SuperComputing Applications and Innovation

## An introduction to

 Adaptive Mesh Refinement (AMR) Part 1: Numerical Methods and Tools

HPC Numerical Libraries 26-28 April 2016 CINECA - Casalecchio di Reno (BO)

## AMR - Introduction

- Solving Partial Differential Equations (PDEs)
- PDEs solved using discrete domain
- Algebraic equations estimate values of unknowns at the mesh points
- Resolution/Spacing of mesh points determines error
- Initial Solution and Boundary condition are needed
- Goal of grid adaptivity:
- tracking features much smaller than overall scale of the problem providing adequate higher spatial and temporal resolution where needed.


## AMR - Introduction



## Uniform meshes

High resolution required for handling difficult regions

- (discontinuities, steep gradients, shocks, etc.)

Computationally extremely costly

## Adaptive Mesh Refinement

- Start with a coarse grid
- Identify regions that need finer resolution
- Superimpose finer sub-grids only on those regions
- Increased computational savings over a static grid
- approach.
- Increased storage savings over a static grid approach.
- Complete control of grid resolution, compared to the fixed resolution of a static grid approach.


## AMR - Applications



- CFD
- Astrophysics
- Climate Modeling
- Turbulence
- Mantle Convection

Modeling

- Combustion
- Biophysics and many more

Demo of a Shock wave passing over a step function (wind tunnel with a step), rendered using the FLASH code.

## AMR Techniques

mesh distortion

Courtesy of Dr. Andrea Mignone, University of Turin

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$\square$ mesh distortion


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mesh distortion
point-wise structured (tree-based) refinement


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## AMR Techniques

mesh distortion
point-wise structured
(tree-based) refinement
-
block structured:


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data blocks are created so that the same stencil can be used for all points and no special treatment is required.High level objects that encapsulate the functionality for AMR and its parallelization are independent of the details of the physics algorithms and the problem being solved.Simplifies the process of adding/replacing physics modules as long as they adhere to the interface requirements.

## Existing Frameworks

- PARAMESH -
http://www.physics.drexel.edu/~olson/paramesh
- SAMRAI - https://computation.IInl.gov/casc/SAMRAI/
- p4est - http://www.p4est.org/
- Chombo -
https://commons.lbl.gov/display/chombo/Chombo
- and many more


-All the grid blocks are related to one another as the nodes of a tree.
-The starting block is called root block, and the blocks with an higher resolution are called leaf blocks.
-When a leaf block is designated for refinement, it spawns 2 child blocks in 1D, 4 child blocks in 2D or 8 child blocks in 3D, and the original block is called mother (or parent) block.
-These child blocks cover the same physical line, area or volume as their parent but with twice the spatial resolution.
- Usually it is helpful to use a particular numbering algorithm (see next slides).


## Typical grid hierarchy



- Each block has a fixed number of grid points -Each block can be divided into $2^{\text {ndim }}$ sub-blocks -Blocks are distributed between processes minimizing communications (see next slides)

An Example:
$\cdot 6 \times 4$ grid is created on each block
-The numbers assigned to each block designate the blocks location in the quadtree
-The numbers assigned to each block designate the blocks location in the quadtree

## Block ordering



- Usually, the most used block ordering algorithm is Morton (or Z) ordering.
- It is particularly useful in order to:
- Optimize the usage of cache memory;
- Optimize ghost cells communications between process (see next slide);



## Block Structure



Usually, each block is composed by: -standard cells

- ghost cells

In Fortran, the indexes starts with 1 and ends with $\mathrm{N}_{(\mathrm{X} \text { or } \mathrm{Y} \text { or } \mathrm{Z})}+2^{*}$ (number of ghost cells) In C , the indexes starts whit 0 and ends $\mathrm{N}_{(\mathrm{X} \text { or } \mathrm{Y}}$ or z$)+2^{*}($ number of ghost cells) -1

## Passing Ghost Cells

- ghost zones values need to be filled before integration;


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- ghost zones values need to be filled before integration;
- Patches at the same level are syncrhonized.


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## Passing Ghost Cells

- ghost zones values need to be filled before integration;
- Patches at the same level are synchronized;
- Physical boundaries are imposed externally;
- Fine-Coarse and Coarse-Fine interface need interpolation / averaging
- Integration proceeds as for the single-grid case


## Ghost cells communications



When we pass the ghost cells to the adjoining blocks, if these blocks have different resolutions we must modify the data.

The most simple (and used) method is the interpolation method:

- If we must pass the ghost cells to a block with higher resolution we can use the linear interpolation to artificially increase the resolution.
- If we must pass the ghost cells to a block with lower resolution we can average the data in order to have the same resolution.


## Pros:

-Easy to implement

- It is possible to use many different kind of interpolation (linear, quadratic, and so on) increasing precision


## Cons:

-Non-conservative

## Passing ghost cells to neighbors blocks



Summation of fluxes at shared cell faces on adjoining grid blocks at different refinement levels. Flux densities are denoted by $f$ and cell face areas by $A$.

Flux conservation:
It is possible to ensure flux conservation after the interpolation checking the equation:
$\mathrm{f}_{1} \mathrm{~A}_{1}+\mathrm{f}_{2} \mathrm{~A}_{2}+\mathrm{f}_{3} \mathrm{~A}_{3}+\mathrm{f}_{4} \mathrm{~A}_{4}=\mathrm{F}_{\text {Tot }} \mathrm{A}_{\text {Tot }}$

## Passing ghost cells to neighbors blocks



Circulation integral control:
It is possible also to check the value of some physical quantity at the edges of the cells

Edge based data on the shared cell face of adjoining grid blocks of different refinement level.

NOTE: Both these three methods are usable in order to change the resolution of the blocks.

## Particular Geometries


(c)
(b) directions, and 1 block on $x$ direction (same resolution on $x$ and $y$, and more parallelizable)


## How to refine

- fill data, level 0


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- find where refinement is needed;


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- fill data, level 0
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- fill data, level 0
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- refine and ensure proper nesting


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- fill data, level 0
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efficiency $=0.9$

efficiency $=0.7$


## Little more background on AMR



Refinement structure can be represented using a quad-tree (2D)/ oct-tree (3D)

An important condition in AMR
Refinement levels of neighboring blocks differ by $\pm 1$
Note: This is generally true, but Chombo library allow more than 1 refinement level discrepancy.

## Traditional Approach - Parallel Implementations



- A set of blocks assigned to a process
- Use space-filling curves for load balancing



## Traditional Approach - Disadvantages

-Adaptive mesh restructuring:
-Tree metadata replicated on each process
$\checkmark$ Required memory increases with \# of cores
$\checkmark$ Memory can became a problem if we use
more than $10^{5}$ cores (and more than $10^{6}$ boxes)
-Level-by-level restructuring
-Ripple propagation
-Step needed to propagate restructuring $\propto$ level of refinement (d)

-Load Balancing
-Memory needed $\propto$ Number of blocks used
-Time needed $\propto$ Number of blocks used
-Currently for 3D problems with less than $10^{6}$ boxes standard AMR library scales up to few tens of thousands of cores
-This is a serious problem considering that next generation supercomputers will require the use of many hundreds of thousands of cores

## Improving AMR: Possible strategies

1. Compress tree metadata

- Already implemented in the last versions of CHOMBO, PARAMESH and SAMRAI libraries

2. Rewrite the algorithm for coarse-fine interpolation in order to minimize communications
-Already implemented in the last versions of CHOMBO, PARAMESH libraries

- Using these first two methods it is possible to scale up to $2 \times 10^{5}$ cores using $10^{7}$ grid cells

3. Use a distributed memory version for tree metadata
-Currently Langer at al are working on the implementation of this algorithm on
CHARM++

## Some additional information about PARAMESH

-Written in Fortran 90

- Easy to implement on a existing code
-Support many geometries (Cartesian, cylindrical, spherical, from 1D to 3D)
-Refinement levels of neighbouring blocks differ by $\pm 1$
-Compatible with hdf5 format
- Some simple routine are already written by the authors of the library in order to save the data and the grid structure into Fortran binary format, and hdf5 format.
-Easy visualization of the results using many external programs (e.g. visit)


## Some additional information about CHOMBO

-Written in C
-Easy to implement on a existing code

- Support many geometries (Cartesian, cylindrical, spherical, from 2D to 3D)
-Compatible with hdf5 format
-Easy visualization of the results using many external programs (e.g. visit)


## Example: 2D Blast Wave



> Problem: Blast Wave - Cloud Interaction Base Grid: $128 \times 128$ $\frac{\text { Levels of Refinement: }}{5 \text { (eq. } 4096 \times 4096)}$ Method: Unsplit PPM Code: PLUTO + Chombo Lib

## Example: 3D Rayleigh-Taylor



## Problem: <br> Rayleigh Taylor <br> Base Grid: <br> $32 \times 64 \times 32$ <br> Levels of Refinement: <br> 2 (eq. 128x256x128) <br> Method: <br> Unsplit PPM <br> Code: <br> PLUTO + Chombo Lib

Courtesy of Dr. Andrea Mignone, University of Turin

## Example: 3D INCOMPRESSIBLE FLUID FLOW Breaking waves due to a ship's hull.



Thank you for attention


## CINECA <br> 䇆数

SuperComputing Applications and Innovation
An introduction to Adaptive Mesh Refinement (AMR)

Part 2: A very short tutorial about PARAMESH

HPC Numerical Libraries 26-28 April 2016
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## Step 1: How to install

-Downolad the source code from:
http://downloads.sourceforge.net/project/paramesh/PARAMESH/paramesh_4.1/paramesh_4 .1.tar.gz
-On PICO use the wget command
-Uncompress the source files:
-tar -xzvf paramesh_4.1.tar.gz
-Enter in the main source directory:
-cd paramesh_4.1
-Load MPI module:
-module load autoload intelmpi/5.1.1--binary
-Edit the Makefile.gnu file:

- kate Makefile.gnu
-Comment row 51 (NAG specific compilation commands)
-Uncomment row 58 (Intel specific compilation commands)
- Save and close the file
-Compile the source code:
-gmake -f Makefile.gnu


## Step 2: Our problem

Solve

$$
\frac{d}{d t} U(x, y, t)=\kappa\left(\frac{\partial^{2}}{\partial x^{1}}-\frac{\partial^{2}}{\partial y^{2}}\right) U(x, y, t)
$$

in the domain

$$
x|\leq 4,|y| \leq 4
$$

with

$$
\kappa-1,
$$

with timestep

$$
\Delta t=\frac{1}{10} \frac{\min \left(\Delta x^{2}, \Delta y^{2}\right)}{\kappa}
$$

and initial concitions

$$
U(x, y, 0)= \begin{cases}10.0 & \text { if }|x| \leq 1 \text { and } \mid y \leq 1 \\ 1.0 & \text { otherwise }\end{cases}
$$

-Our numerical scheme (4-pt centered second order accurate difference method):
$U(i, j, t+d t)=U(i, j, t)+d t{ }^{*} A /\left(d x^{*} d x\right)$
$A=U(i+1, j, t)+U(i-1, j, t)+U(i, j+1, t)+U(i, j-1, t)-4^{*} U(i, j, t)$

## Step 3: Create the files

## -Preliminary steps:

-Create a subdirectory inside PARAMESH main directory (AMRDIR from now) named your_tutorial
-Copy the file AMRDIR/templates/amr_main_prog_template.F90 into the current directory and rename it tutorial.F90
-Copy the file AMRDIR/templates/amr_1blk_bcset_template.F90 into the current directory and rename it amr_1blk_bcset.F90


## Step 4: Modify paramesh_preprocessor.fh (old version)

-Edit the header file paramesh_preprocessor.fh
$\cdot c d$ to $A M R D I R /$ headers
-Edit paramesh_preprocessor.fh
-If you want to use double precision then define REAL8: \#define REAL8
-Comment out the following preprocessor definitions (none of these features will be used in this example):
!\#define VAR_DT
!\#define PRED_CORR
!\#define EMPTY_CELLS
-Define the preprocessor variable DIAGONALS (used only during the test phase in this case): \#define DIAGONALS

- Set the model dimensionality to 2 by setting
\#define N_DIM 2
-Leave CURVILINEAR undefined since we are using cartesian coordinates in the tutorial.
-Comment out the following preprocessor definitions since none of these features will be used in this example.
!\#define NO_PERMANENT_GUARDCELLS
!\#define ADVANCE_ALL_LEVELS
-Make the following definitions to set up the case we want to run. In order, these settings establish the grid blocks as $4 \times 4$, allow up to 100 blocks on each processor, establish 1 cell centered variable and 0 cell-face-centered variables, 0 edgedentered variables, 0 corner-centered variables, and set 1 layer of guard cells at each block boundary.
\#define NX_B 4
\#define NY_B 4
\#define MAX_BLOCKS 100
\#define N_GŪARD_CELLS 1
\#define N_GUARD_CELLS_WORK 1
\#define N_VAR 1
\#define N_FACEVAR 0
\#define N-VAR EDGE 0
\#define N_VAR_CORN 0
\#define N_VAR_WORK 1
\#define N_FLUX_VAR 1
\#define N_EDGE_VAR 0


## Step 4: Modify paramesh_preprocessor.fh <br> and amr_runtime parameter

-Edit the header file paramesh_preprocessor.fh
-cd to AMRDIR/headers
-Edit
paramesh_preprocessor.fh - If you want to use double precision then define REAL8:
\#define REAL8
-Edit the amr_runtime_parameter file
-cd to AMRDIR/
-Copy amr_runtime_parameter into your_tutorial directory
-Edit the file in the your_tutorial directory following this example:


## Step 5: Create the makefile

-Copy the AMRDIR/templates/Makefile.gnu_template file into your_directory

- Edit the file:
- Modify the macro definition MAIN to:
main := tutorial. $F 90$
- Modify the macro definition SOURCES to:
sources :=amr_1blk_bcset.F90
-Define the CMD macro to be tutor, ie:
CMD = tutor
-cd back on AMRDIR
-Copy Makefile.gnu into make_tutor.
-Edit the file:
-Replace the character string 'User_applic' with 'your_tutorial', wherever it appears.



## Step 6: Modify the program template

-Edit the file tutorial.f90:
-The file is divided into a sequence of numbered sections. Comment out all executable lines in sections 4,5 and 6.
-Edit the file amr_1blk_bcset.F90:
-Uncomment the line:
! if(ibc.eq. ????) then

- and its corresponding endif.
-Change the ???? in the if statement to any integer less than or equal to -20
-Uncomment the line:
! unk1(:, i, j, k,idest) = ???? !<<<<< USER EDIT
-and replace the right hand side of this line with 0.0


## Step 7: Build \& Run

## -Build the executable:

gmake -f make_tutor your_tutorial
-Run the executable:
./tutor
-If everything went according to plan you should have generated a short output listing which concludes with something equivalent to the following lines (the order in which the blocks are listed may vary slightly, from one machine to another):



## Step 8: Inizializing the solution

-copy the file AMRDIR/templates/amr_initial_soln_template.F90 into the current directory and rename it amr_initial_soln.F90
-edit /your_tutorial/Makefile.gnu, adding amr_initial_soln.F90 to the macro definition of source
-Edit amr_initial_soln.F90:
-delete the lines unk(1,i,j,k,lb)=??? and unk(2,i,j,k,lb)=??? the 3 dotted lines that follow.
-insert the following lines before the triply nested loop which sets values for unk:
$\mathrm{dx}=\mathrm{bsize}(1, \mathrm{lb}) /$ real $(\mathrm{nxb})$
dy = bsize(2,lb)/real(nyb)
-replace the line unk $(1, i, j, k, l b)=$ ??? with the following segment:
unk $(1, i, j, k, l b)=1.0$
$x i=$ bnd_box(1,1,lb) + dx*(real(i-nguard0)-.5)
yi = bnd_box(1,2,lb) + dy*(real(j-nguard0)-.5)
if( abs(xi).lt.1.0 .and. abs(yi).lt.1.0) then
$\operatorname{unk}(1, i, j, k, l b)=10.0$
endif
-Edit tutorial.F90:
-uncommenting the call to amr_initial_soln, in SECTION 4.
-insert the following write statements at the end of SECTION 4.
do lb=1, lnblocks
if(coord(1,lb).eq.1.0.and.coord(2,lb).eq.1.0) then
do $j=1$, nyb $+2 *$ nguard
write (*,50) j, (unk(1, i,j, 1,lb), i=1, nxb+2*nguard)
enddo
endif

## Step 9: Build \& Run

-Remake and run:
cd AMRDIR
gmake -f make_tutor your_tutorial
cd your_tutorial
./ tutor

- You have now initialized the solution array unk ( $1,:,:,:,:$, ) on all the grid blocks of the initial grid. As proof, the last six lines of your output show the data values on the centered at (1.0,1.0). It should look like this:

| File | Edit View | Search | Terminal | Help |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 0.0000 | 0.0000 | 0.0000 | 0.0000 | 0.0000 | (0.0000 | ค |
| 2 | 0.0000 | 10.0000 | 10.0000 | 1.0000 | 1.0000 | 0.0000 |  |
| 3 | 0.0000 | 10.0000 | 10.0000 | 1.0000 | 1.0000 | 0.0000 |  |
| 4 | 0.0000 | 1.0000 | 1.0000 | 1.0000 | 1.0000 | 0.0000 |  |
| 5 | 0.0000 | 1.0000 | 1.0000 | 1.0000 | 1.0000 | 0.0000 |  |
| 6 | 0.0000 | 0.0000 | 0.0000 | 0.0000 | 0.0000 | 0.0000 | - |
| mguarral@node066.plco:[your_tutorlal]\$ $\square$ |  |  |  |  |  |  |  |

-This block is located at $0<x<2$ and $0<y<$ 2. It straddles one corner of the high density region. Notice, the $4 \times 4$ block interior has been initialized with non-zero values and there is a layer of guard cells surrounding the block which are currently all set to 0.0. -The complete initial state is shown here, with the block boundaries superimposed in black and the grid cells outlined in red:


## Step 10: Filling Guardcells

-Edit the file tutorial.f90:
-Uncomment the 3 executable lines in SECTION 5.

- Move the output code fragment shown below from the end of SECTION 4 to the end of SECTION 5:
do lb=1, lnblocks
if(coord(1,lb).eq.1.0.and.coord(2,lb).eq.1.0) then
do $j=1, n y b+2 * n g u a r d$

```
                                    write(*,50) j,(unk(1,i,j, 1,lb),i=1,nxb+2*nguard)
```

enddo
endif
enddo
50 format(1x,i3,6(2x,f7.4))

## Step 11: Build \& Run

-Remake and run:
cd AMRDIR
gmake -f make_tutor your_tutorial
cd your_tutorial
./tutor

- Notice, the guard cell layer has been filled with the correct data from the neighboring blocks.



## Step 12: Constructing a routine to test refinement levels - 1

-Copy AMRDIR/templates/amr_test_refinement_template.F90 into the local directory and rename it amr_test_refinement.F90
-edit /your_tutorial/Makefile.gnu, adding amr_test_refinement.F90 to the macro definition of source -Edit amr_test_refinement.F90, commenting out the call to error_measure and immediately after the call inserting this simple error measure:
$\operatorname{error}(:,:,:,:)=0$.
do k=klw,kuw
do $j=j l w+1$, juw-1
do $\mathrm{i}=\mathrm{ilw}+1$, iuw- 1
error1 $=\operatorname{abs}(\operatorname{work}(\mathfrak{i}+1, j, k, l b, 1)-\operatorname{work}(i, j, k, l b, 1))$
error2 $=\operatorname{abs}(\operatorname{work}(\mathrm{i}-1, \mathrm{j}, \mathrm{k}, \mathrm{lb}, 1)-\operatorname{work}(\mathrm{i}, \mathrm{j}, \mathrm{k}, \mathrm{lb}, 1))$
error3 $=\operatorname{abs}(\operatorname{work}(\mathrm{i}, \mathrm{j}+1, \mathrm{k}, \mathrm{lb}, 1)-\operatorname{work}(\mathrm{i}, \mathrm{j}, \mathrm{k}, \mathrm{lb}, 1))$
error4 = abs(work(i,j-1,k,lb,1)-work(i,j,k,lb,1))
error_num $=\max ($ error1, error2,error3,error4 $)$ error_den $=\max (\operatorname{work}(i, j, k, l b, 1)$, work $(i+1, j, k, l b, 1), \&$ work( $\mathrm{i}-1, j, k, l b, 1$ ), work ( $\mathrm{i}, \mathrm{j}+1, \mathrm{k}, \mathrm{lb}, 1$ ), \& work(i,j-1,k,lb,1), 1.0e-6 )
error(i,j,k) $=$ error_num/error_den
enddo

## enddo

enddo
-Edit tutorial.F90
-Uncomment the call to amr_restrict and the 2 lines preceding it (making sure that the 'if
(.not.advance_all_levels) then' and corresponding 'endif' are also uncommented), and uncomment the calls to amr_test_refinement, amr_refine_derefine, amr_prolong and amr_guard cell in SECTION 6.
-Change Irefine_max in SECTION 3 to allow 1 more level of refinement:
Trefine_max = 4

## Step 12: Constructing a routine to test refinement levels - 2

-Continue in editing tutorial.F90:
-Insert the following lines after the call to amr_test_refinement in SECTION 6:
if(mype.eq.0) write( ${ }^{*},{ }^{*}$ ) ' pe blk refine derefine', \&
curr.ref.level'
call MPI_BARRIER(MPI_COMM_WORLD, ierr)
do $\mathrm{l}=1$, $\overline{\text { nhblocks }}$
write (*, 51) mype, l , refine $(\mathrm{l})$, derefine(l), trefine( l$)$
enddo
51 format(1x, i3,2x, i3,2x, $18,2 x, 18,10 x, i 3)$

- Insert the following lines at the end of SECTION 6:
if (mype.eq.0) write (*,*) 'pe / blk / blk-coords / blk-sizes'
call MPI_BARRIER(MPI_COMM_WORLD, ierr)
do $\mathrm{l}=1$, lnblocks
write(*,*) mype, $\mathrm{l},(\operatorname{coord}(\mathrm{i}, \mathrm{l}), \mathrm{i}=1$, ndim), (bsize ( $\mathrm{j}, \mathrm{l}), \mathrm{j}=1$, ndim)
enddo
- Set the number of guard cell layers for 'work' :
-Edit amr_runtime_parameters, defining the variable:


## Step 13: Build \& Run - 1

-Remake and run:
cd AMRDIR
gmake -f make_tutor your_tutorial
cd your_tutorial
./tutor
-The changes that you have just made, analyzed the error estimate on each existing grid block, and marked some blocks for additional refinement. In your new output there will be a section looking like this (the order of lines may be slightly different) :

-This is telling you that the test in amr_test_refinement marked blocks $3,6,7,10,13,14$, 17, and 18 for further refinement.
-However blocks 3, 7, 13, and 17 are parent blocks at level 2 and so their refinement flags will be ignored.
$\cdot$ Blocks 6, 10, 14 and 18 will be refined. Notice also that blocks $2,4,5,8,9,11,12,15,16,19,20$ and 21 have been marked for derefinement.
-However each of these blocks has a sibling which has not been marked for derefinement (in fact all their siblings have been marked for refinement ), and so these particular derefinement choices will be cancelled by PARAMESH.

## Step 13：Build \＆Run－2

－This is the new positions of the grid blocks：
－and this is the new structure：

| 图 mguarra1＠node066：～／PARAMESH／test／paramesh＿4．1／your＿tutorial |  |  |  |  |  | －－$\times$ |
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| － |  | $-1.50000000000000$ | －0．50000000000000 | 1．00000000000000 | 1．00000000000000 |  |
| － | 10 | －0．500000000000000 | －0．500000000000000 | 1．00000000ө00000 | 1．00000000000000 |  |
| 0 | 11 | $2.00000 \theta 00 \theta 00000$ | －2．000өөө日өө日өө日 | 4．00өөө日өөө日өө日 | 4．0ө日өөөөөөөө日ө |  |
| － | 12 | 1．00000000000000 | －3．000000000日0009 | 2.00000000000000 | 2．000000000000日 |  |
| － | 13 | з．00000000өөө000 | －3．0000000000000ө | 2．00000000000000 | 2．00000000000000 |  |
| 0 | 14 | 1．000000000日0000 | －1．00000000000000 | 2．000000000日0000 | 2．000000000日00日 |  |
| － | 15 |  | －1．500өөө日өөө日ө日ө | 1．өө日өөөөөөөө日өө | 1．0өө日өө日өөөөө日 |  |
| － | 16 | 1.50000000000000 | －1．50000000000000 | 1．00000000000000 | 1．00000000000000 |  |
| － | 17 |  |  |  | 1．0ө0ө日ө日өөө日өөө |  |
| 0 | 18 | 1.50090900909009 |  | 1．．ө0ө日өөөөөөө日өө |  |  |
| － | 19 | з． 0 өөөө日өө日өө日өө | －1．000000000000日 | 2．00000000ө日ө日00 | 2．00000ө000ө日0ө0 |  |
| 0 | 20 | －2．00000000000000 | 2．00000000000000 | 4.00000000000000 | 4．00000000000000 |  |
| － | 21 | －3．өө日өөөөөөө日豕 | 1．00өөөөөөөөөөөө | 2． ．0өөөөөөөөөөө |  |  |
| 0 | 22 | $-1.00000000000009$ | 1．000өөө日өөөөө日0 | 2．000өө日өө日өө日00 | 2．00000ө日өөө日000 |  |
| 0 | 23 | $-1.50009000900098$ |  | 1．00өөө日өө日өө日өө | 1．0ө0ө日ө日өө日өө日 |  |
| 0 |  |  |  | 1．000000000日0日00 |  |  |
| 0 | 25 | $-1.5000 \theta \theta 00 \theta 00000$ | 1．500өөөөөөөөө日 | 1．000өөө日өөөөөөө | 1．0ө0өөөөөөөөөөө |  |
| － | 26 |  | 1．50000000日ө0日00 |  |  |  |
| 0 | 27 | －3．өө日ө日өөө日өө日өө | 3． ．0өөөөөөөөөө日 | 2． ．0ө日өөөөөөө日өө |  |  |
| － | 28 | $-1.00000900090000$ |  |  |  |  |
| 0 | 29 | 2.00009000900000 |  | 4．000өөө日өөөөө日 | 4．0ө0өөө日өөөөө日 |  |
| 0 | 30 | 1．000өө日өөөөө日өө | 1．00өөөөөөөөөө日 | 2.00090900909090 |  |  |
| － | 31 |  |  | 1．00өөө日өөө日ө日өө | 1．0өө日өөө日өөө日өө |  |
| － | 32 | 1．5000000日000000 | 0．50000日0000ө日ө00 | 1．00000ө00өөө00 | 1．0ө0000өөө日өө日 |  |
| 0 | 33 | 0．50000ө日ө日өөө日өө |  | 1．00өөө日өөөөөөөө | 1．000өөөө日өөөө日 |  |
| 0 | 34 | 1.50000900900090 |  |  |  |  |
| 0 | 35 | з．өөө日өө日өөөөөө | 1．000өө日өөө日өөө |  | 2．0ө0ө日ө日өө日өө日 |  |
| 0 | 36 | 1．000ө日ө日ө日өө日өө | з．өөө日өө日өөөөөөө |  |  |  |
| 0 | 37 | з．0000ө000000000 | з．000000000ө0000 | 2.00000000000000 | 2．000000000000日 |  |
|  |  |  |  |  | 77，1 |  |



## Step 14: Create the routine to update the solution

-Copy the file ../teamplates/amr_initial_soln.F90 to advance_soln.F90
-Edit advance_soln. F90, making the following changes:
-Change the subroutine statement to:
subroutine advance_soln(mype,time,dt)
-Make the same modification to the end statement
-end subroutine advance_soln
-Add the declarations:
integer :: mype
real :: time,dt
real old_soln(il_bnd:iu_bnd,jl_bnd:ju_bnd,kl_bnd:ku_bnd)
-making sure that they appear after the use statements.
-Before the "! loop over leaf grid blocks" comment line insert the line:
call amr_timestep(dt,dtmin,dtmax,mype)
-Insert the following line immediately before the "! set values for unk" comment line:

```
old_soln(:,:,::)=unk(1,:,:,:,lb)
```

$\mathrm{dx}=\mathrm{bsize}(1, \mathrm{lb}) /$ real(nxb)
-Replace the triply nested loop which updates 'unk' with the following lines:

```
do k=kl_bnd+nguard*k3d,ku_bnd-nguard*k3d
do j=jl_bnd+nguard*k2d,ju_bnd-nguard*k2d
do i=il_bnd+nguard,iu_bnd-nguard
unk(1,i,j,k,lb) = old_soln(i,j,k) + dt/(dx*dx)* (&
old_soln(i+1,j,k) + old_soln(i-1,j,k) + & 
old_soln(i,j+1,k) + old_soln(i,j-1,k) - &
old_soln(i,j,k)*4.0 )
enddo
enddo
enddo
```

-Add the following lines before the return statement:

## Step 15: Create the timestep routine

-Copy AMRDIR/templates/amr_timestep_template.F90 in to the current directory and rename it amr_timestep.F90
-Edit amr_timestep.F90, making the following changes:
-Delete the lines declaring the real variables speed2, press and maxspeed.
-Delete the line including the file pointers.fh
-Delete the following lines inside the loop over grid blocks
rho $\Rightarrow$ ) unk ( $1, \ldots, \ldots, \therefore, \mathrm{l}$ )
vx $=>\operatorname{unk}(2,:,:, \therefore,!$ )
vy => unk ( $3,:,:,:$, , l)
vz => unk(4,:,:,:,:, $)$
-Change the parameter statement defining courant to:
real, parameter :: courant=.1, kappa=1.0
-Replace all the lines in the section labeled 'users timestep calculation' with the following line:
-dtl = courant**×*dx/kappa


## Step 16: Modify main program to call the advance_soln routine.

-Edit tutorial.F90 making the following changes:
-Uncomment the lines setting minstp and maxstp.
-Uncomment the do istep=... statement and the corresponding enddo statement.
-Uncomment the call to advance_soln .F90 .
-Delete the two blocks of output code which we inserted into SECTION 6 earlier.

- Insert the following output code immediately after the call to advance_soln:

```
write(*,*) 'dt = ',dt
do lb=1,lnblocks
    if(coord(1,lb).eq.1.0.and.coord(2,lb).eq.1.0) then
        do j=1,nyb+2*nguard
        write(*,50) j,(unk(1, i, j, 1,lb), i=1,nxb+2*nguard)
        enddo
        endif
enddo
```


## Step 17: Build \& Run

-remake and rerun by typing:
gmake -f make_tutor your_tutorial . ./tutor

- You have now advanced the solution through 1 timestep, and the output section immediately after the call to advance_soln will show how the data on the block centered on $(1.0,1.0)$ has been diffused. The data should look like this: :
- Note, at this point the cell interior (indeces 2-5 in both $x$ and $y$ ) are correct, but the guardcells (indeces 1 and 6) have not yet been updated.
-After the solution has been advanced on the block interiors, we test the solution to see if refinement is required. In this case refinement is selected for the 4 blocks around the center of the domain. These are refined, and the solution is prolonged to the newly created blocks there. The complete updated solution after these steps is shown here


## Step 18: Run for 250 timesteps - 1

-Edit tutorial.F90 making the following changes:
-Set maxstp = 250
-Remove the output statements immediately after the call to advance_soln in SECTION 6.
-Insert the following line into SECTION 6 immediately before the enddo statement:
if(mype.eq.0) write(*,*) 'iteration ',istep, \&
' no of blocks = ',lnblocks
-Insert the following statements immediately before the amr_close call:
if (mype.eq.0) write (*,**) 'pe / blk / blk-coords / blk-sizes'
call MPI_BARRIER(MPI_COMM_WORLD, ierr)
do $\mathrm{l}=1$, Inblocks
write (* ${ }^{*}$ ) mype,, , (coord( $\left.\mathrm{i}, \mathrm{l}\right), \mathrm{i}=1$, ndim $),(\operatorname{bsize}(j, \mathrm{l}), j=1$, ndim $)$
enddo
-remake and rerun by typing:
gmake -f make_tutor your_tutorial .
./tutor
-In your output you will notice that before the first timestep we had 21 blocks, with uniform refinement at level 3 throughout the computational domain. On the first timestep (iteration 1) the 4 blocks at the center containing the high data values were refined, adding 16 blocks to make a total of 37 . After the seventeenth timestep the solution has diffused outward so that all the outer level 3 blocks, except for those on the corners, are now all marked for refinement, adding another 32 child blocks at level 4, for a total of 69 .

## Step 18: Run for 250 timesteps - 2

-After 250 timesteps, we can see from the final block listing below that block number 55 is a leaf block located near the origin (it has coordinates $x=0.5, y=0.5$; the line order may be slightly different in your output).

## Step 19: Check solution

-Edit tutorial.F90, adding the following immediately before the call to amr_close, to show the solution on the block centered on $(0.5,0.5)$ :

```
do lb=1, Inblocks
        if (coord(1,lb).eq..5. and.coord(2,lb).eq..5) then
            do \(j=1\), nyb+2*nguard
                write(*,50) j,(unk(1,i,j,1, lb ), i=1, nxb+2*nguard)
            enddo
        endif
    enddo
```

-remake and rerun by typing:
gmake -f make_tutor your_tutorial. ./tutor

- Your final lines of output should look like this:

图 mguarral@node066:~/PARAMESH/test/paramesh_4.1/your_tu _ $\quad \times$ File Edit View Search Terminal Help

| 1 | 2.6343 | 2.6343 | 2.6062 | 2.5514 | 2.4728 | 2.3744 | A |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 2 | 2.6343 | 2.6343 | 2.6062 | 2.5514 | 2.4728 | 2.3744 |  |
| 3 | 2.6062 | 2.6062 | 2.5785 | 2.5247 | 2.4475 | 2.3508 |  |
| 4 | 2.5514 | 2.5514 | 2.5247 | 2.4727 | 2.3982 | 2.3049 |  |
| 5 | 2.4728 | 2.4728 | 2.4475 | 2.3982 | 2.3275 | 2.2391 |  |
| 6 | 2.3744 | 2.3744 | 2.3508 | 2.3049 | 2.2391 | 2.1567 | $=$ |
| mguarra1@node066.pico:[your_tutorial]\$ $\square$ |  |  |  |  |  |  | $\checkmark$ |

-The final solution is displayed here:
$>$


## Step 20: Run in Parallel

-Create the file jobscript.sh

- Open the file
-Write:

-Type:
qsub jobscript.sh


Thank you for your attention


