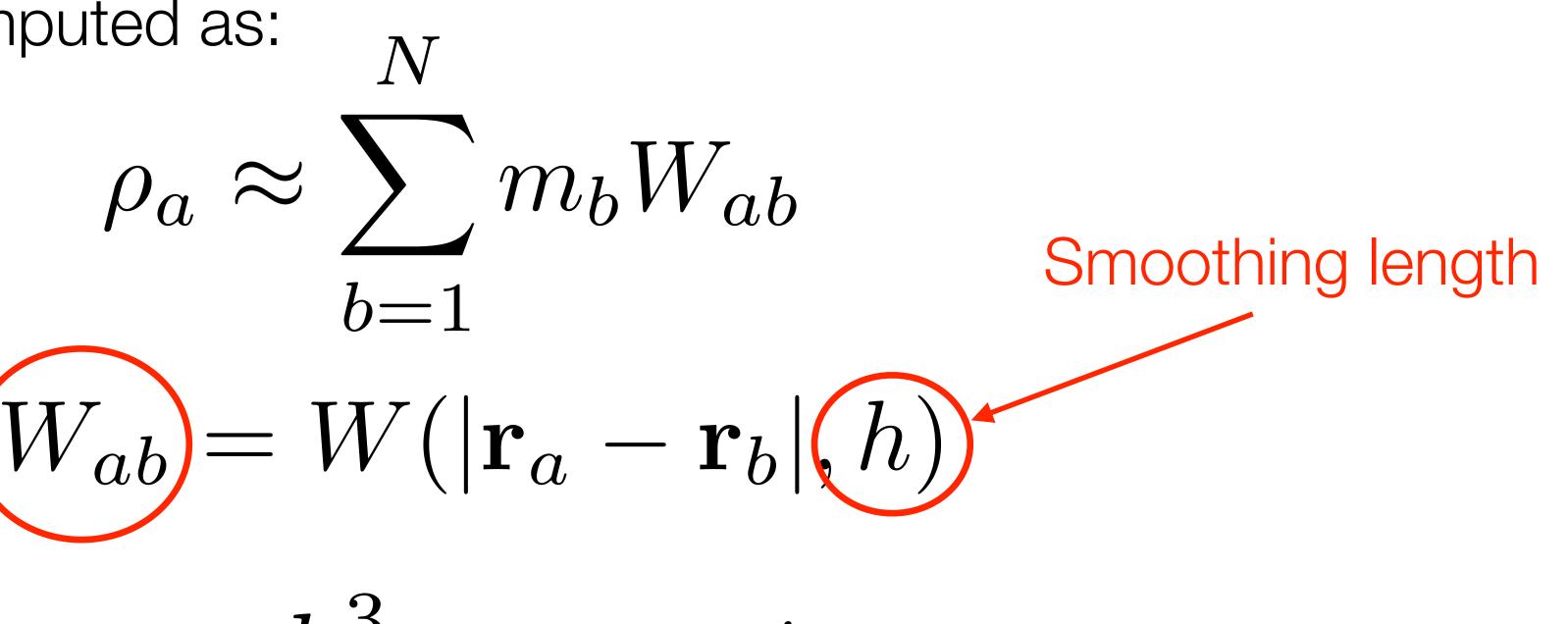
Method 3: weight contributions according to distance from sample point (SPH)



Smoothing kernel

- point masses
- Density in SPH is computed as: •

Fundamental idea behind SPH: how to compute density from a collection of



 $\rho h^3 = const.$ Resolution follows density



Choice of the kernel function

- The main property of the kernel is that is should approximate a delta of fluid properties.
- One could use a Gaussian:

W(r,h) = -

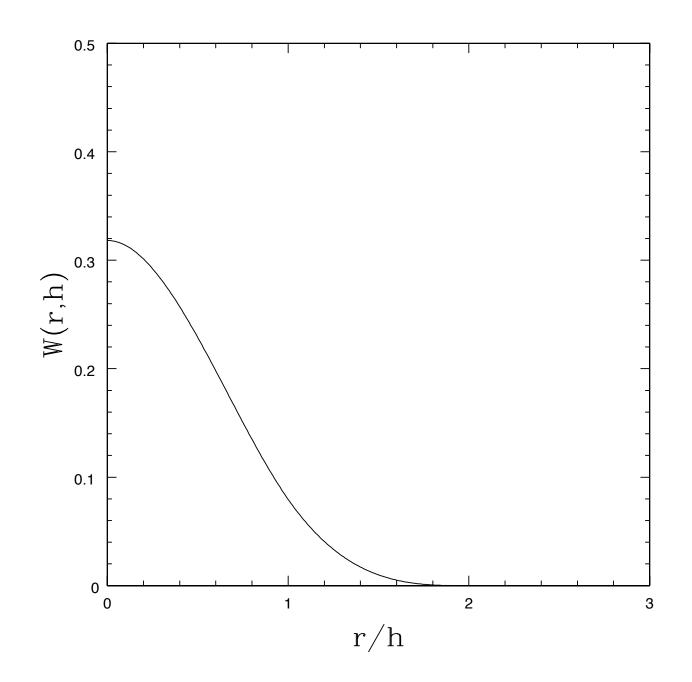
function: particles which are close should count more in the local evaluation

$$\frac{1}{\pi^{3/2}h^3}e^{-(r/h)^2}$$

 Problem is that support is not compact. SPH summations must then extend to all particles, resulting in a total computational cost scaling with N^2 :

Choice of the kernel function

- given distance).
- is a cubic polynomial which vanishes for r > 2h)

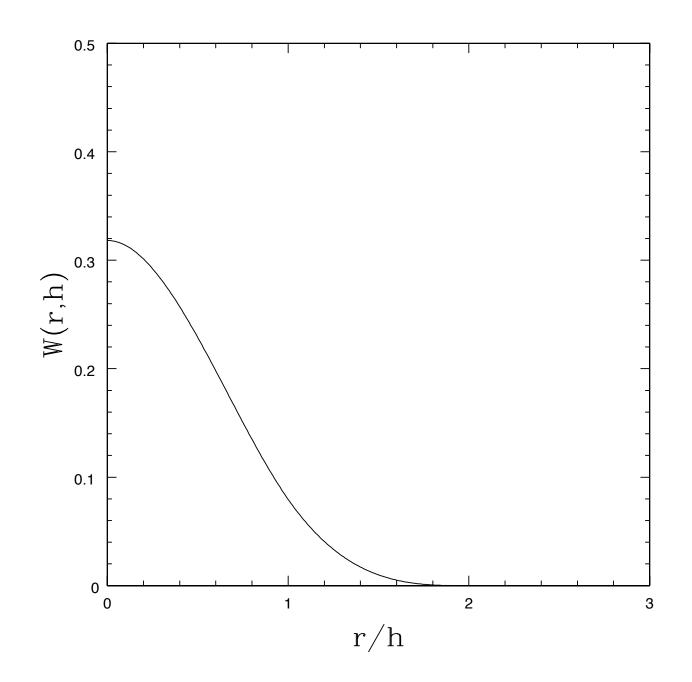


Better to use a kernel with compact support (ie. that vanishes beyond a

Most widely used is the cubic spline kernel (find full expression in textbooks:

Choice of the kernel function

- given distance).
- is a cubic polynomial which vanishes for r > 2h)



Better to use a kernel with compact support (ie. that vanishes beyond a

Most widely used is the cubic spline kernel (find full expression in textbooks:

- SPH sums only involve summing over particles which lie within 2 smoothing lengths from the particle of interest. These particles are called the "neighbours"
- Important to realize: each SPH particle only feels fluid forces from its neighbours

Dynamics

- OK, we have computed density. How do we move the particles?
- Eckart (1960): Lagrangian of a continuum fluid system

Discretize in SPH form ullet

Equation of motion

$$\mathcal{L} = \int \left(\frac{1}{2}\rho v^2 - \rho u\right) \mathrm{d}V$$

$$\mathcal{L} = \sum_{b} m_{b} \left(\frac{1}{2} v_{b}^{2} - u_{b} \right)$$
$$\frac{\mathrm{d}}{\mathrm{d}t} \left(\frac{\partial \mathcal{L}}{\partial \mathbf{v}_{a}} \right) = \frac{\partial \mathcal{L}}{\partial \mathbf{r}_{a}}$$

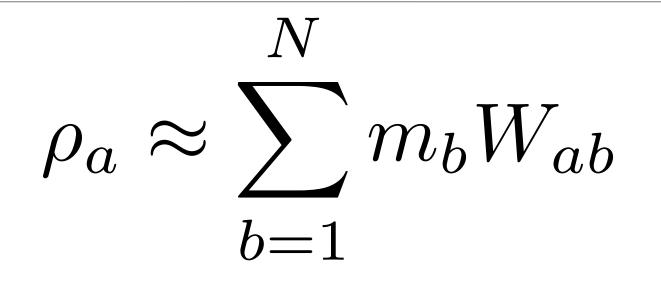


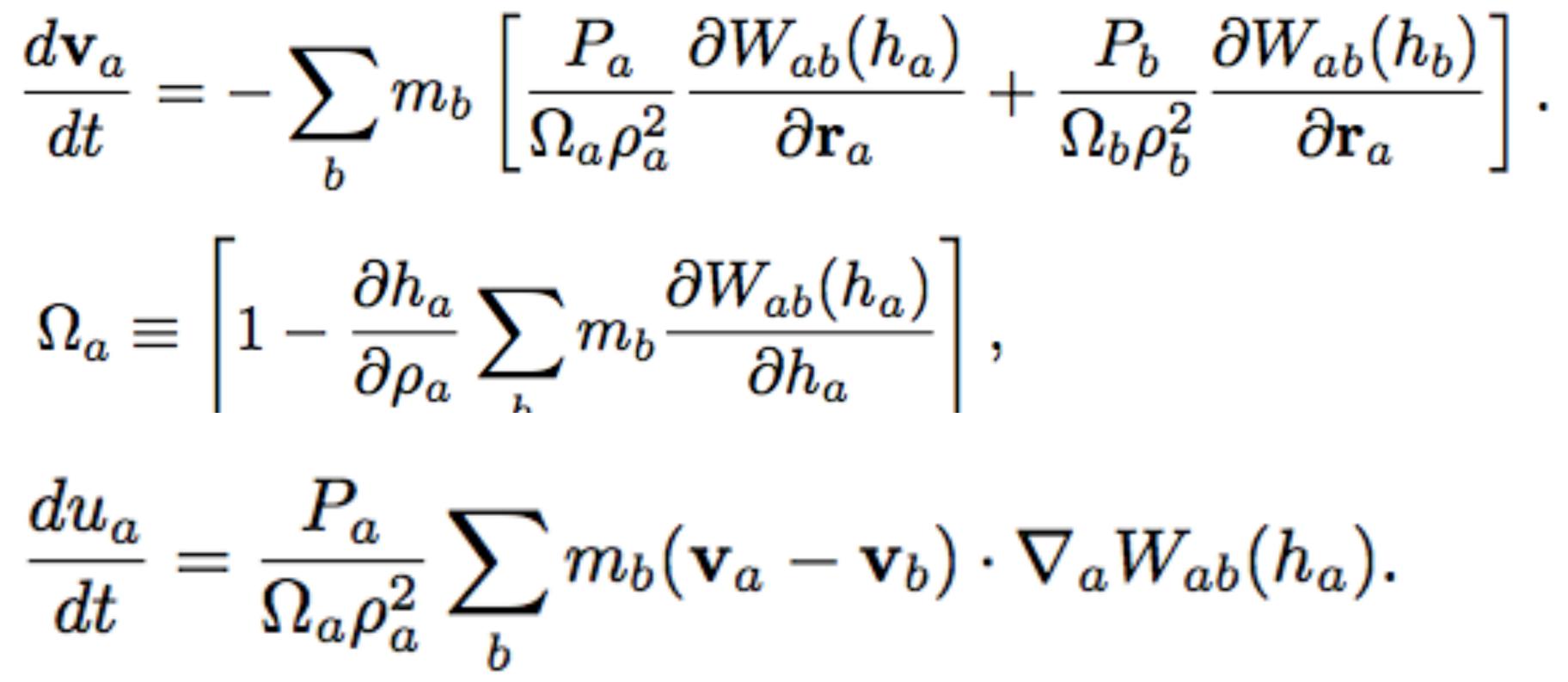
Dynamics: note

- One could well consider a set of N bodies interacting through that Lagrangian
- Hamiltonian properties of the system preserved
- **Noether's theorem:** any symmetry in the Lagrangian determines a constant of motion •
 - Linear momentum exactly conserved (to machine precision) ٠
 - <u>Angular momentum exactly conserved</u> (to machine precision) •
 - Energy exactly conserved (to machine precision, if symplectic time-integrator is used) •
 - Continuity exactly solved (Lagrangian nature of scheme) \bullet



Basic SPH equations





Intrpretation of SPH equations based on interpolation theory

- Not needed in fact, but we go through it to clarify the nature of SPH •
- Consider a fluid property A •

$$A(\mathbf{r}) = \int A($$

$(\mathbf{r'})\delta(\mathbf{r}-\mathbf{r'})\mathrm{d}\mathbf{r'}$

Intrpretation of SPH equations based on interpolation theory

- Not needed in fact, but we go through it to clarify the nature of SPH •
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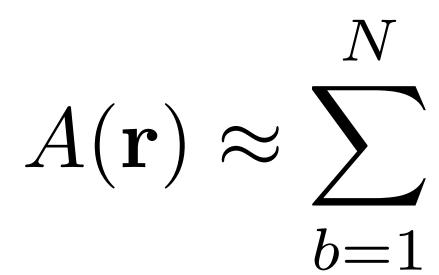
$A(\mathbf{r}) \approx \int A(\mathbf{r}') W(|\mathbf{r} - \mathbf{r}'|, h) d\mathbf{r}'$

Intrpretation of SPH equations based on interpolation theory

- Not needed in fact, but we go through it to clarify the nature of SPH •
- Consider a fluid property A •

 $A(\mathbf{r}) \approx \int \frac{A(\mathbf{r})}{\rho(\mathbf{r})}$

Discretize in mass •



$$rac{\left(\mathbf{r'}
ight)}{\mathbf{r'}}W(|\mathbf{r}-\mathbf{r'}|,h)
ho(\mathbf{r'})\mathrm{d}\mathbf{r'}$$

$$m_b rac{A_b}{
ho_b} W(|\mathbf{r} - \mathbf{r}_b|, h)$$

SPH interpolation

SPH representation of unity:

SPH representation of zero:

 \mathcal{N} $1 \approx \sum_{b=1}^{\cdot} \frac{m_b}{\rho_b} W_{ab}$ N $0 = \nabla 1 \approx \sum_{b=1}^{\infty} \frac{m_b}{\rho_b} \nabla_a W_{ab}$

Derivatives in SPH

$$A(\mathbf{r}) \approx \sum_{b=1}^{N} m_b \frac{A_b}{\rho_b} W(|\mathbf{r} - \mathbf{r}_b|, h)$$

 $\nabla A(\mathbf{r}_a) \approx \sum_{i}$

- and no approximation is done at this stage

• SPH representation of $A(\mathbf{r})$ only depends on \mathbf{r} through the kernel. Therefore:

$$\sum_{b=1}^{N} m_b \frac{A_b}{\rho_b} \nabla_a W_{ab}$$

Important property of SPH: the derivative is done analitically on the kernel

Immediately see that this is **NOT** a good approx for constant functions.

Derivatives in SPH

 $\nabla A - A \nabla 1$:

$$\nabla A(\mathbf{r}_a) \approx \sum_{b=1}^{N} m_b \frac{(A_b - A_a)}{\rho_b} \nabla_a W_{ab}$$

- This form vanishes exactly for constant functions.
- Example. Compute the divergence of velocity:

$$\nabla \cdot \mathbf{v}(\mathbf{r}_a) \approx \sum_{b=1}^{N}$$

A much better derivative estimate is obtained by the SPH representation of

$$\frac{m_b}{\rho_b} (\mathbf{v}_b - \mathbf{v}_a) \cdot \nabla_a W_{ab}$$

Momentum equation

equation λΤ

$$\frac{\mathrm{d}\mathbf{v}(\mathbf{r}_a)}{\mathrm{d}t} = -\sum_{b=1}^{N} m_b \frac{(P_b - P_a)}{\rho_a \rho_b} \nabla_a W_{ab}$$

- This has the advantage of vanishing for constant pressure, but....
- Has the **BIG** disadvantage of not conserving momentum!!!
 - on *b*!

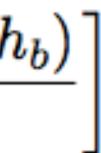
 $rac{d\mathbf{v}}{dt}$

$$\frac{\mathrm{d}\mathbf{v}}{\mathrm{d}t} = -\frac{1}{\rho}\nabla P$$

One might naively take the usual estimate for the gradient of P and put in the

Force of particle b on a is equal (and not opposite!) to force of particle a

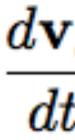
$$\frac{da}{dt} = -\sum_{b} m_b \left[\frac{P_a}{\Omega_a \rho_a^2} \frac{\partial W_{ab}(h_a)}{\partial \mathbf{r}_a} + \frac{P_b}{\Omega_b \rho_b^2} \frac{\partial W_{ab}(h_a)}{\partial \mathbf{r}_a} \right]$$



Interpretation of SPH Euler's equ

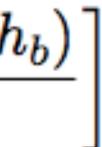
 $\frac{1}{\rho}\nabla P = \nabla \left(\frac{P}{\rho}\right) + \frac{P}{\rho^2}\nabla\rho$

 $\frac{1}{\rho}\nabla P \approx \sum_{b} m_b \left(\frac{P_b}{\rho_b^2} + \frac{P_a}{\rho_a^2}\right) \nabla_a W_{ab}$



vation
$$\frac{\mathrm{d}\mathbf{v}}{\mathrm{d}t} = -\frac{1}{\rho}\nabla P$$

$$rac{da}{dt} = -\sum_{b} m_b \left[rac{P_a}{\Omega_a
ho_a^2} rac{\partial W_{ab}(h_a)}{\partial \mathbf{r}_a} + rac{P_b}{\Omega_b
ho_b^2} rac{\partial W_{ab}(h_a)}{\partial \mathbf{r}_a}
ight]$$



Summary

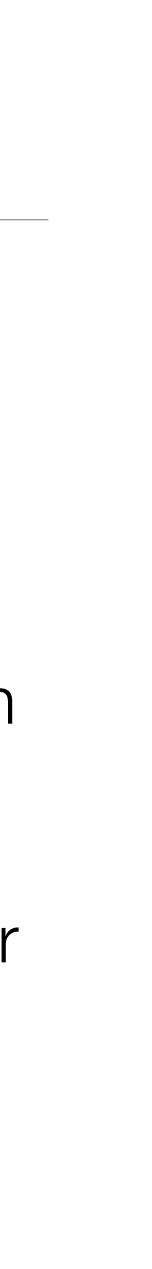
- SPH basics •
- **Advanced SPH** •
- A few applications to protostellar disc dynamics in the ALMA era

Advanced SPH

- Resolving shocks and discontinuities
- Adding self-gravity
- Additional physics:
 - Individual timesteps
 - Sink particles
 - MHD •
 - Radiative transfer ullet
 - General relativity

Resolving shocks and discontinuities

- The whole SPH method relies on the fact that all physical quantities are continuous and differentiable.
- This is not true at discontinuities (e.g. contact discontinuities) and shocks.
- Fluid equations can develop discontinuities even from initial conditions which are continuous
- If the SPH solution has to be continuous, such discontinuities will not appear in the solution ("the shock is not resolved")
- How do we treat these cases?



Artificial dissipations vs Riemann solvers

- Two possible approaches:
 - Solve analitically the equations in integral form on the two sides of the discontinuity • (Riemann solvers -- Godunov schemes). Preferred method in fluid dynamics.
 - Remove the cause of the discontinuity adding an "artificial dissipation" term to • smear it out
- **Note:** in the real world there are no discontinuities --> viscosity (or physical dissipation) removes it at the microscopic scale
- Artificial dissipation is thus analogous to what happens in Nature, but on scales generally much larger

- grid-based methods
- they are more difficult to implement in SPH (but can be done)
- Most SPH codes use artificial viscosity to resolve shocks -- i.e. discontinuities in the momentum equations

Both Godunov schemes and artificial viscosity can be used in both SPH and

• Some grid based methods use artificial viscosity (e.g. ZEUS), but most don't.

While Godunov schemes have a natural implementation in grid-based codes,



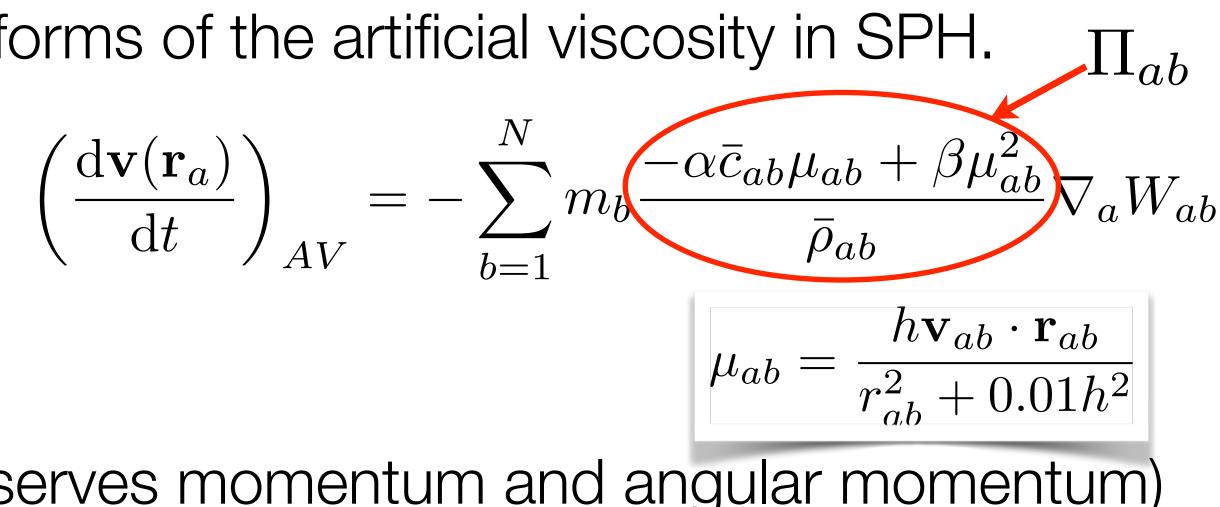
- There are various specific forms of the artificial viscosity in SPH.
- The most common is: $\left(\frac{\mathrm{d}\mathbf{v}(\mathbf{r}_a)}{\mathrm{d}t}\right)$

- Properties:
 - Is Galilean invariant (conserves momentum and angular momentum) •
 - Vanishes for rigid body rotation
 - The "β"-term is analogous to von Neumann Rightmyer viscosity
 - Best choices for parameters are $\alpha = 1$ and $\beta = 2$

$$_{AV} = -\sum_{b=1}^{N} m_b \frac{-\alpha \bar{c}_{ab} \mu_{ab} + \beta \mu_{ab}^2}{\bar{\rho}_{ab}} \nabla_a W_{ab}$$
$$\mu_{ab} = \frac{h \mathbf{v}_{ab} \cdot \mathbf{r}_{ab}}{r_{ab}^2 + 0.01 h^2}$$

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- Both the α and the β terms provide <u>both a **shear** and a **bulk**</u> viscosity in a <u>ratio of 5 to 3</u> (bulk viscosity = 5/3 shear viscosity)
- The α term is equivalent to a kinematic viscosity coefficient of

$$(\nu)_{ab}$$
 =

Energy equation needs modifications in order to conserve energy

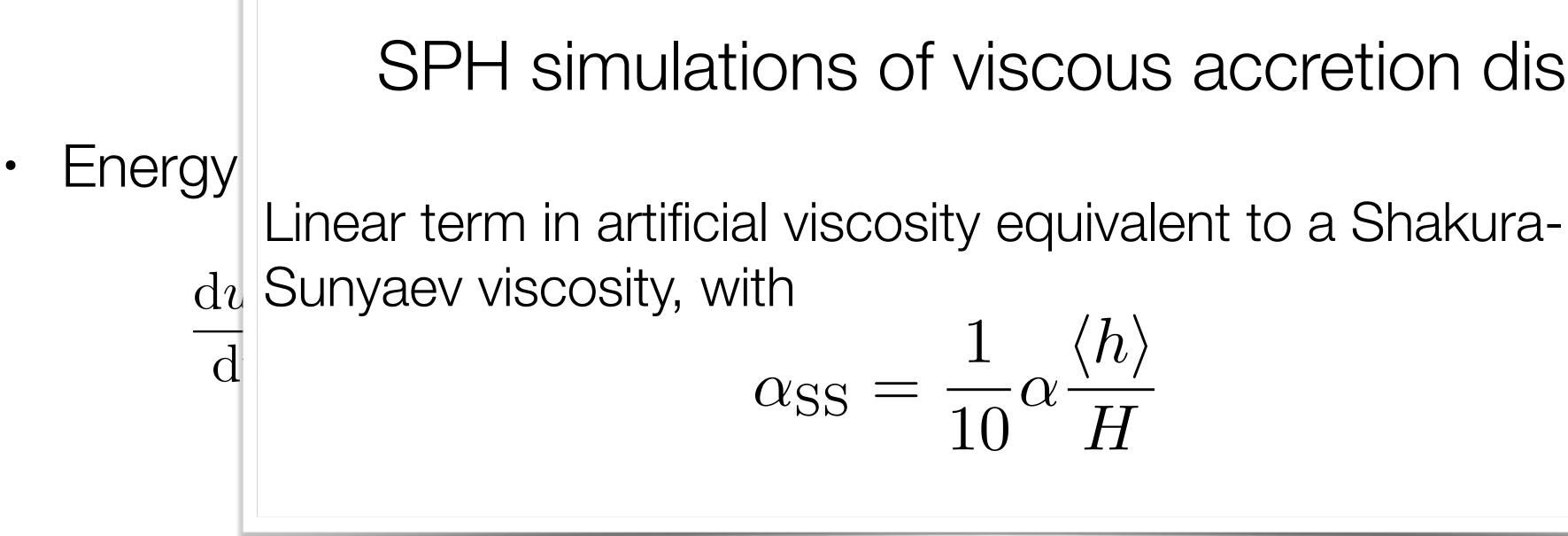
$$\frac{\mathrm{d}u_a}{\mathrm{d}t} = \frac{P_a}{\rho_a^2} \sum_b m_b (\mathbf{v}_a - \mathbf{v}_b) \cdot \nabla_a W_{ab} + \frac{1}{2} \sum_b m_b \Pi_{ab} (\mathbf{v}_a - \mathbf{v}_b) \cdot \nabla_a W_{ab}$$

$$\left(\frac{\mathrm{d}\mathbf{v}(\mathbf{r}_a)}{\mathrm{d}t}\right)_{AV} = -\sum_{b=1}^{N} m_b \frac{-\alpha \bar{c}_{ab} \mu_{ab} + \beta \mu_{ab}^2}{\bar{\rho}_{ab}} \nabla_a W_{ab}$$

$$= \frac{1}{10} \alpha \bar{c}_{ab} h_{ab}$$



- <u>ratio of 5 to 3</u> (bulk viscosity = 5/3 shear viscosity)
- The α term is equivalent to a kinematic viscosity coefficient of



$$\left(\frac{\mathrm{d}\mathbf{v}(\mathbf{r}_a)}{\mathrm{d}t}\right)_{AV} = -\sum_{b=1}^{N} m_b \frac{-\alpha \bar{c}_{ab} \mu_{ab} + \beta \mu_{ab}^2}{\bar{\rho}_{ab}} \nabla_a W_{ab}$$

Both the α and the β terms provide both a **shear** and a **bulk** viscosity in a

SPH simulations of viscous accretion discs

$$\frac{1}{10} \alpha \frac{\langle h \rangle}{H}$$



Note on simulating disc-like structures

- Relevant for protostellar discs, but also to disc galaxies that may form in cosmological simulations
- A disc in vertical hydrostatic balance has a thickness $H=c_s/\Omega$
- Differential rotation over a radial range ~ H, gives $\Delta v \sim \Omega H \sim c_s$
- If disc thickness not resolved, the code will think that differential rotation is a shock and will damp it strongly via artificial viscosity!!!
- It is essential that h << H for simulating any disc

Problems associated with artificial viscosity

- We are actually simulating a different physical process
- Angular momentum conservation non modified, but can have significant spurious transport
- Important to limit the use of artificial viscosity to the bare minimum
- Need to use a number of "switches": •
- 1. Turn it off for non approaching particles (standard practice)
- 2. Balsara switch --> Removes significantly the shear component
- 3. Morris & Monaghan switch. Have individual alpha terms where for every particle alpha evolves as: $\frac{\alpha - \alpha_{\min}}{1 + S(\nabla \cdot \mathbf{v})}$ $d\alpha$ $\mathrm{d}t$ \mathcal{T}

Also, recently introduced Cullen & Dehnen switch

Physical viscosity in SPH

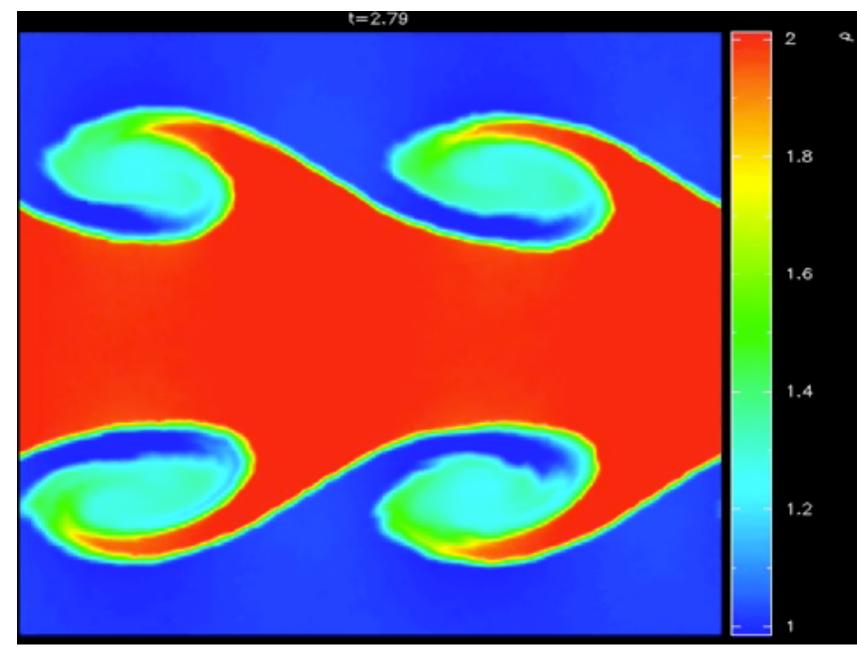
- It is also possible to implement Navier-Stokes viscosity terms in SPH
- Formulation is a bit difficult, based on either SPH estimates of second 1993, Lodato & Price 2010)

$$\frac{\partial v_a^i}{\partial x_a^j} = \frac{1}{\rho_a \Omega_a} \sum_b m_b \left(v_b^i - v_a^i \right) \frac{\partial W_{ab}(h_a)}{\partial x_a^j}$$

derivatives (Espanol & Revenga 2003) or computing velocity gradients (Flebbe

Kelvin-Helmholtz instabilities in SPH

- KH instability occurs when two fluids drift past each other
- It has been claimed that SPH cannot give rise to the instability even in cases where it should (Agertz et al. 2007)
- It has been shown (Price 2008) that this is due to the fact that most codes do not include artificial thermal conductivity and hence cannot resolve discontinuities in the energy equation (the origin of the KHI)



Self-gravity in SPH

- In many cases the self-gravity of the fluid is very important
 - E.g.: collapse of a molecular cloud in star formation, dynamics of self-gravitating discs,.....
- SPH lends itself naturally to these kinds of problems due to its N-body like structure.
- Can simply use the techniques developed for years in the N-body community
- Need to remember: we are simulating a fluid, not a collection of N particles
 - Need to remove two-body interactions --> need to use gravitational softening •





Softening vs smoothing

- than a typical scale, called the "<u>softening length</u>"
- smoothing kernel to effect the softening
- dsensity profile given by the kernel
- Not all codes do that!!!! Example: GADGET does not!
- to spurious behaviour (e.g. enhanced/suppressed fragmentation)

Gravitational softening is a way to reduce the gravitational force on scales smaller

• In SPH, the natural choice is to use the smoothing length for this purpose, and the

Consider each particles gravitational field as due to an extended sphere with

• If you don't, gravity and fluid forces are resolved differently, which might give rise



Resolving fragmentation in SPH

- How much resolution do you need to do that?
- Typical fragment mass is the Jeans
- Jeans mass!
- smoothing kernel, which is ~ $N_{neigh}m_p$ ~ 100m_p (Bate & Burkert 1997)

 Very often want to simulate processes where Jeans instability determines the structure of your system (from cosmological simulations down to star formation)

mass
$$M_{\rm J} = rac{\pi}{6} rac{c_{
m s}^3}{G^{3/2}
ho^{1/2}}$$

• <u>Zeroth order</u>: the mass of an SPH particle should be at least smaller than the

<u>First order</u>: Actually, the minimum resolvable mass is the mass contained in a



Tree-SPH

- scales with N^2)
- here!)
- Using a tree is also a very efficient way of getting the neighbour list
- A tree code scales more mildly, as N logN
- conservation
- Most SPH codes actually are Tree/SPH

Computing self-gravity directly through summation is a computationally expensive task (it

• Much easier to do when self-gravity is computed using a tree code (no time to explain it

However, the use of the tree leads to a small momentum and angular momentum non-

- Over the years, the "standard" SP additions
- Individual particle timesteps
 - Needed because the typical evolutionary timescale in the densest regions can be orders of magnitude smaller than that in the rest of the simulation
 - While only a small number of particles are doing something, the rest is just sitting there with little evolution

• Over the years, the "standard" SPH has been improved with a number of

- additions
- Sink particles •
 - Useful to simulate accretion processes
 - For example, accretion onto a newborn star
 - Accretion onto a black hole in a large scale simulation
 - Need to be very careful with boundary conditions!

• Over the years, the "standard" SPH has been improved with a number of

- Over the years, the "standard" SPH additions
- · MHD
 - This is tricky.
 - Not easy to implement the "divergence-free" nature of magnetic fields
 - Improvement have been made using Euler potential (Price)
 - Restricted to simple configurations of the field (tangled field difficult to be produced

Over the years, the "standard" SPH has been improved with a number of

- Over the years, the "standard" SPH has been improved with a number of additions
- **Radiative transfer**
 - Important feature in cases where behaviour is very sensitive to thermal physics (for example, fragmentation of a gravitationally unstable disc)
 - Difficult and expensive to implement. •
 - Mostly done within the diffusion approximation for optically thick cases ●
 - Alternative and promising (Montecarlo radiative transfer, e.g. MCFOST)

- additions
- **Godunov SPH:** Potentially very important (Cha & Whitworth) •
- **Chemistry, multiphase SPH** •
- **Gas-dust interaction** (Laibe & Price) •

• Over the years, the "standard" SPH has been improved with a number of

Good practice suggestions

- 1. <u>Always use variable smoothing lengths!</u>!
 - Include "grad h" terms to conserve energy!
- 2. Number of neighbours should be large (50-100) to avoid particle noise
- When possible soften gravity on the same scale as fluid forces (i.e. smoothing length = softening length)
- 4. Remember to resolve Jeans mass with > 100 SPH particles
- 5. Use a symplectic time integrator (i.e. leapfrog rather than Runge-Kutta)
- 6. Use artificial viscosity switches (Morris & Monaghan, Balsara)
- 7. For disc simulations, always resolve the disc thickness with several smoothing lengths

To SPH or not to SPH?

Pros

- •
- Its Lagrangian nature makes it very good in handling problems without well defined • <u>symmetries</u> (eccentric, warped discs, binaries)
- Do not need to worry about boundaries (and its spurious effects!): the flow is not • confined "in a box"
- It is easy to implement and will always give an answer (careful here: possible source of • problems!)
- Advection of fluid properties natural in SPH (without losses due to the grid)

SPH is a solid method with exceptionally good conservation properties (far above any grid based code), which follow directly from its inherent Galilean invariance

To SPH or not to SPH?

Cons

- spurious dissipation.
- •
- Kelvin-Helmholtz case)
- Mixing of properties very hard to implement
- better off using a high-order grid-based code.

Most SPH codes use <u>artificial viscosity</u> to treat shocks: leads potentially to large

Artificial viscosity is not inherent to SPH. Godunov schemes (potentially better at treating shocks) can be designed to work in SPH. Needs more investigation.

Not using artificial dissipation might lead to unphysical behaviour at discontinuities (i.e.

• For problems with (a) high degree of symmetry or (b) physical boundaries you might be

Summary

- SPH basics •
- Advanced SPH •
- A few applications to protostellar disc dynamics in the ALMA era •

- Disc imaging across the years •

• With every new instrument, emphatic statements on the revolution it will bring

- •
- Disc imaging across the years •

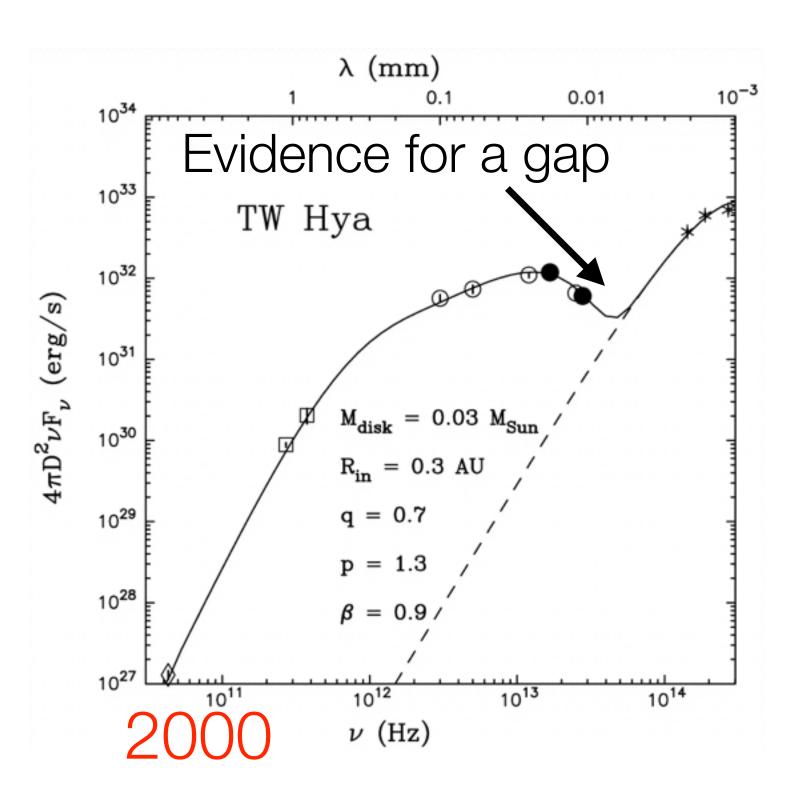
TW Hya - $d \sim 50 pc$



With every new instrument, emphatic statements on the revolution it will bring



- •
- Disc imaging across the years •

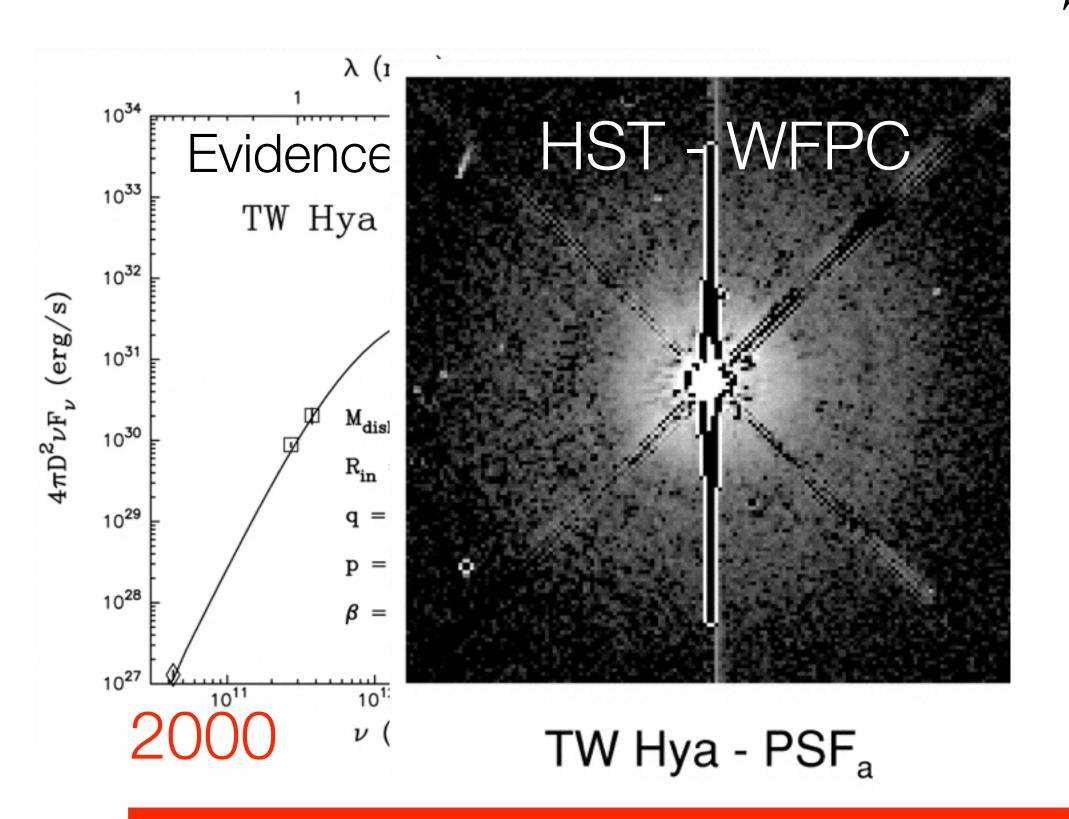


With every new instrument, emphatic statements on the revolution it will bring

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- •
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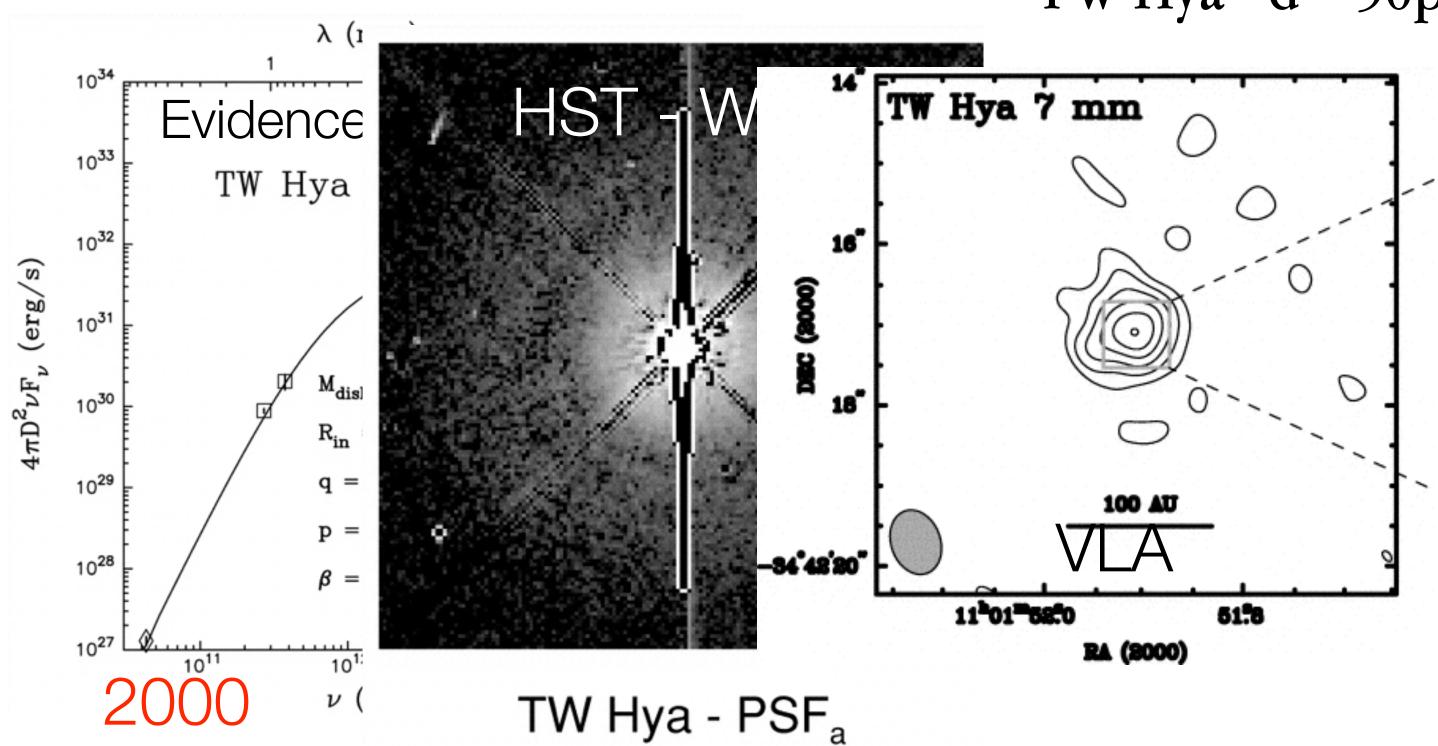


With every new instrument, emphatic statements on the revolution it will bring

TW Hya - $d \sim 50 pc$



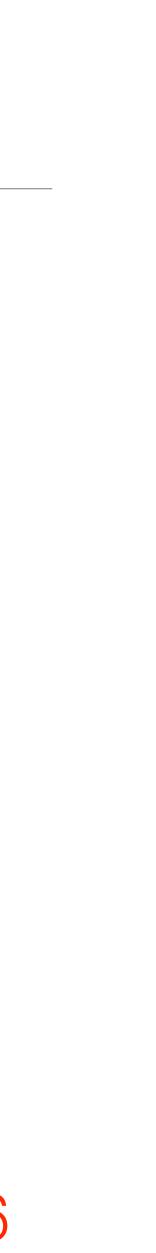
- •
- Disc imaging across the years •



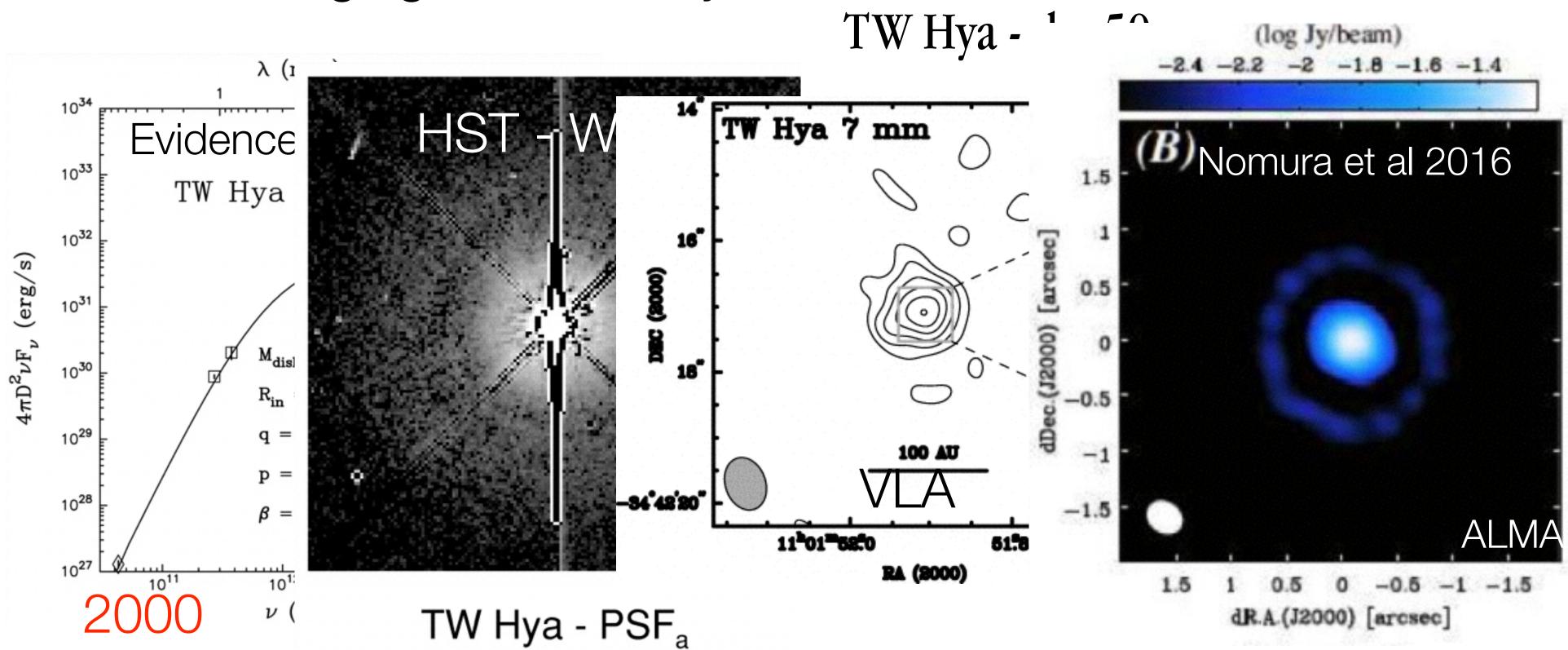
With every new instrument, emphatic statements on the revolution it will bring

TW Hya - $d \sim 50 pc$

2016



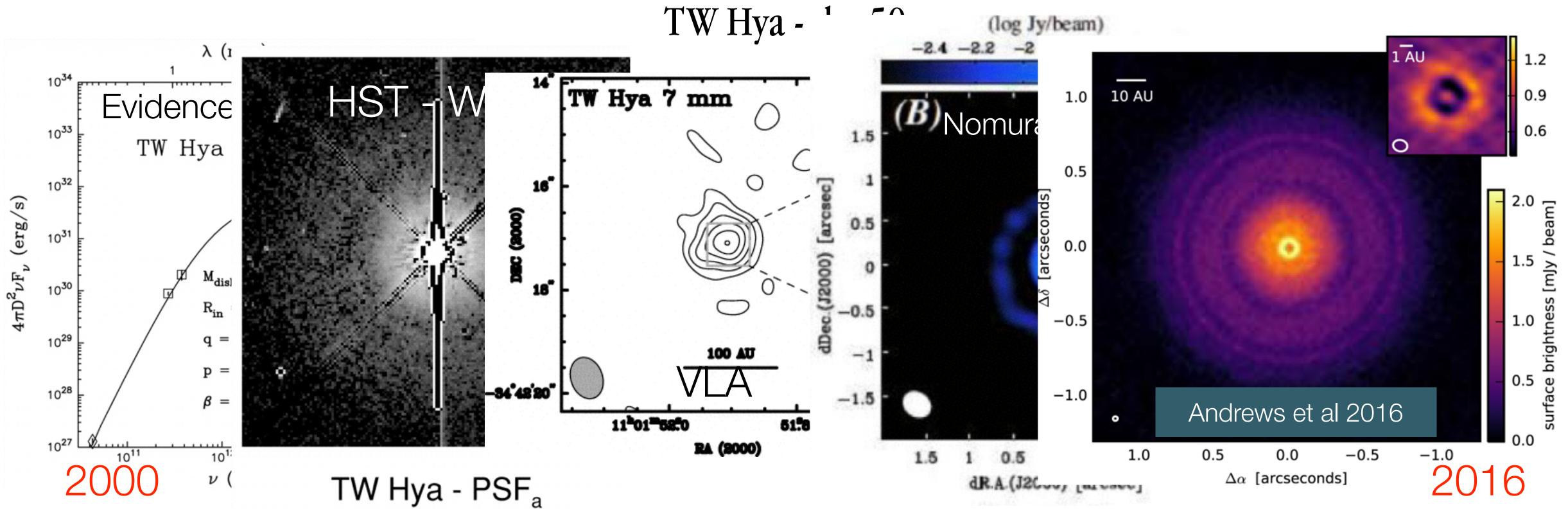
- •
- Disc imaging across the years •



With every new instrument, emphatic statements on the revolution it will bring

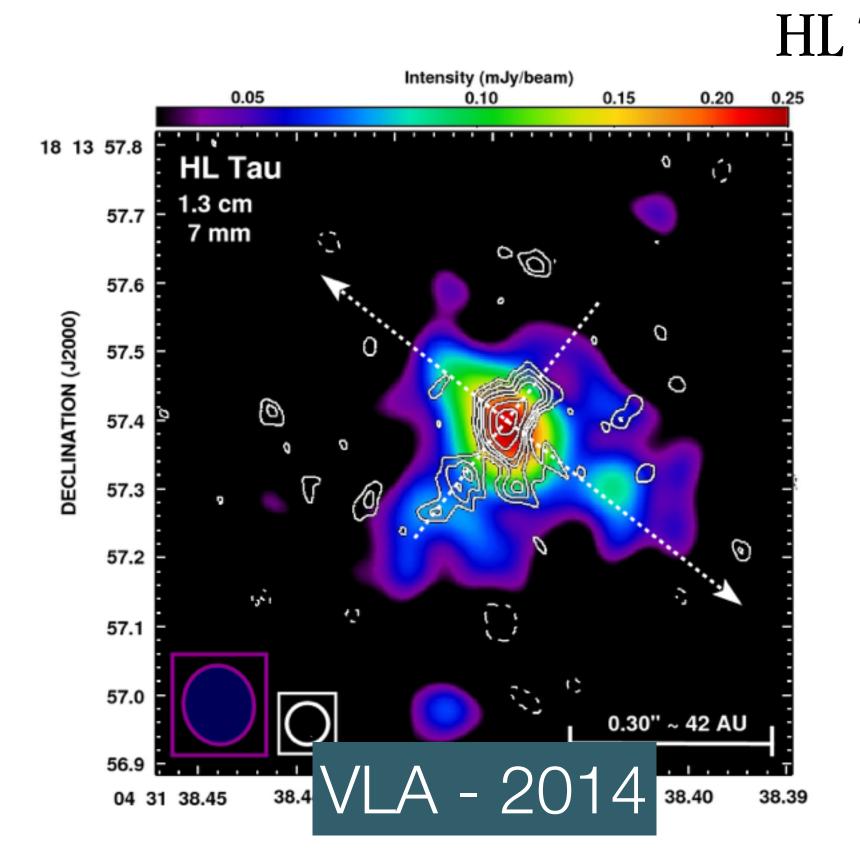


- •
- Disc imaging across the years •



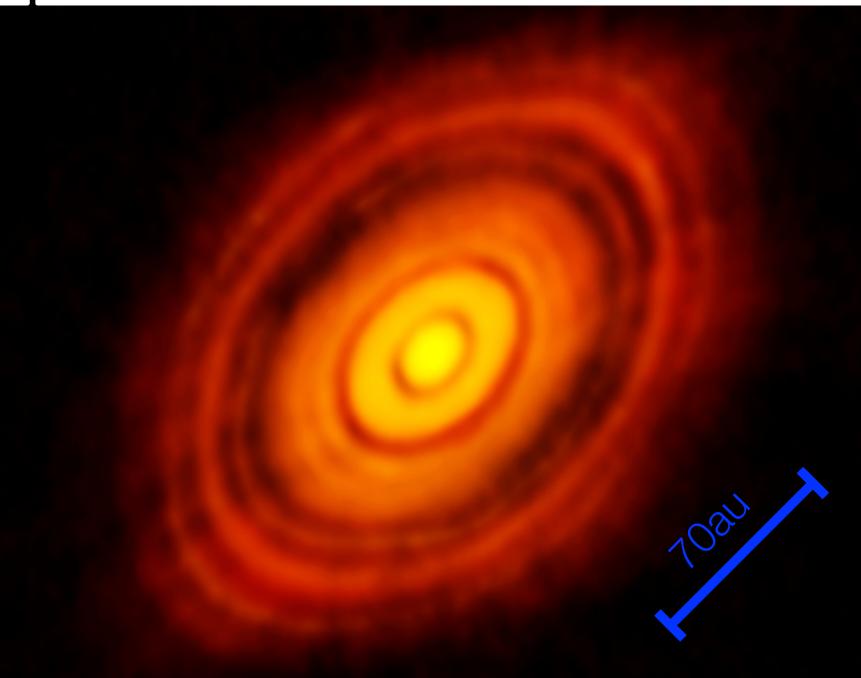
With every new instrument, emphatic statements on the revolution it will bring

- •
- Disc imaging across the years •



With every new instrument, emphatic statements on the revolution it will bring

HL Tau - $d \sim 140 pc$



ALMA 2015

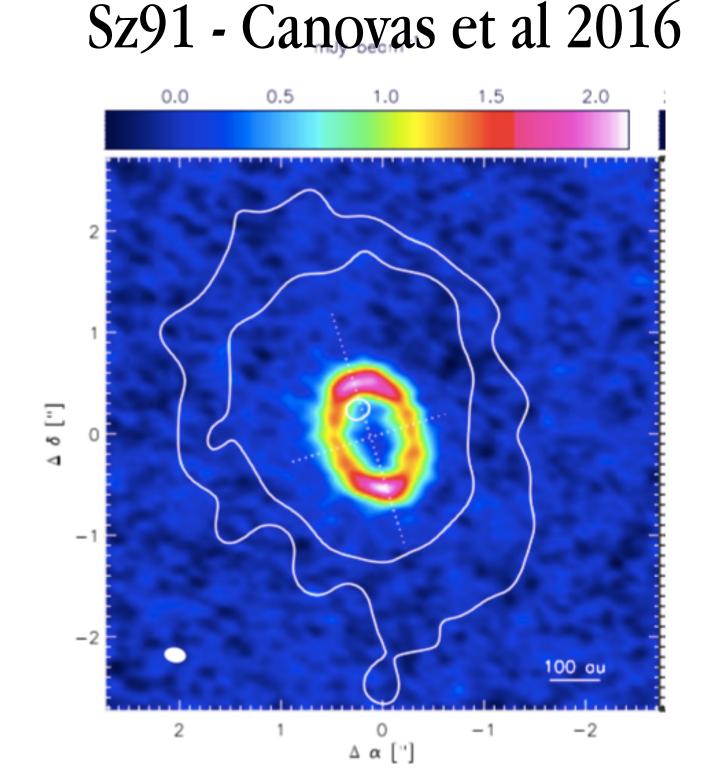
- •
- Disc imaging across the years •

HD97048 - van der Plas in prep

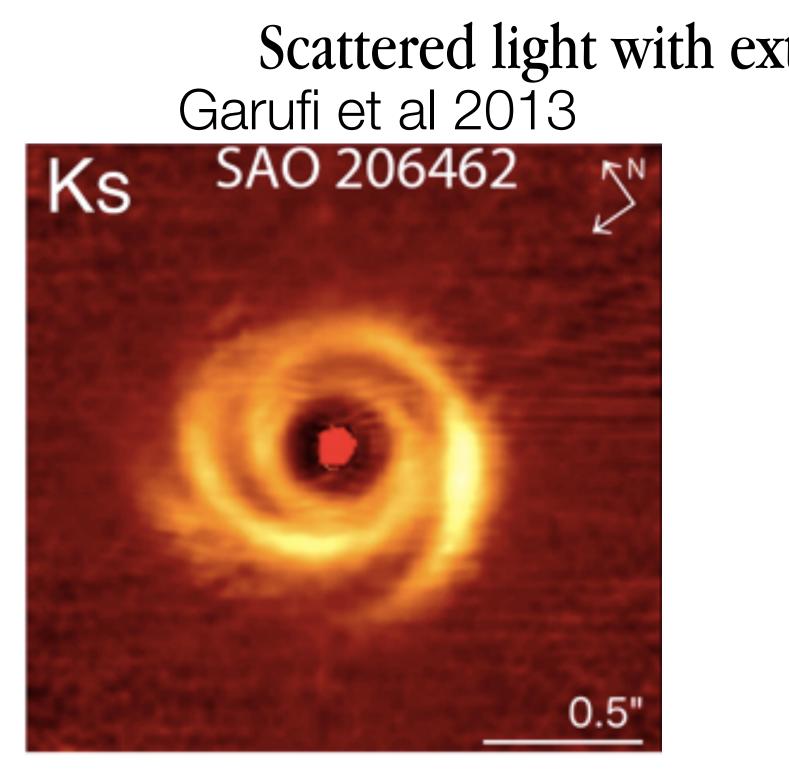
ALMA 0.8mm



With every new instrument, emphatic statements on the revolution it will bring



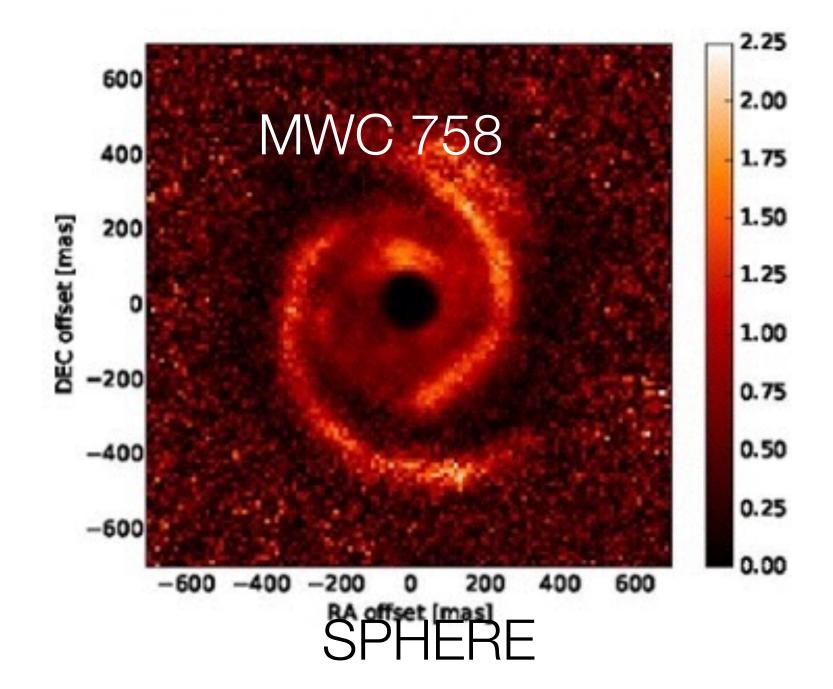
- •
- Disc imaging across the years •





With every new instrument, emphatic statements on the revolution it will bring

Scattered light with extreme AO (eg. SPHERE, HiCiao) Benisty et al 2015



What should modelers do?

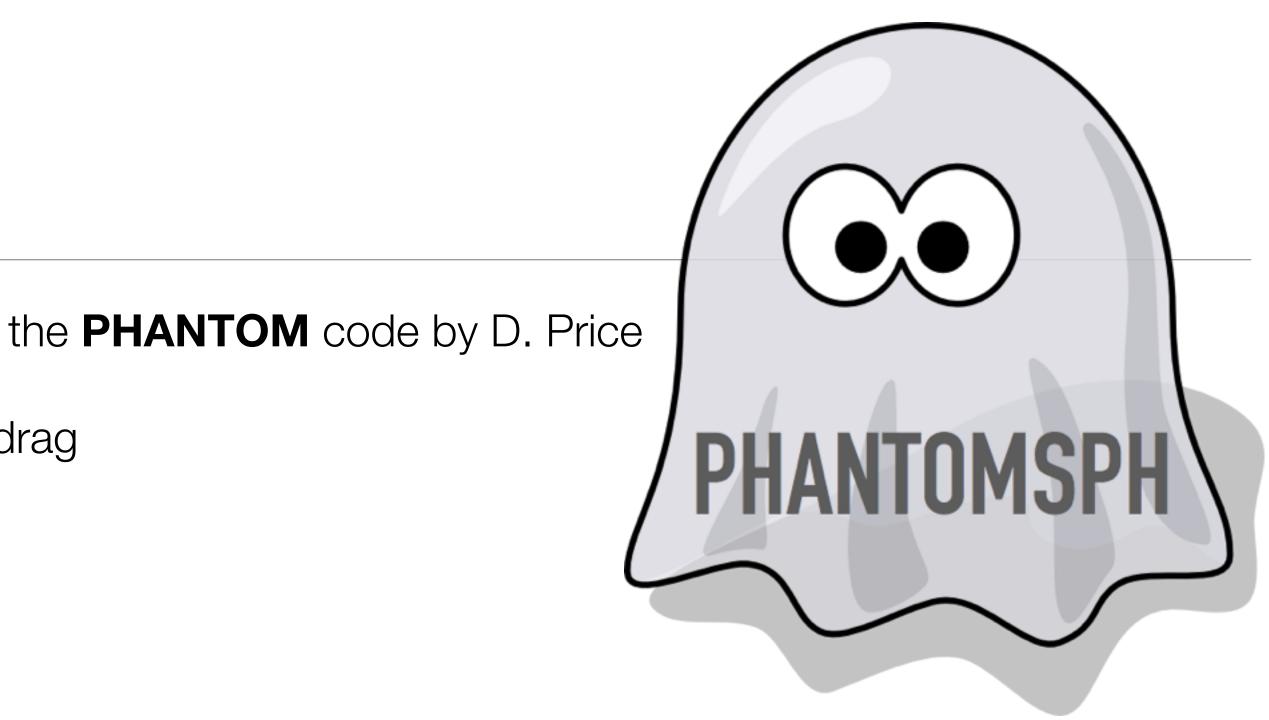
- for density and temperature
- also to understand dynamics
- Two component modeling (gas/dust) is crucial (CRUCIAL!) •

• For many years, disc models where 1D, axi-symmetric, power-law structures

Going beyond such models is essential not only to explain observations, but

What do we (in Milano) do?

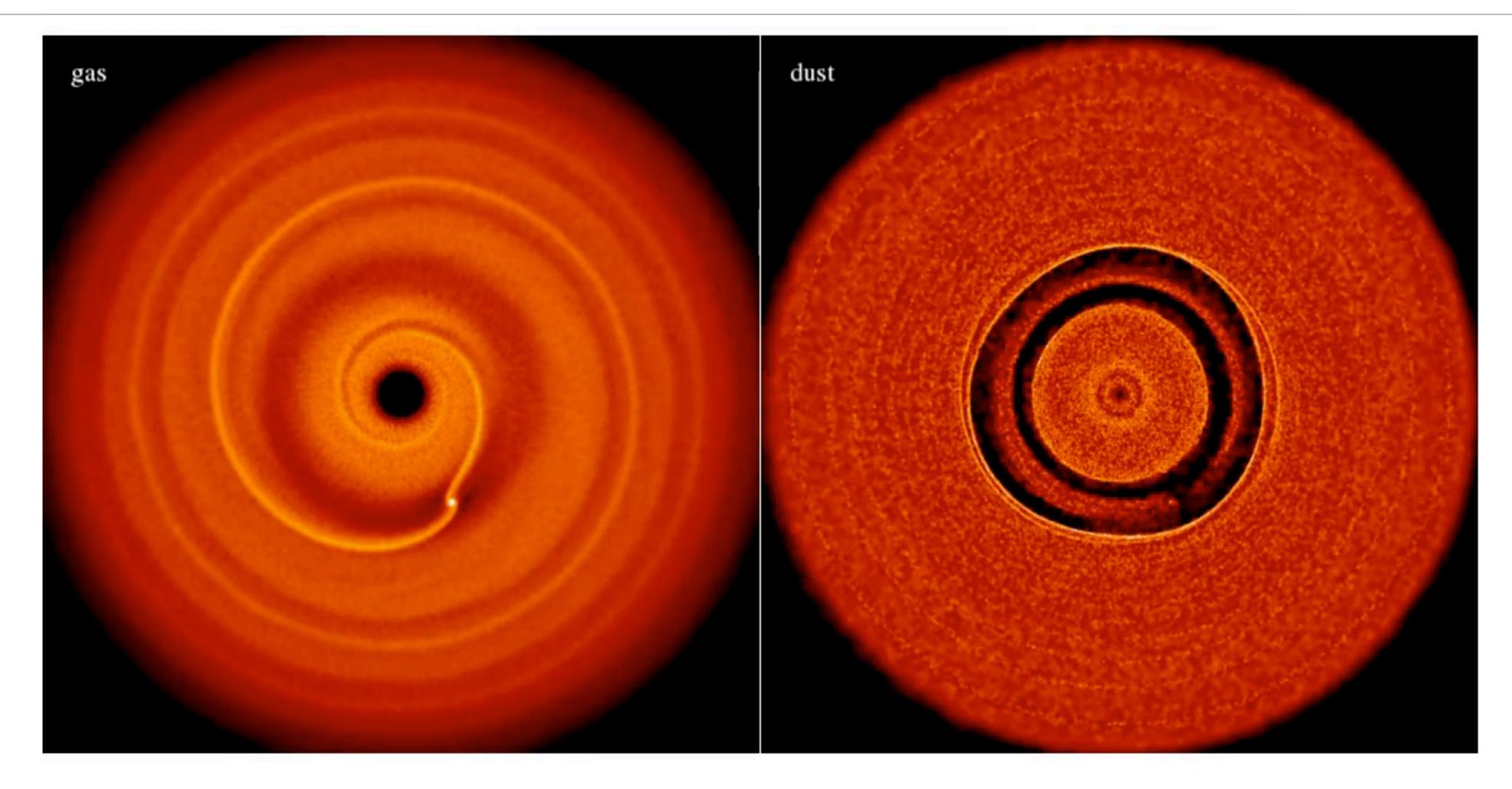
- We start from a hydrodynamical SPH simulation using the **PHANTOM** code by D. Price
 - Two components: gas and dust coupled though drag
 - Several point masses: **star(s), planets**
 - **Self-gravity** (of both gas and dust)
- We use a Monte-Carlo ray tracing code to get dust temperatures from irradiation
- We compute synthetic images either in scattered light or in dust continuum assuming a given instrumental response (ALMA, HiCIAO, etc...)
- What we do NOT do (yet):
 - Chemistry: chemical network needed to get molecular species and produce gas intensity maps
 - Radiative transfer: to have temperature self-consistently during hydro simulation (almost there!)



Gap opening in a dust disc (Dipierro et al 2016)

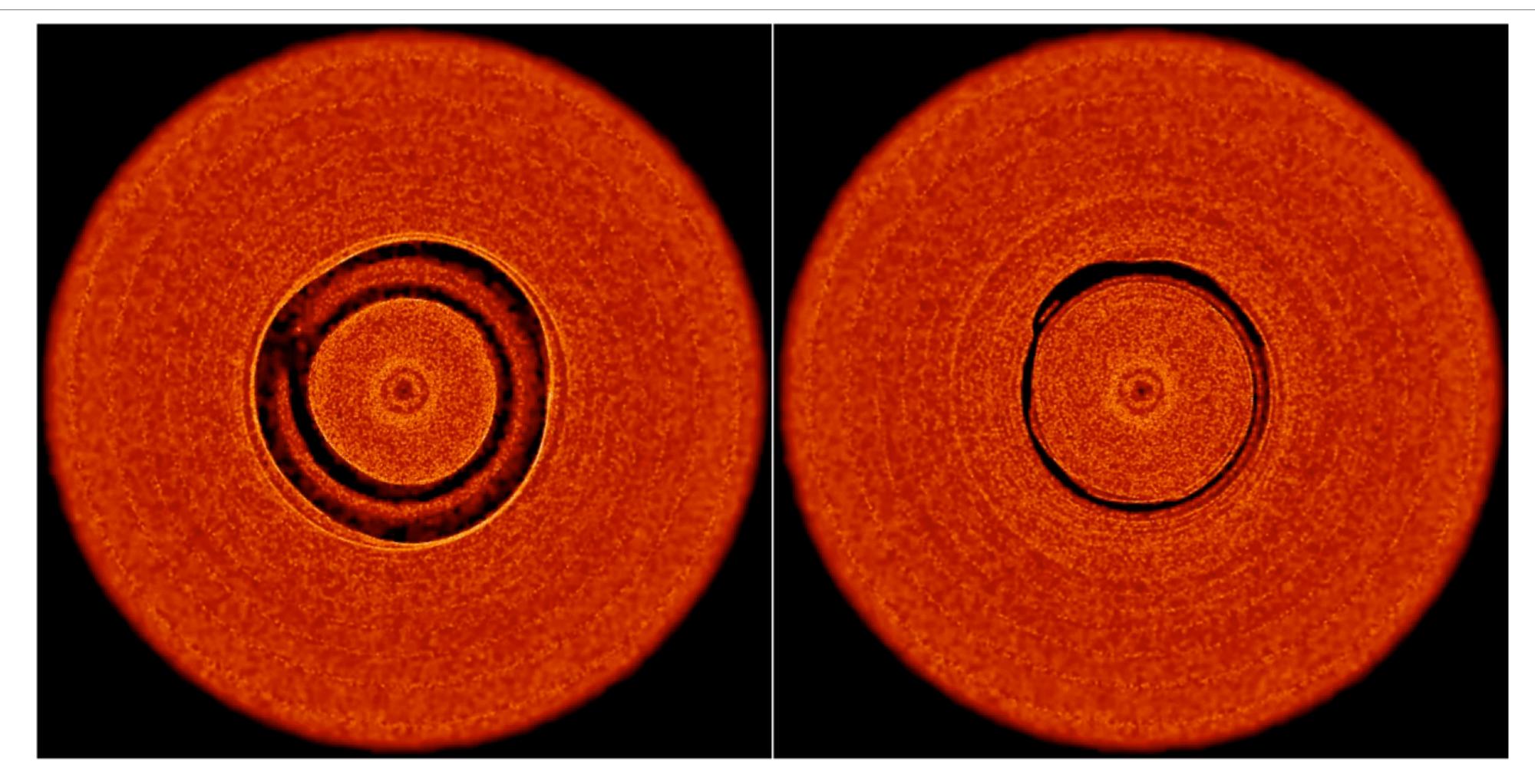
- Several possible mechanisms, depending on planet mass and Stokes number ullet
 - Large planet (satisfies gas gap opening) •
 - Small dust (St << 1): follows the gas
 - For St~1: dust trapping at the gap edge (Pardekooper & Mellema 2004)
 - Dust filtration at the gap edge (Rice et al 2006) •
 - This is likely to create narrow rings in dust
 - **Small planet** (does not open a gap in the gas) •
 - For St > 1, a gap can still be opened in the dust
 - Here, drag resists rather than assists gap opening

Gap opening in a dust disc (Dipierro et al 2016)



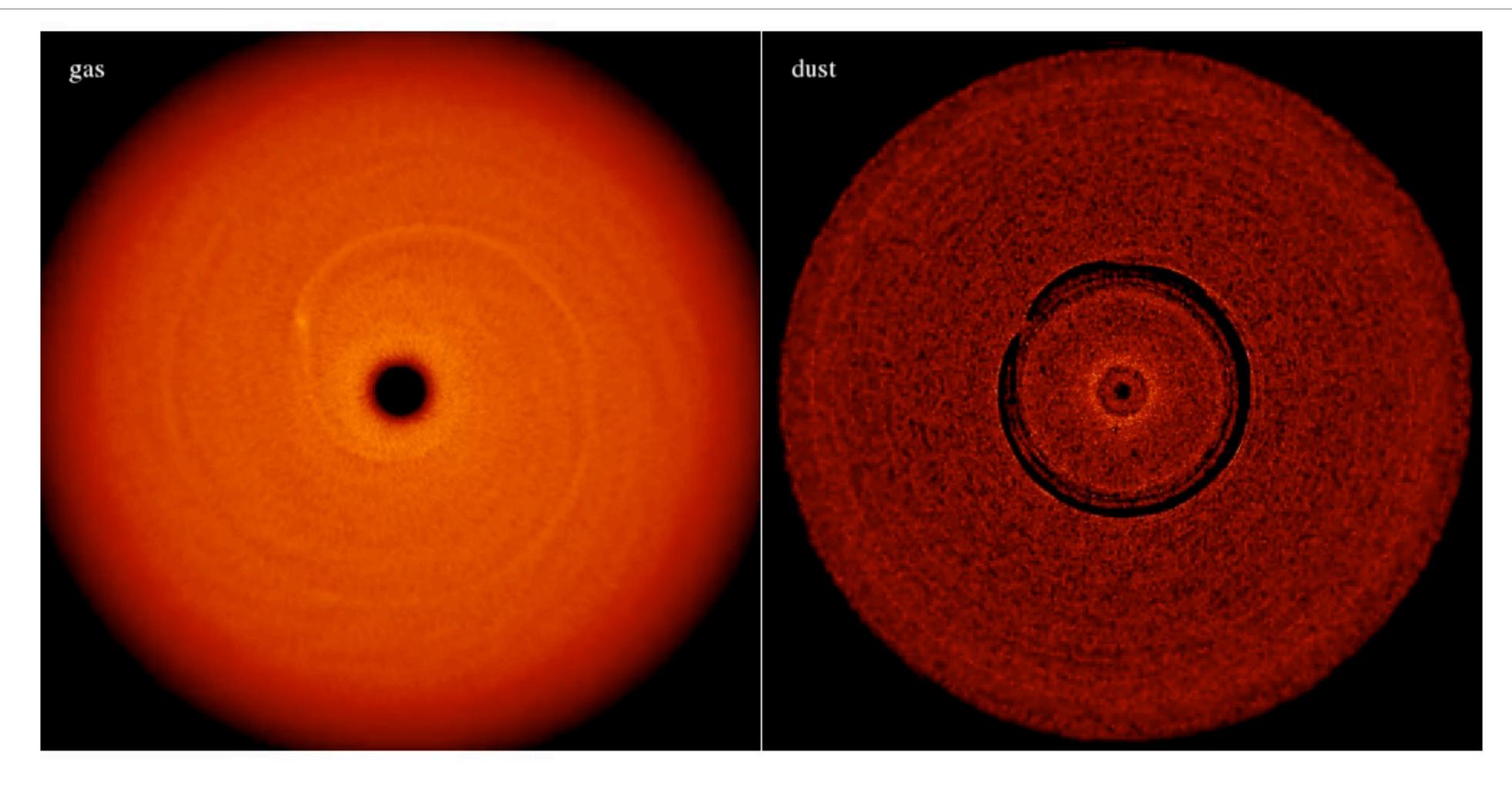
 $M_p = 1M_{Jup} - St = 10$

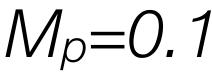
Gap opening in a dust disc (Dipierro et al 2016)



 $M_p = 1M_{Jup} - St = 10$

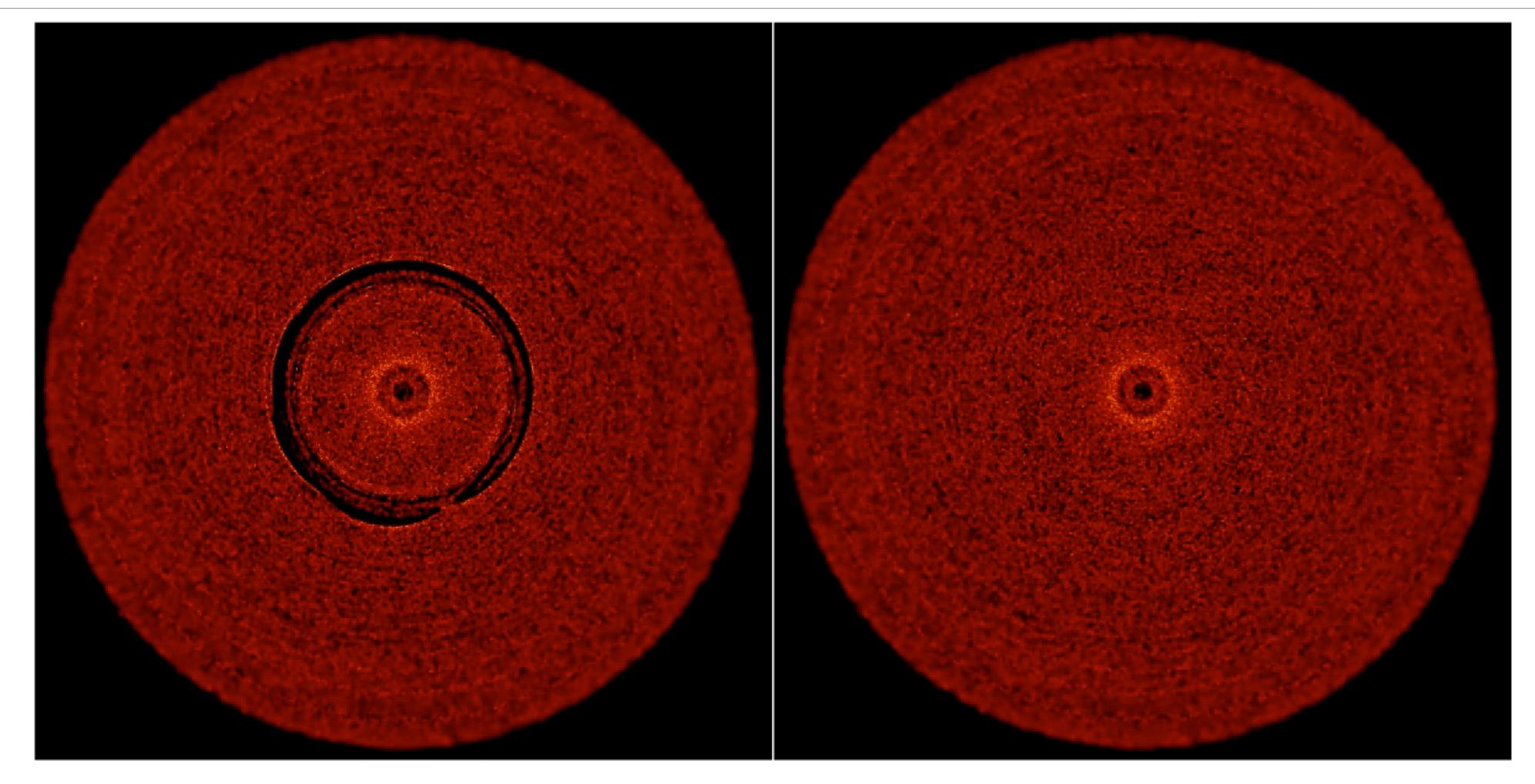
Gap opening in a dust disc (Dipierro et al 2016)

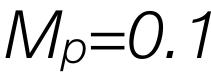




 $M_{p}=0.1M_{Jup} - St=10$

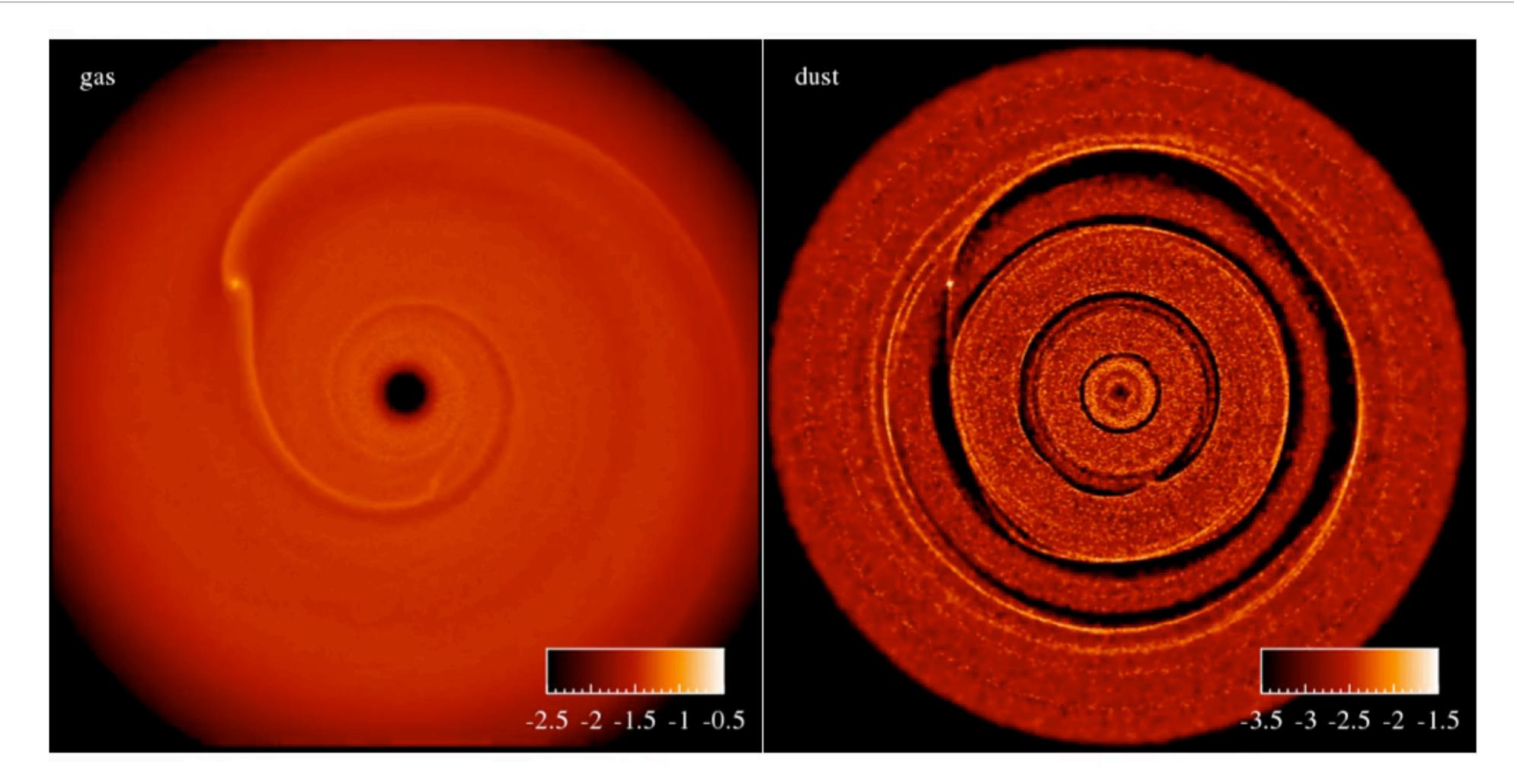
Gap opening in a dust disc (Dipierro et al 2016)





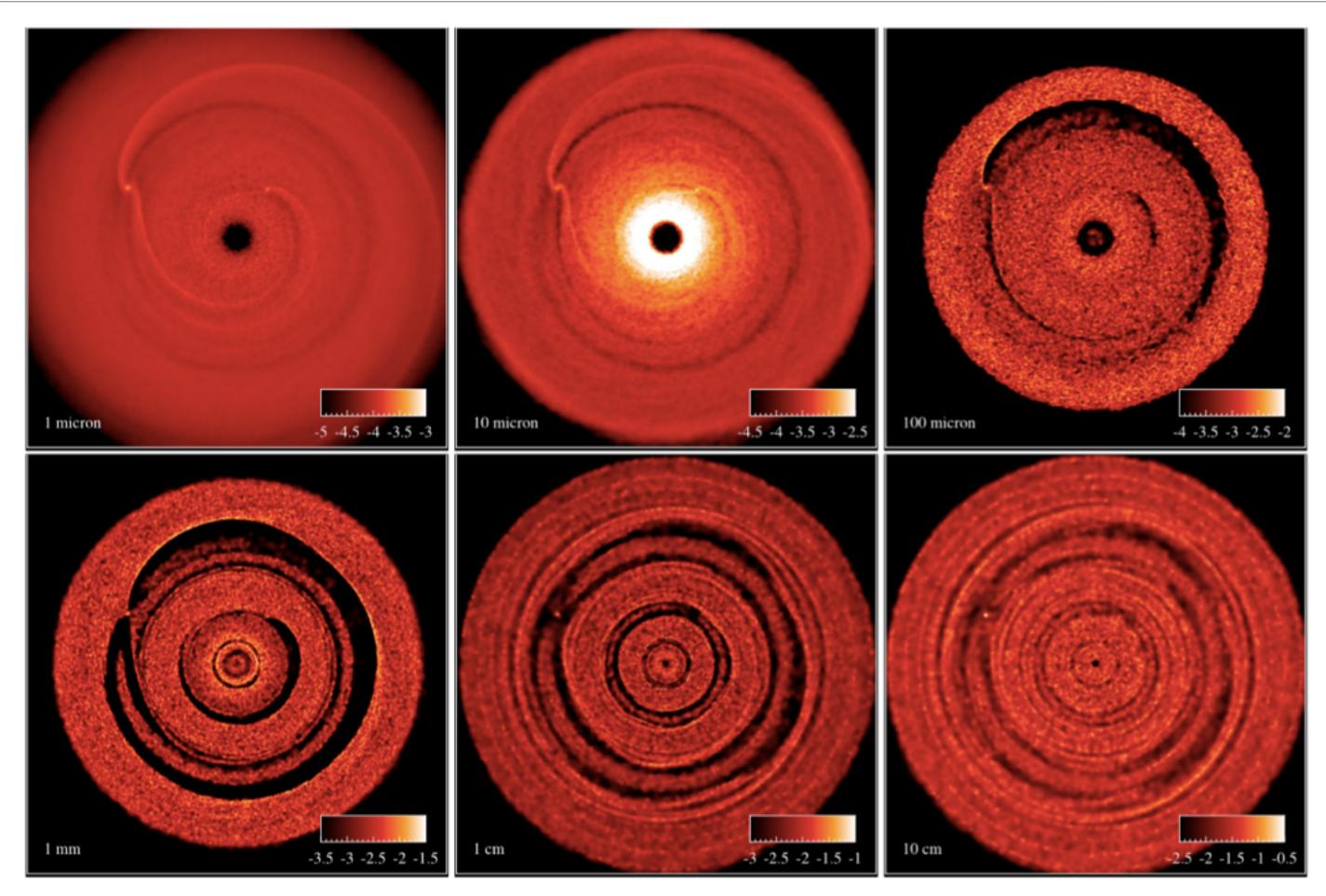
 $M_{p}=0.1M_{Jup} - St=10$

Explaining the HL Tau disc (Dipierro et al 2015b)



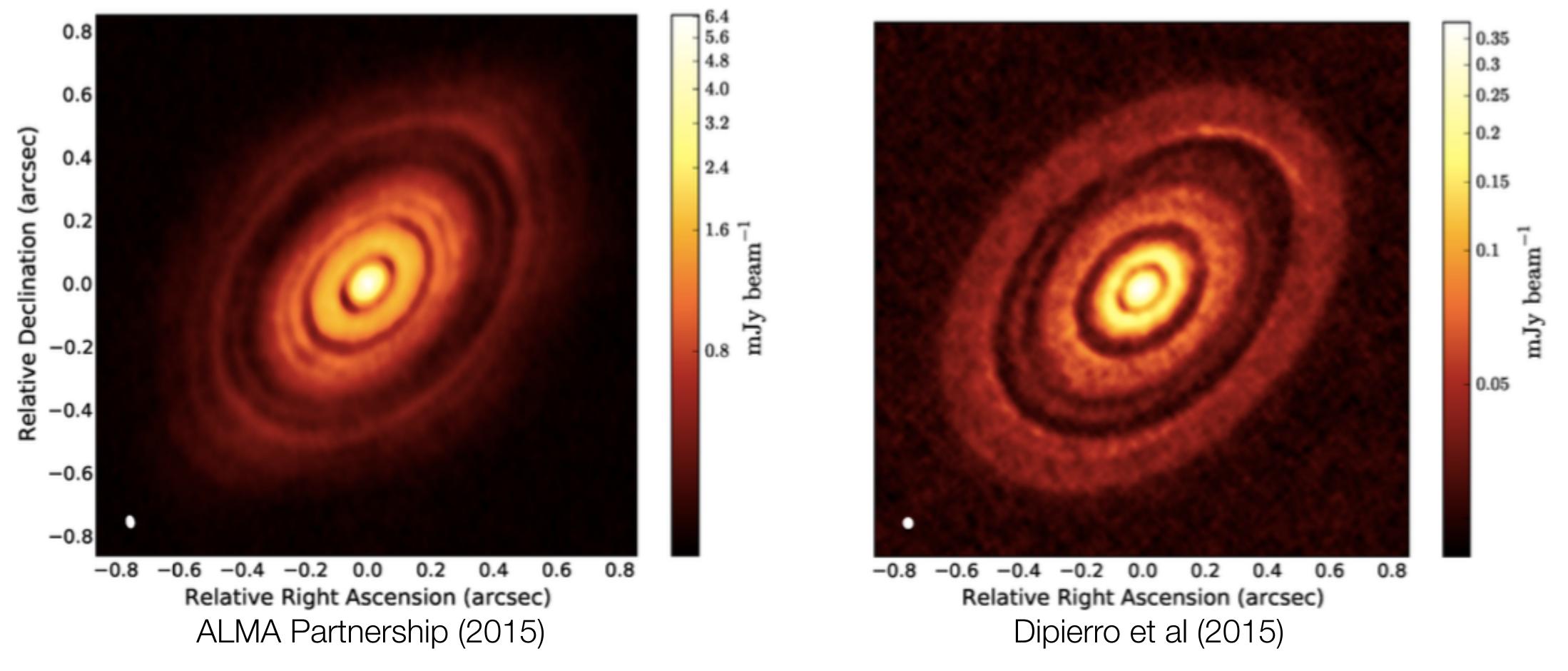
Three planets: 0.2M_{Jup} (@13.2au), 0.27M_{Jup} (@32.3au), 0.55M_{Jup} (@68.8au)

Explaining the HL Tau disc (Dipierro et al 2015b)



Simulate 6 different sizes, assume a dust size distribution and a gas/dust ratio -> compute synthetic images

Explaining the HL Tau disc (Dipierro et al 2015b)



Simulate 6 different sizes, assume a dust size distribution and a gas/dust ratio ->compute synthetic images

Asymmetric cavities in binary systems

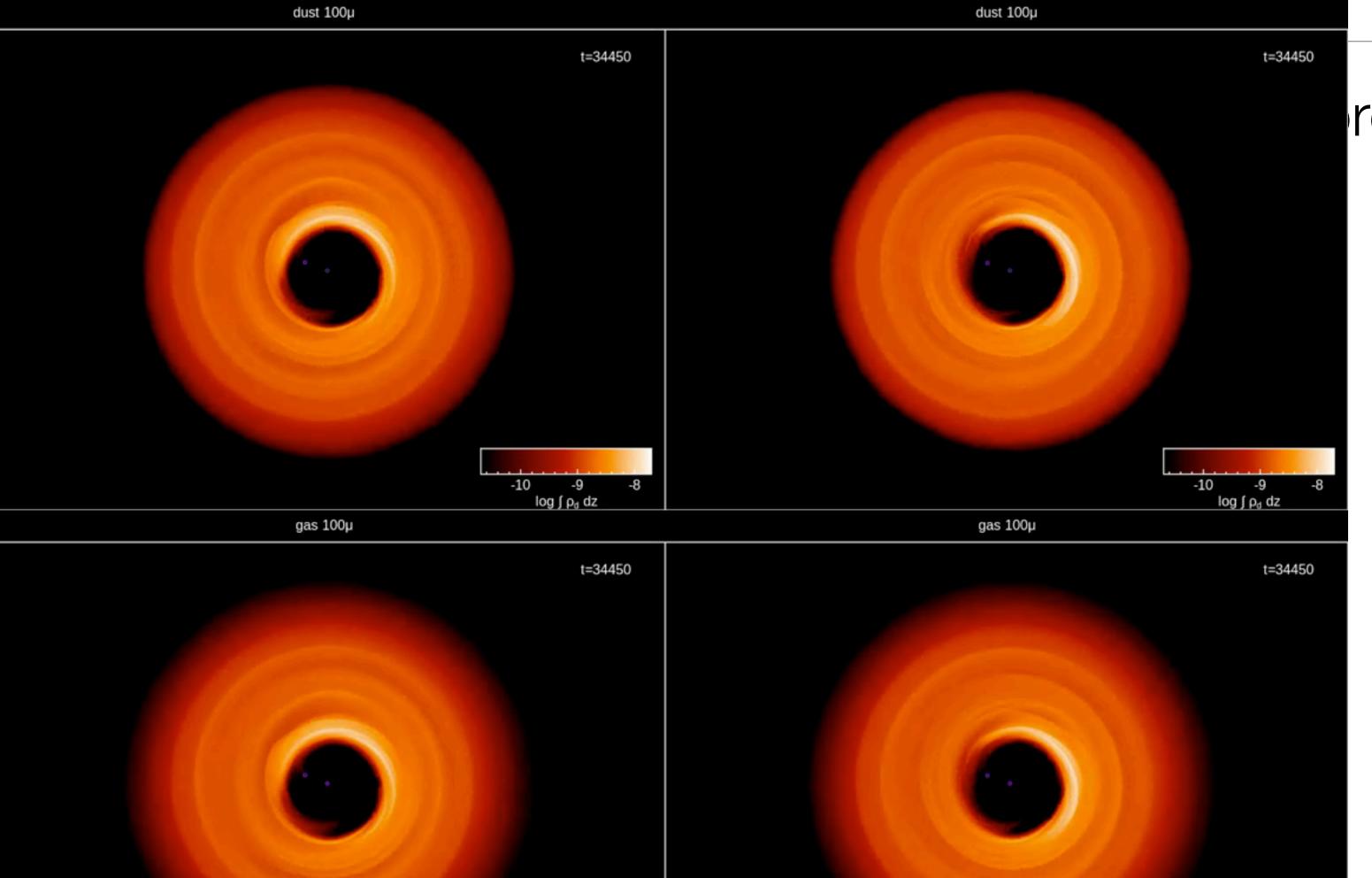
- eccentric instability
- Require mass ratios q > ~0.04 (D'Orazio et al 2016) •
- Well known in the context of supemassive black hole binaries •
- See Aitee et al (2013) for the protostellar case •

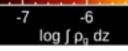
Ragusa et al, MNRAS in press 2016

Cavity produced by a massive planet or a low mass companion prone to

Asymmetric cavities in binary systems

- Cavity prod eccentric in
- Require ma
- Well known
- See Aitee e





Ragusa et al, MNRAS in press 2016

-7 -6

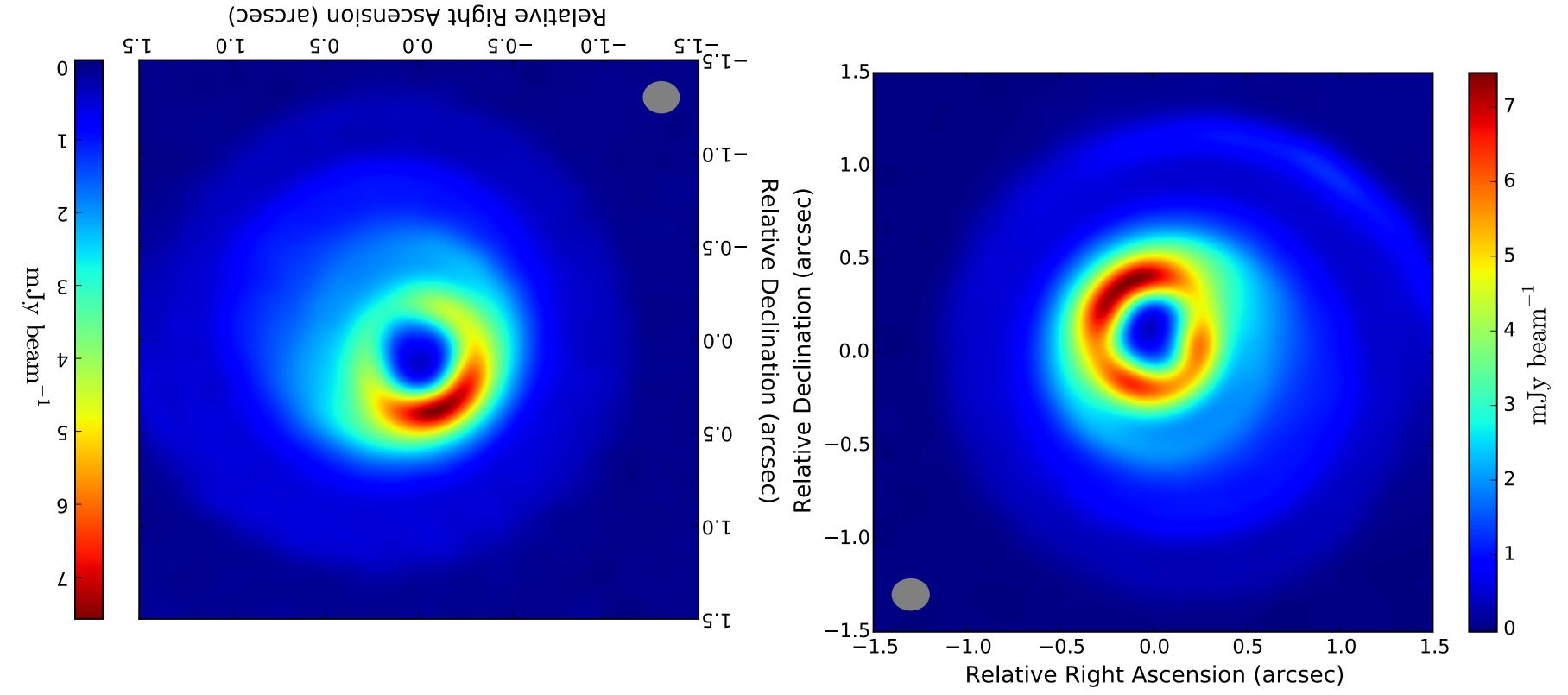
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rone to

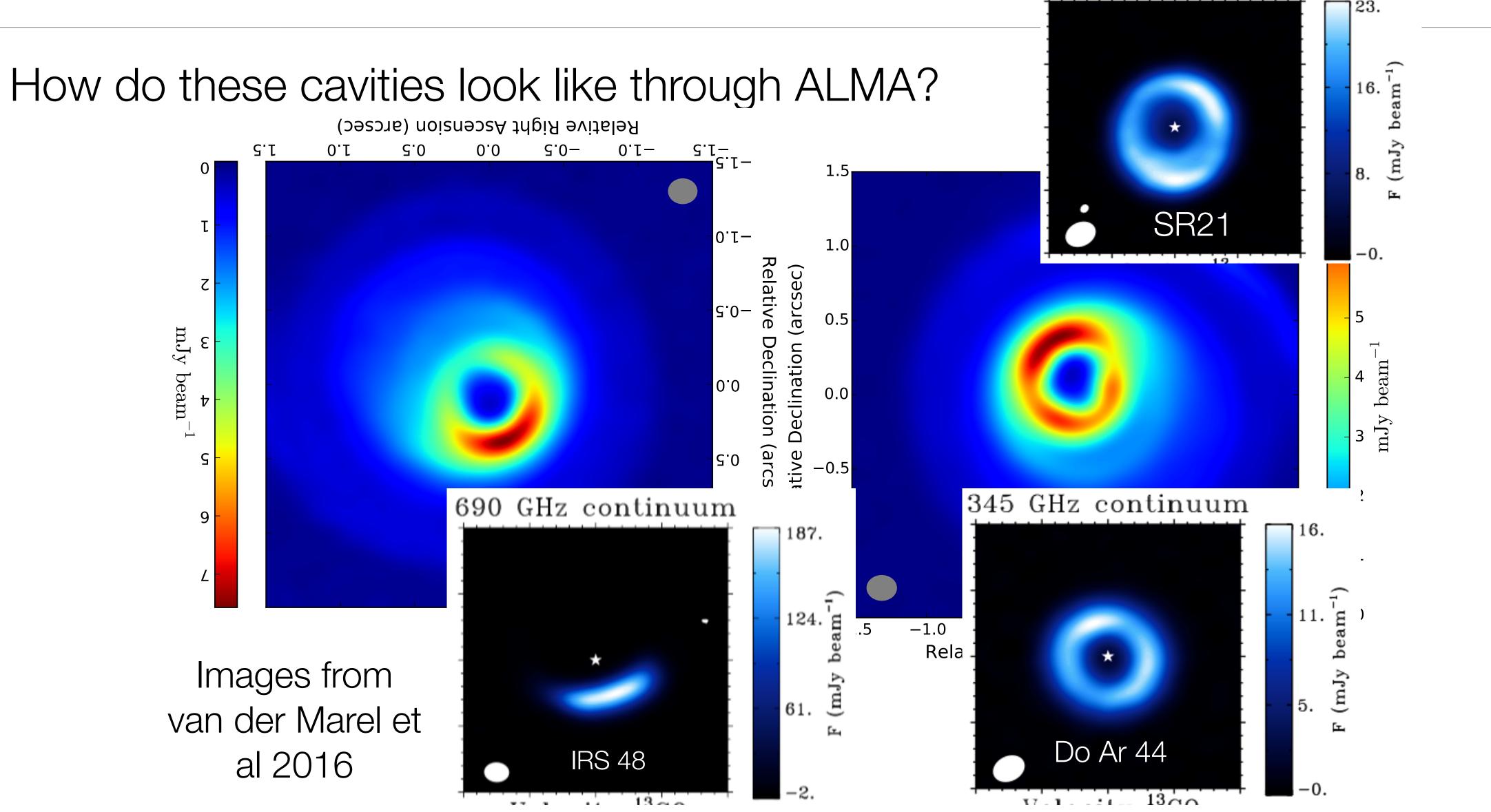
Ragusa et al, MNRAS in press 2016 Asymmetric cavities in binary systems

How do these cavities look like through ALMA? •



Ragusa et al, MNRAS in press 2016 Asymmetric cavities in binary systems

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Conclusions

- processes included
- appear to converge
- SPH usually does not break: very careful with validating ones solution •
- Very often, bad SPH results actually come from bad SPH codes
- SPH does not mean GADGET!!! ullet

SPH is reaching its maturity: a well founded hydro code with many physical

Whenever a detailed comparison with grid based code has been done, results