



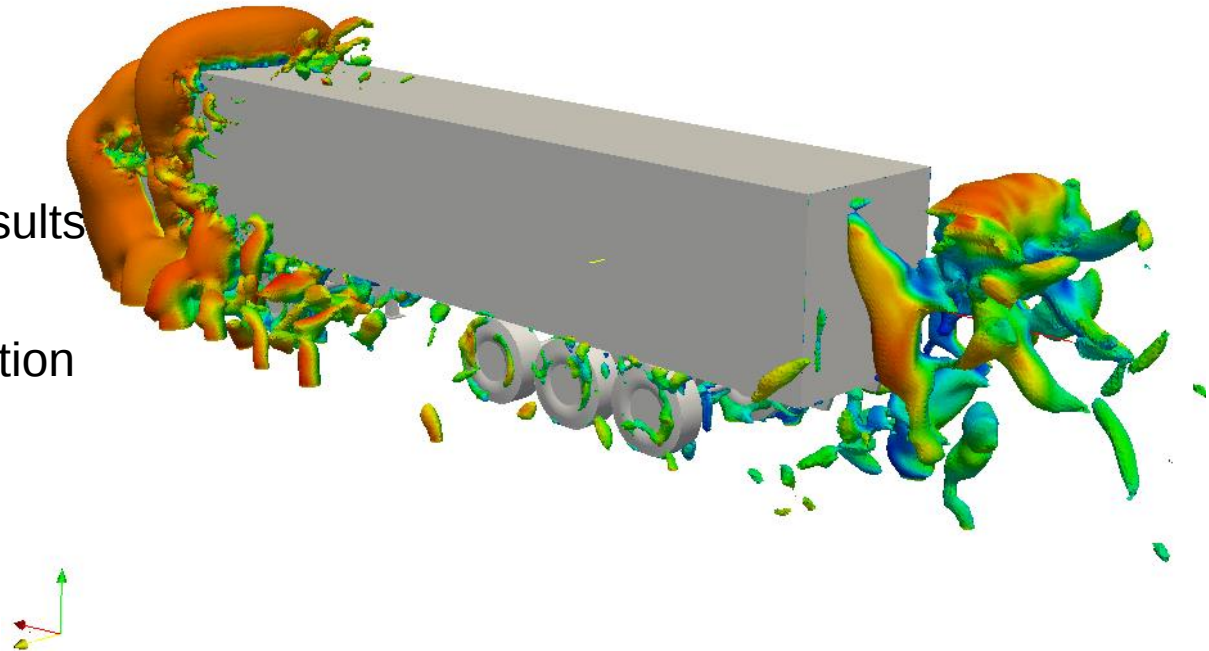
HEAVY TRUCK AERODYNAMICS

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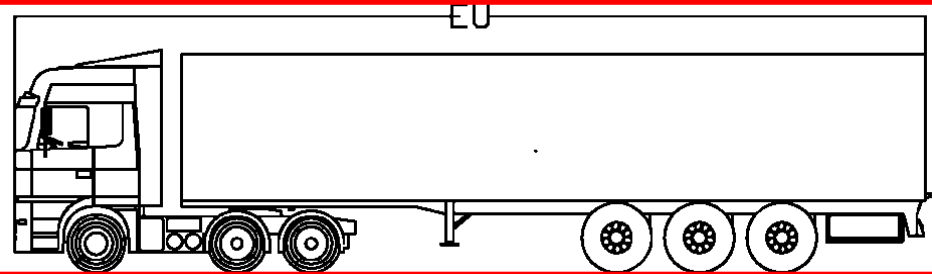
Department of Mechanical Engineering

- Introduction
- Simulations Set-up
- RANS Simulation
 - Target vehicle results
 - Tested devices
 - Devices optimization
 - Crosswind
- DES Simulation
- Conclusion

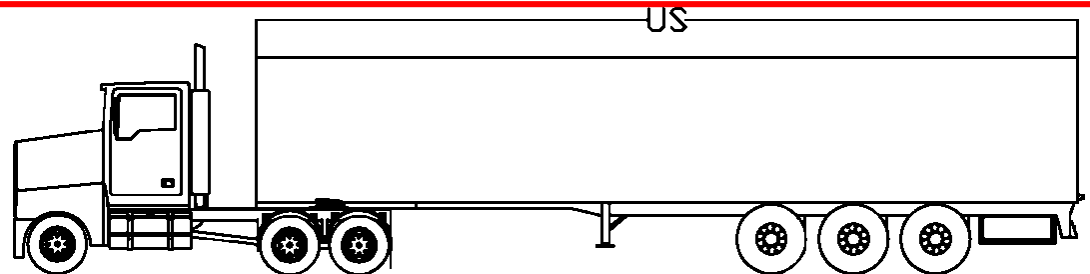


Current regulation: Directive 96/53 EC

width < 2,55 m
height < 4,00 m
overall length < 16,50 m



width < 2,6 m
height < 4,10 m
loading length ~ 14 -18 m



European Commission – DGMOVE – Working group on Aerodynamics:.

Analyze impact on fuel consumption of :

- higher aerodynamic efficiency,
- combustion efficiency,
- energy efficiency and
- **Risks connected with the increase of the maximum permitted dimension of the vehicle.**

Fuel saving		1,00%
Fuel consumption	2,6	(Km/l)
Fuel cost	1,6	(€)
Km travelled per day	880	(Km/day)
Liter per day	338,5	(l/day)
Economical Benefit		
Liter saved per day	3,38	(l/day)
Euro saved per day	5,42	(€/day)
Working day	22	(day/month)
Saved per mounth	119	(€/month)
Saved per year	1'430	(€/truck)
Emission		
CO ₂ emission per liter	2,4	(kg/l)
CO ₂ emission saving	8,12	(kg/day)
CO ₂ emission saving	178,71	(kg/month)
CO₂ emission saving	2144	(kg/year)

Devices currently installed on the heavy-truck :

- cab roof fairings (drag reduction ~ 7-9%);
- side fairings (drag reduction ~ 4-6%);
- side-skirt (drag reduction ~ 4-6%)

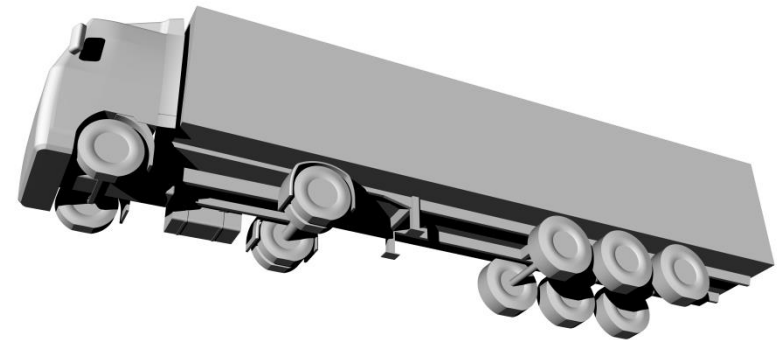
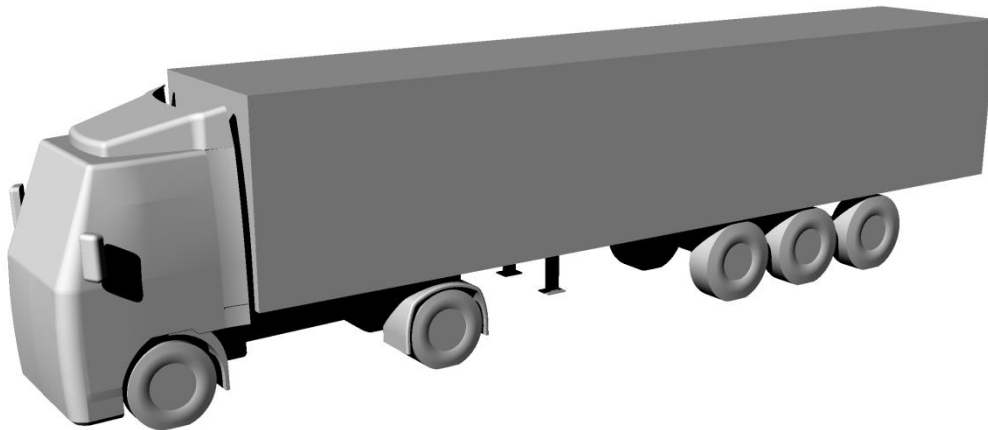
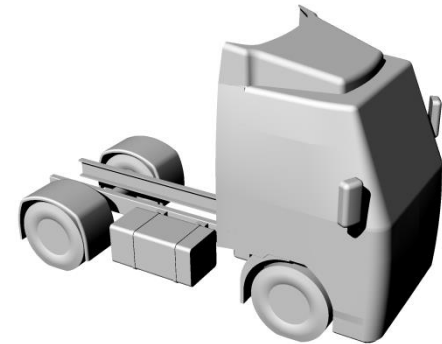
- Boat-tails (drag reduction ~ 8%)
 - Problem with the current European regulation
 - Safety issues



reference: <http://blog.ucsusa.org/semi-tractor-trailer-truck-skirt-359>

Aerodynamics devices installed:

- cab roof fairings;
- side fairings;
- wheel houses for the tractor tires;
- suitable design of the front corner radius of the tractor.



length	width	height
[m]	[m]	[m]
15,8	2,5	3,9

Simulations set-up

7

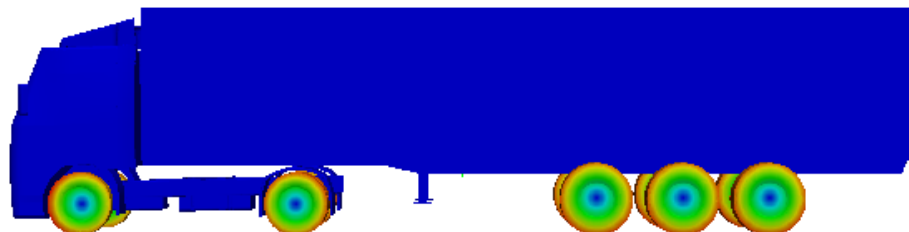
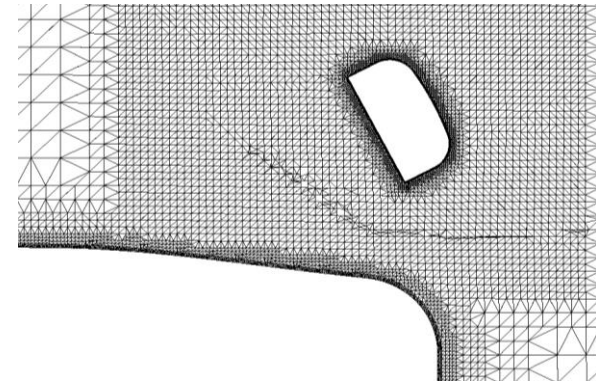
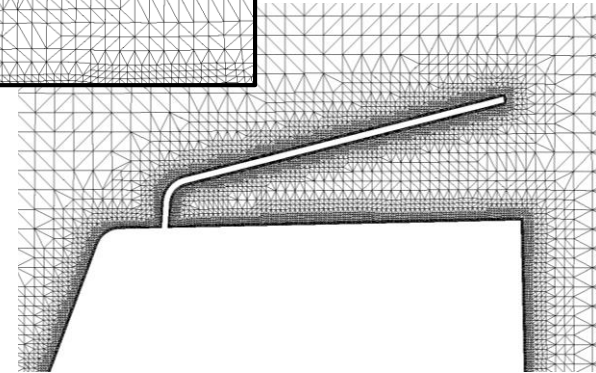
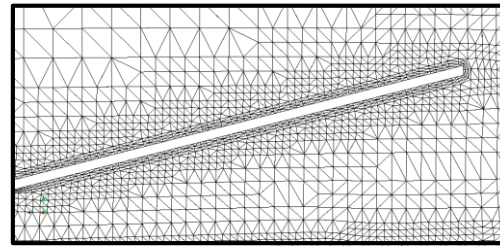
- CFD Solver: OpenFOAM
- Mesh: OpenFOAM - snappyHexMesh
- Speed: 27,7 m/s (≈ 100 km/h)

- RANS simulations:
 - Turbulence model k- ω SST
 - **≈ 10 millions cells**

- DES simulations:
 - Turbulence model S-A
 - Time step= 10^{-4} s
 - **≈ 40 millions cells**

- Approximation of the contact area wheel/ground

- Boundary condition:
 - V=27.7 m/s inlet
 - P=0 Pa outlet
 - V=27.7 m/s ground
 - Slip wall top and lateral
 - Rotating wheels



➤ Computational domain:

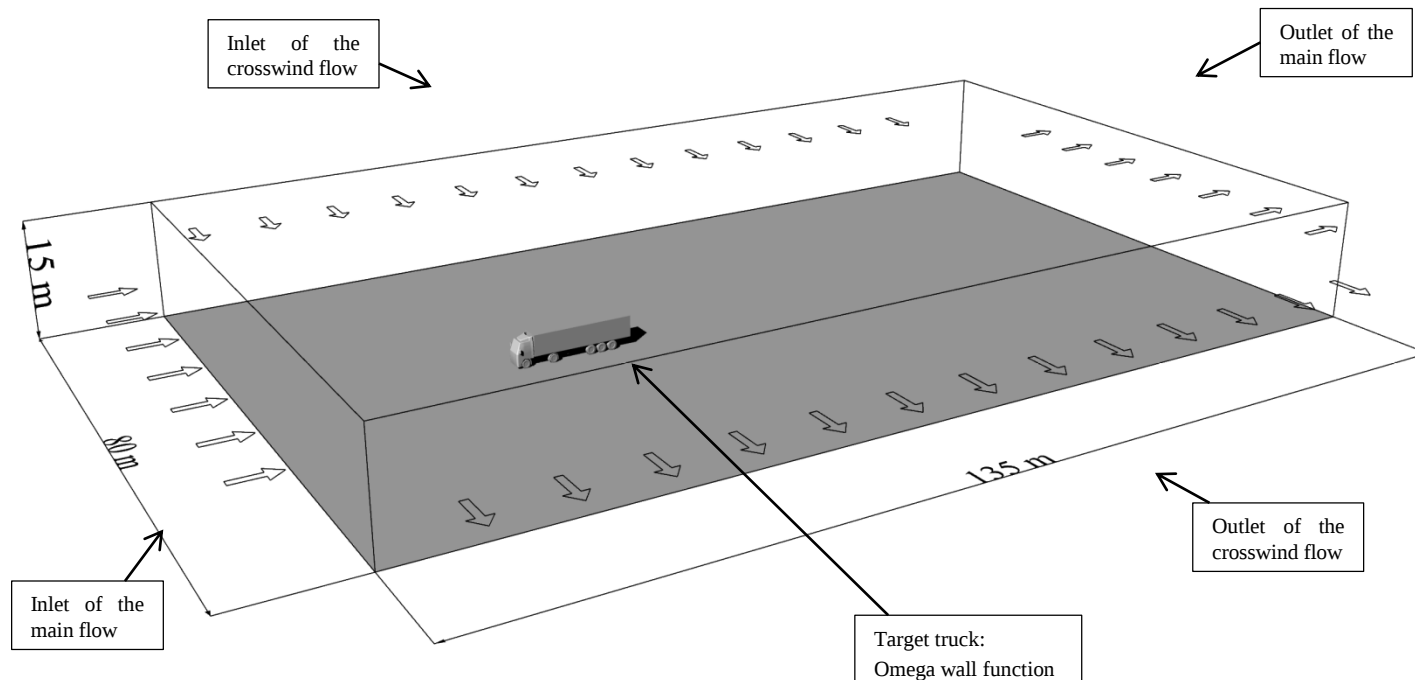
- RANS Simulations

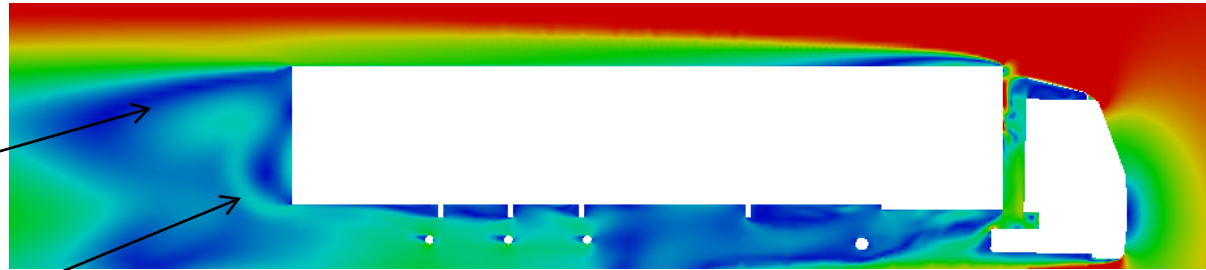
Yaw angle 0° , 5° , 10° , 15° , 20° , 25° , 30°

- DES Simulations

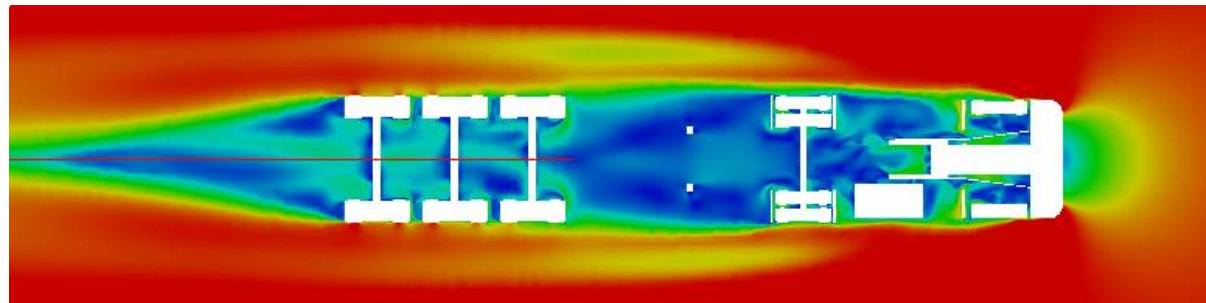
Yaw angle 0° , 5° , 10°

Million of elements	C_d	% C_d
10,8	0,593	
39,7	0,581	2,02
48,5	0,583	1,69





Normalized magnitude velocity contour plot at $y=0$

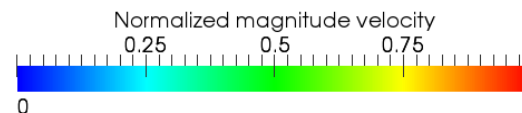


Normalized magnitude velocity contour plot at $z=0.63$



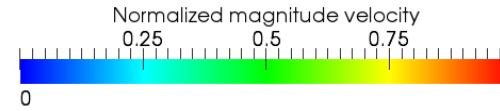
Normalized magnitude velocity contour plot at $z=2.6$

C_d
0,593

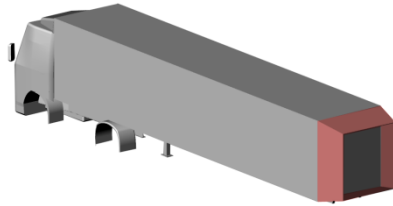


Tested devices

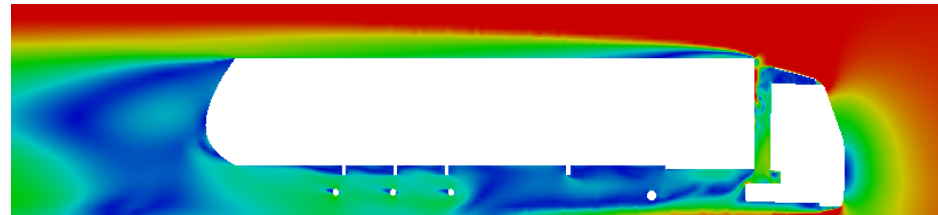
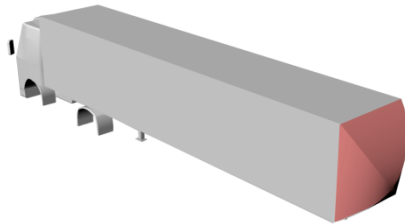
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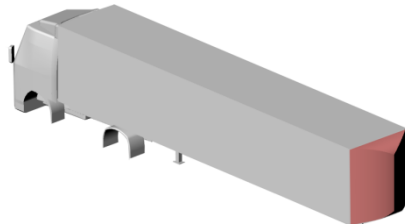
- Boat-tails (drag reduction $\sim 8\%$)



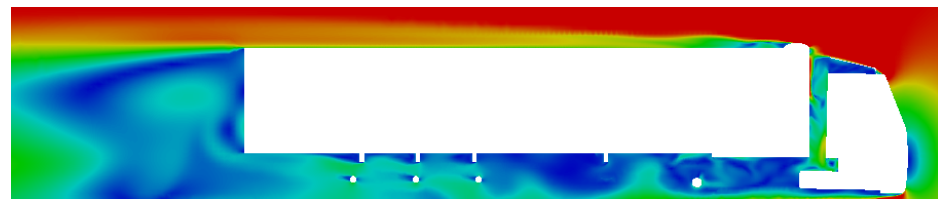
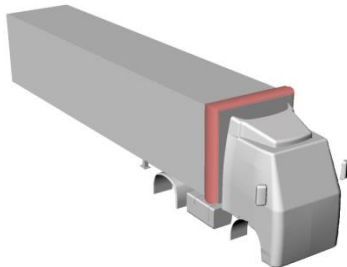
- Airbags (drag reduction $\sim 4\%$);



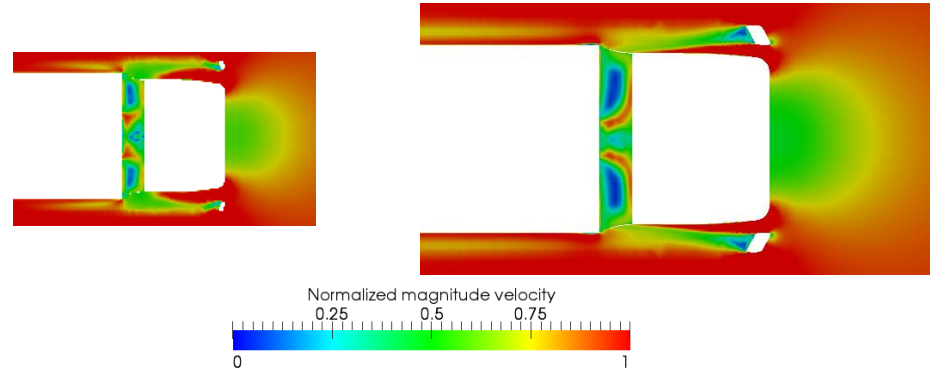
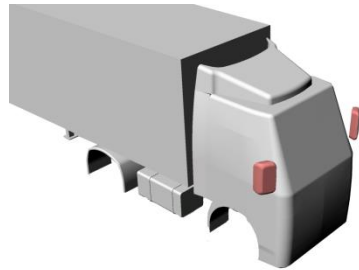
- Fins (drag reduction $\sim 8\%$);



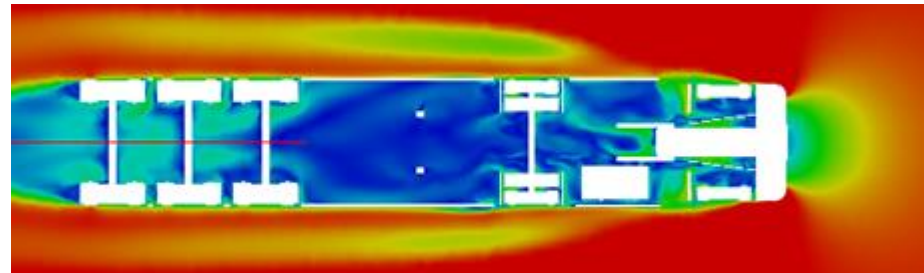
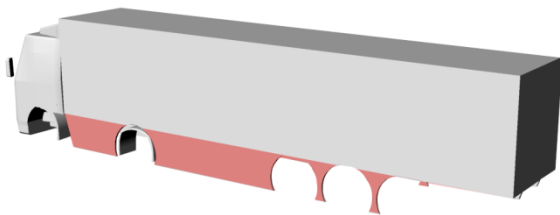
- Trailer devices (drag reduction $\sim 7\%$);



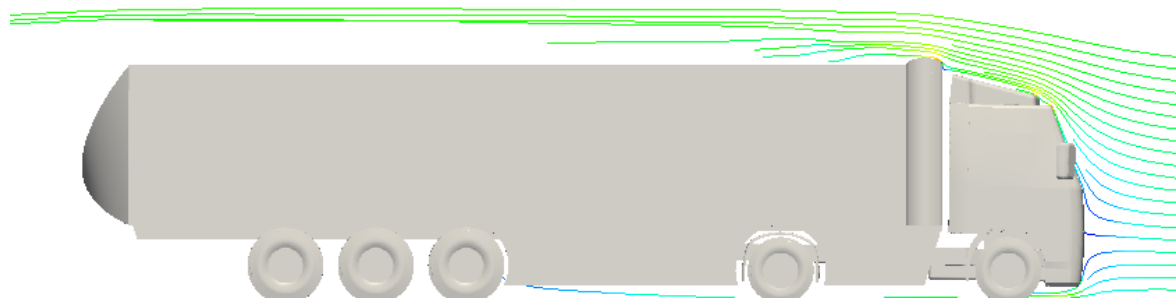
- Side mirrors design (drag reduction ~ 3 %);

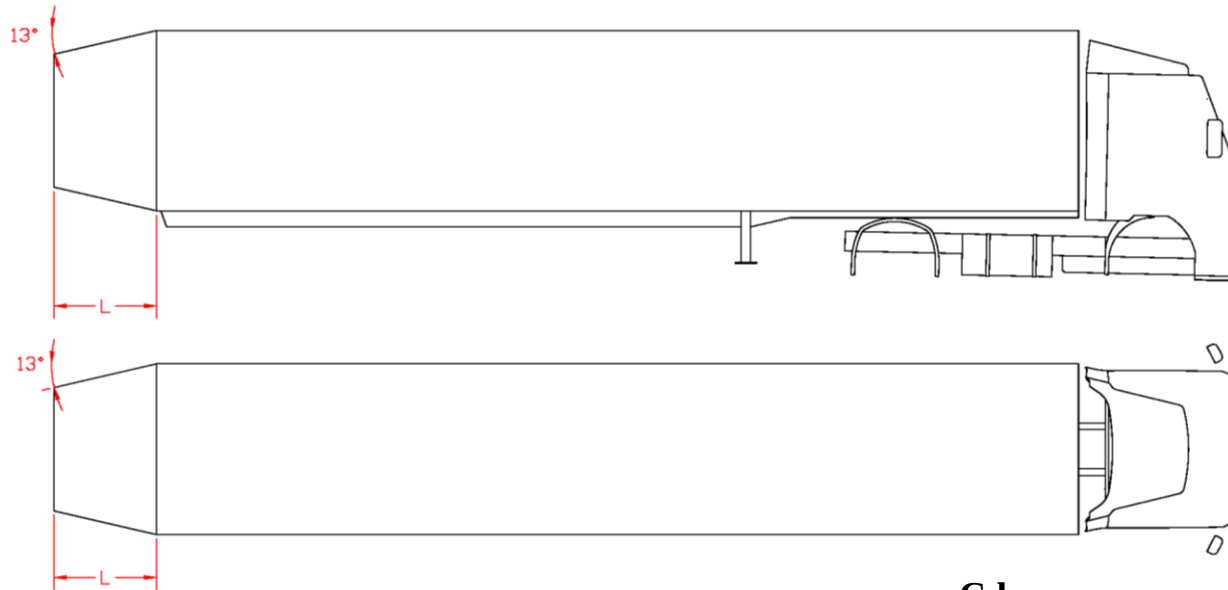


- Side skirt (drag reduction ~ 4 %);

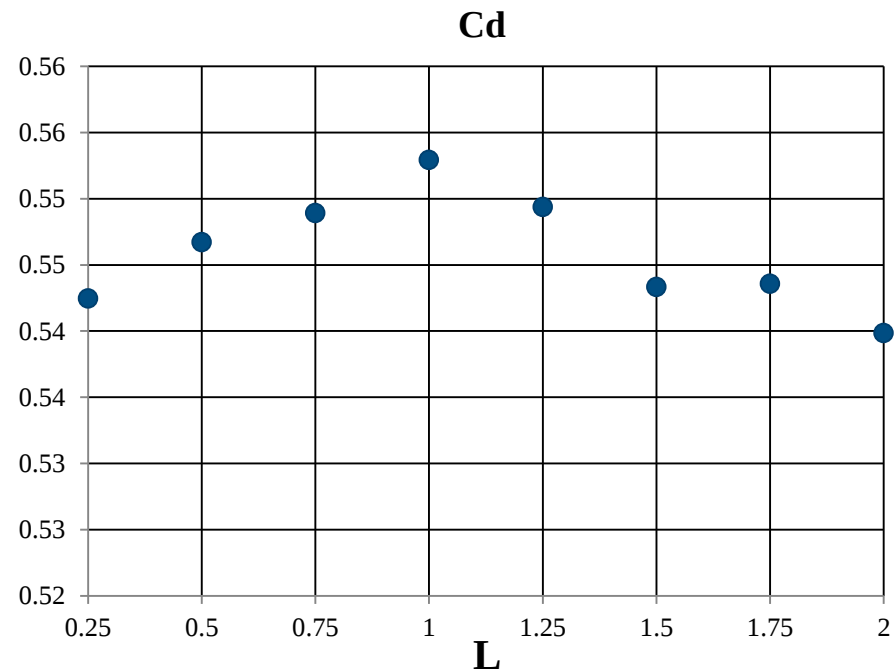


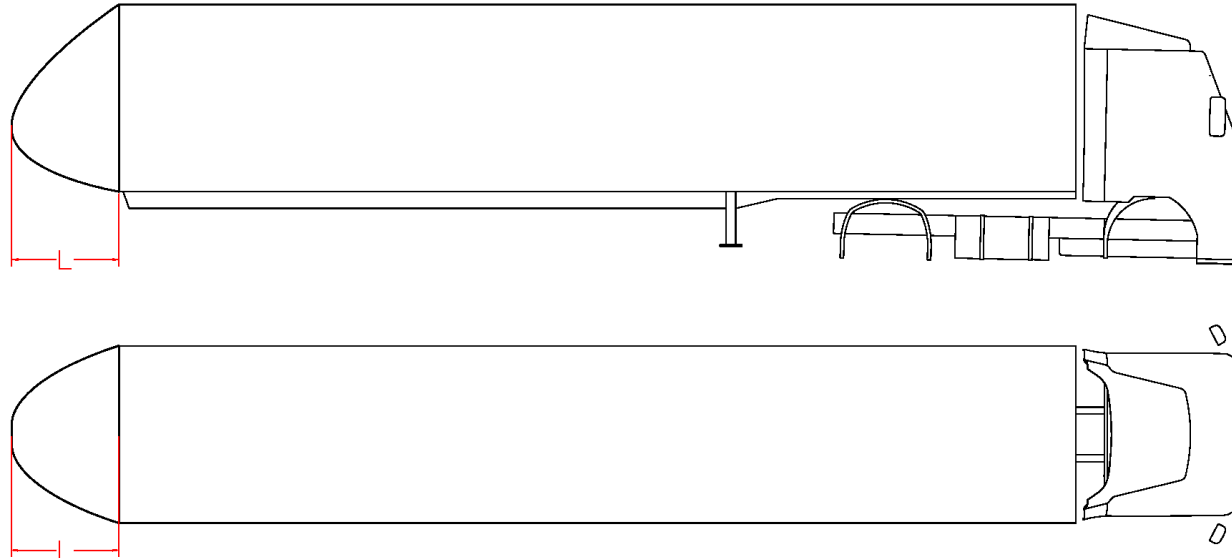
A proper mix of the previous devices installed on the heavy truck decrease the overall drag about 15%.



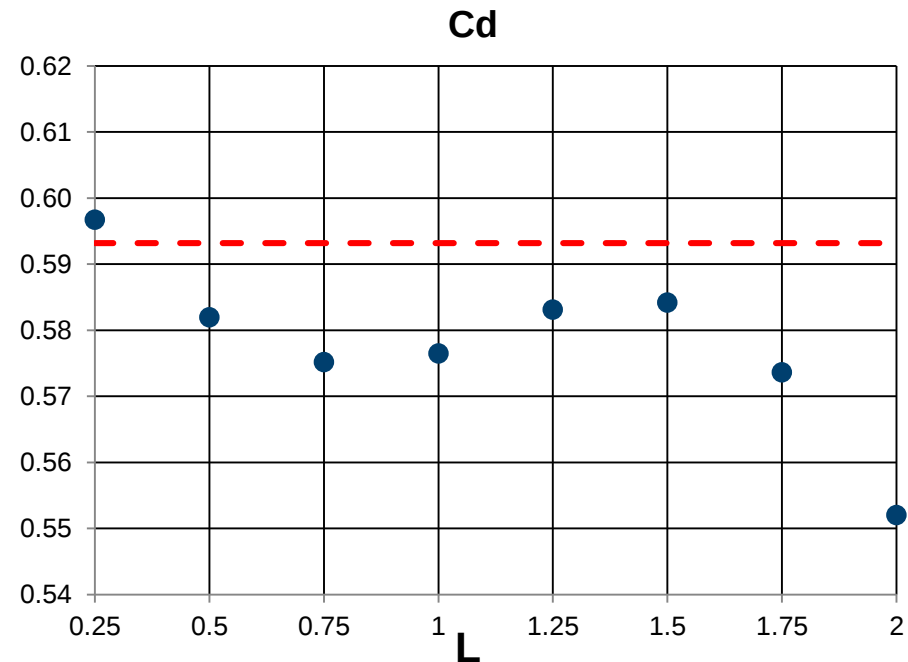


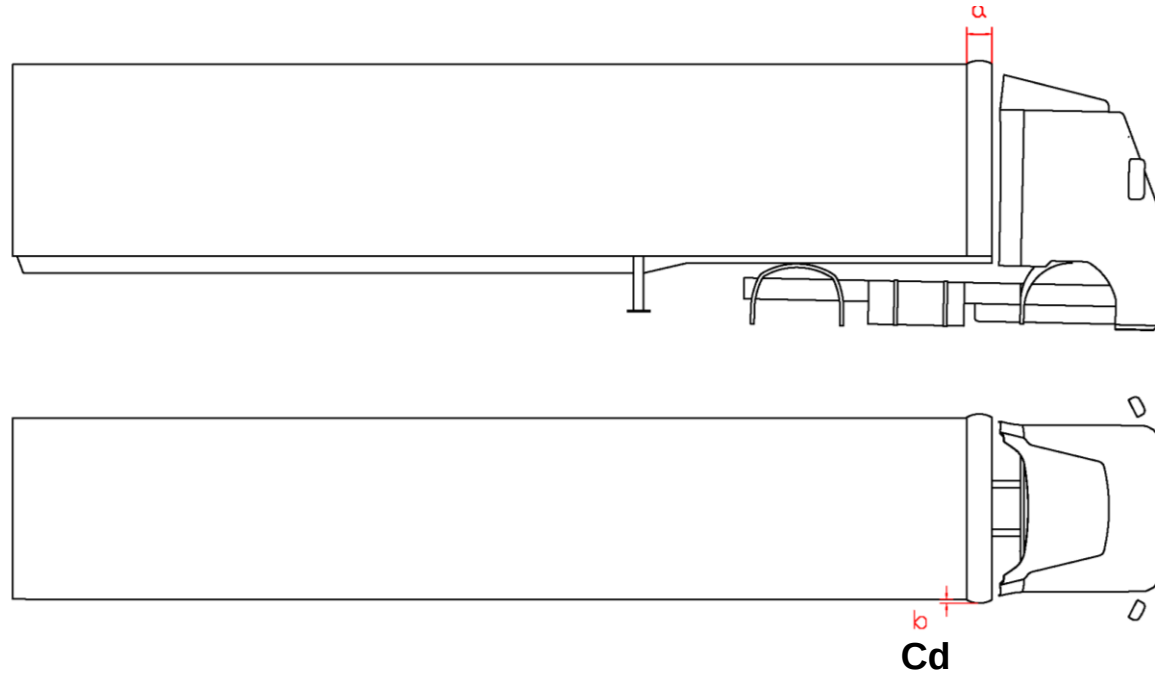
L [m]	C _d	% C _d reduction
0,25	0,54	8,55
0,5	0,55	7,83
0,75	0,55	7,46
1	0,55	6,79
1,25	0,55	7,38
1,5	0,54	8,40
1,75	0,54	8,36
2	0,54	8,99



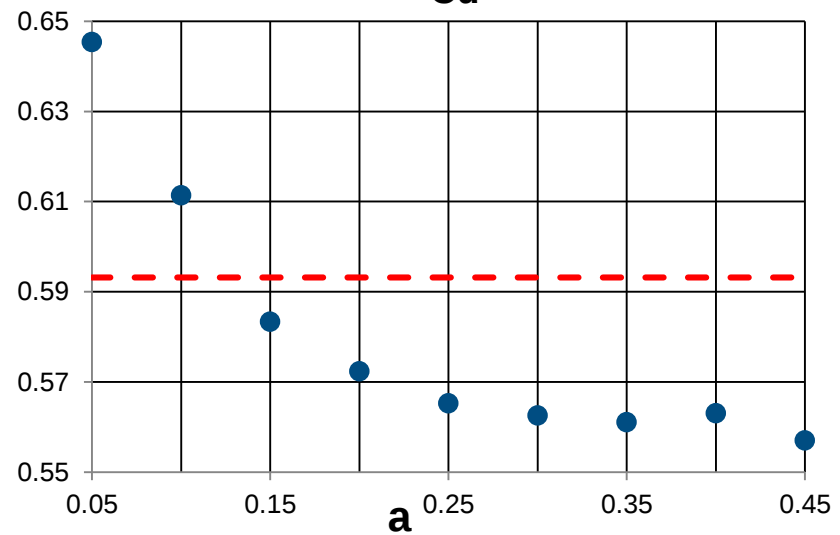


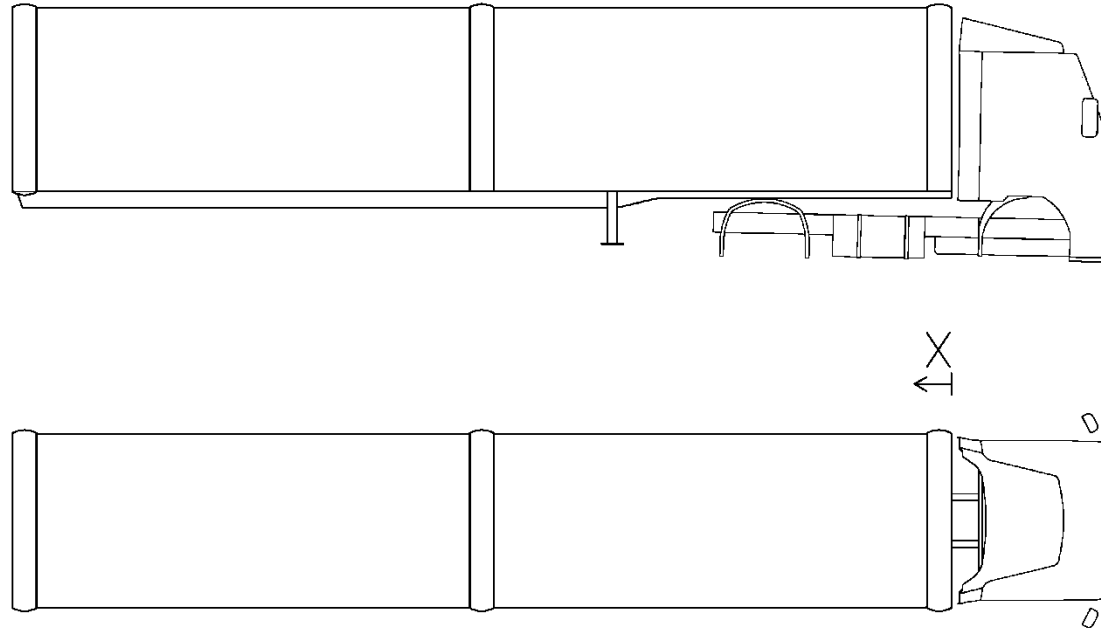
L [m]	C _d	% C _d reduction
0,25	0,60	-0,60
0,5	0,58	1,89
0,75	0,58	3,03
1	0,58	2,81
1,25	0,58	1,69
1,5	0,58	1,51
1,75	0,57	3,29
2	0,55	6,93



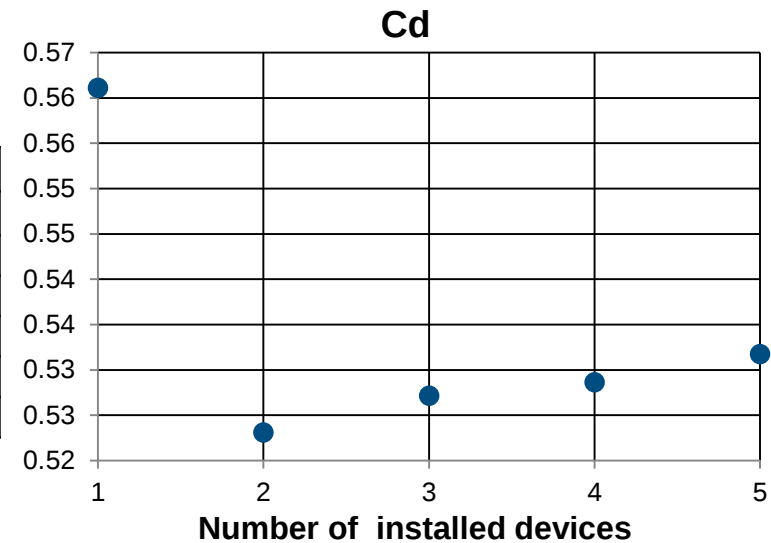


b [m]	fix	
a [m]	C_d	% C_d reduction
0,05	0,65	-8,81
0,1	0,61	-3,08
0,15	0,58	1,64
0,2	0,57	3,50
0,25	0,57	4,69
0,3	0,56	5,15
0,35	0,56	5,41
0,4	0,56	5,07
0,45	0,56	6,09



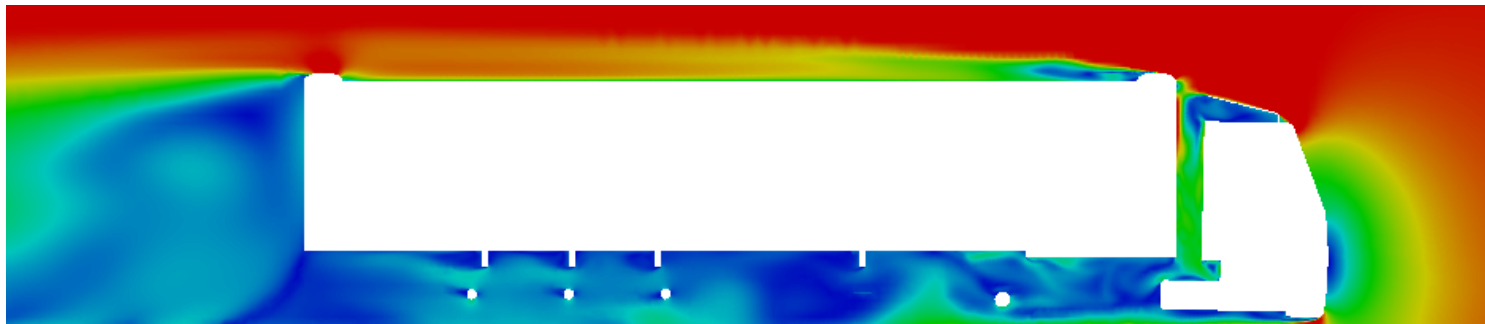
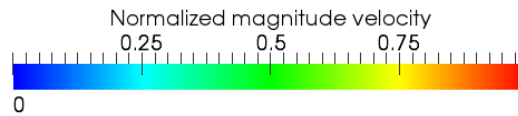
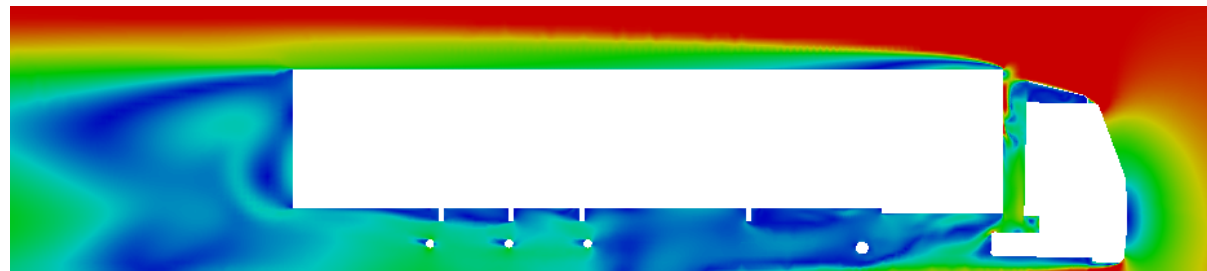


Trailer lenght	13,5	[m]
Number of devices installed	C_d	% C_d reduction
1 ($X=0$)	0,56	5,41
2 ($X=0$; $X=L$)	0,52	11,81
3 ($X=0$; $X=L/2$; $X=L$)	0,53	11,13
4 ($X=0$; $X=L/3$; $X=2/3L$; $X=L$)	0,53	10,88
5 ($X=0$; $X=L/4$; $X=L/2$; $X=3/4L$; $X=L$)	0,53	10,36



2 (X=0; X=L)		
a [m]	C_d	% C_d reduction
0,35	0,52	11,81
0,45	0,518	12,73

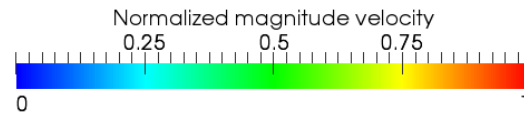
Target vehicle



Normalized magnitude velocity contour plot at y=0

2 (X=0; X=L)		
a [m]	C_d	% C_d reduction
0,35	0,52	11,81
0,45	0,518	12,73

Target vehicle



Normalized magnitude velocity contour plot at $z=2.6$

Front trailer device ($a=0,45$ m)

DRAG

yaw angle	Cd	% Cd rid. tot
0	0.549	6.23%
5	0.653	4.47%
10	0.812	2.80%
15	0.975	2.51%
20	0.990	4.86%
25	0.998	1.82%
30	1.033	1.09%

Front-rear trailer device ($a=0,45$ m)

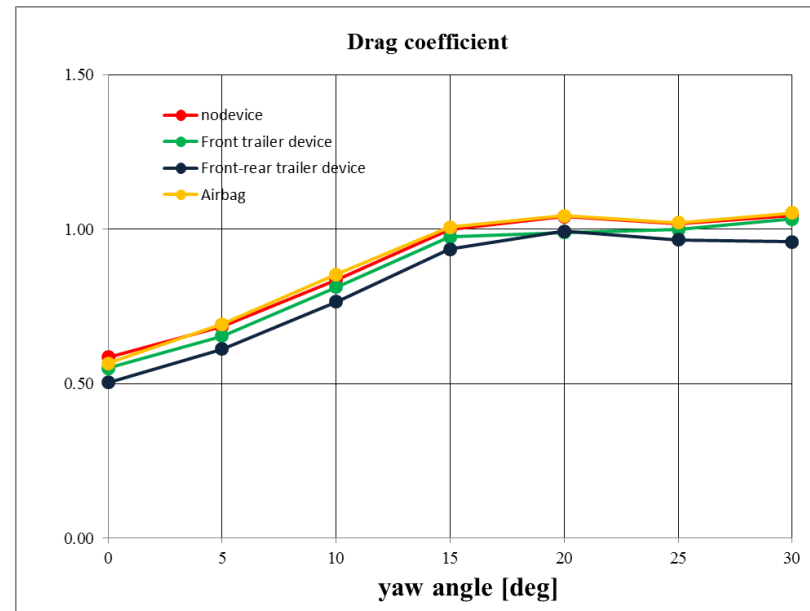
DRAG

yaw angle	Cd	% Cd rid. tot
0	0.503	14.08%
5	0.612	10.52%
10	0.765	8.45%
15	0.935	6.51%
20	0.993	4.52%
25	0.965	5.05%
30	0.959	8.12%

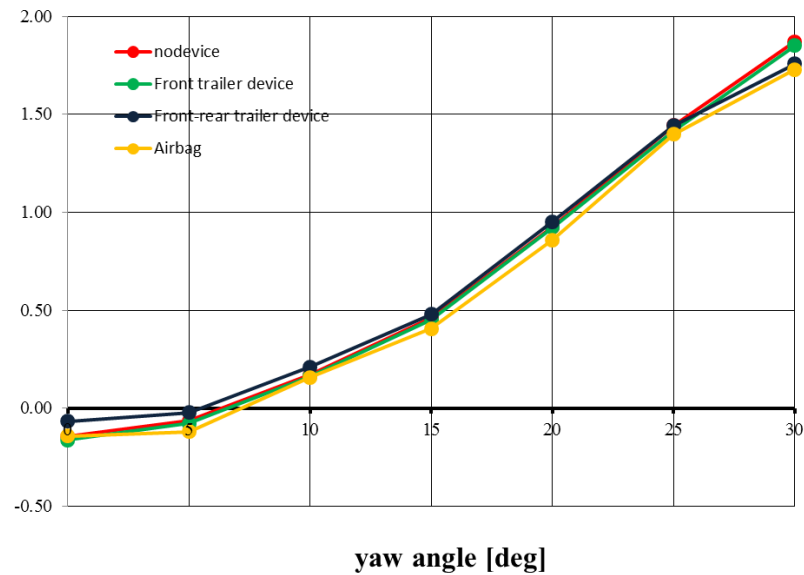
Airbag ($L=0,75$ m)

DRAG

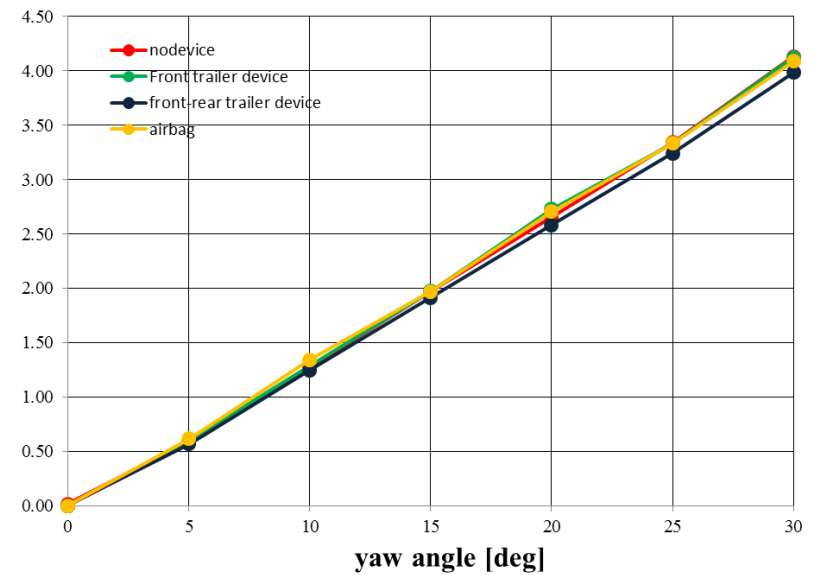
yaw angle	Cd	% Cd rid. tot
0	0.566	3.39%
5	0.693	-1.26%
10	0.853	-2.04%
15	1.007	-0.67%
20	1.043	-0.27%
25	1.021	-0.47%
30	1.052	-0.80%



Lift coefficient



Side coefficient



Target vehicle

DRAG

yaw angle	C_d RANS	C_d DES
0	0,581	0,623
5	0,661	0,679
10	0,824	0,813

SIDE FORCE

yaw angle	C_s RANS	C_s DES
0	0,000	0,000
5	0,594	0,616
10	1,307	1,379

LIFT

yaw angle	C_l RANS	C_l DES
0	-0,155	-0,105
5	-0,058	-0,048
10	0,188	0,183

Front-rear trailer device

DRAG

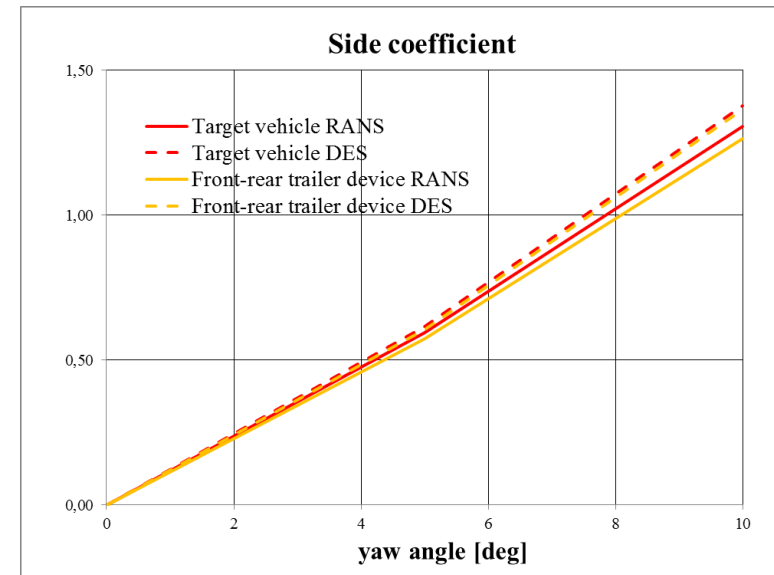
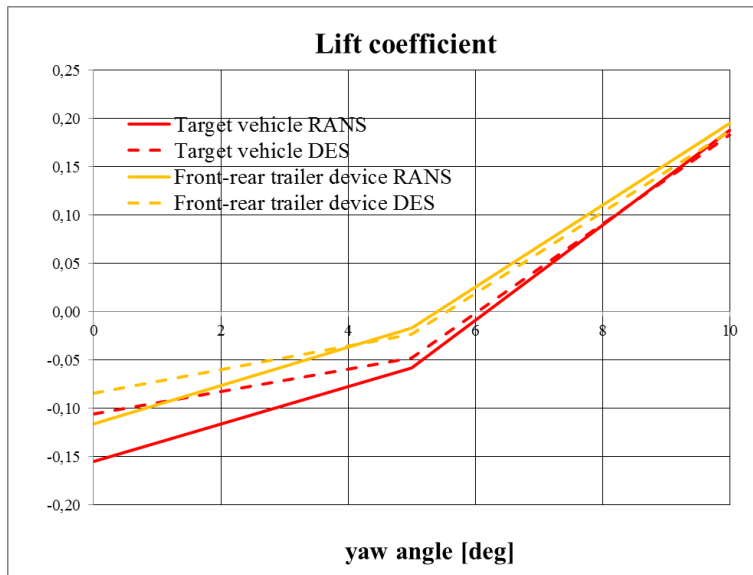
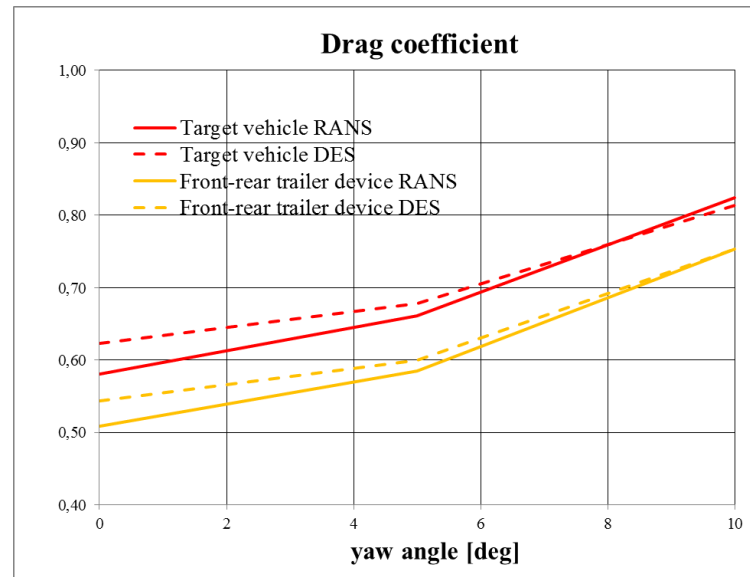
yaw angle	C_d RANS	% C_d reduction RANS	C_d DES	% C_d reduction DES
0	0,508	12,506%	0,544	12,702%
5	0,585	11,504%	0,600	11,610%
10	0,753	8,606%	0,753	7,454%

SIDE FORCE

yaw angle	C_s RANS	% C_s reduction RANS	C_s DES	% C_s reduction DES
0	0,000	0,000%	0,000	0,000%
5	0,572	3,716%	0,606	1,603%
10	1,265	3,202%	1,364	1,066%

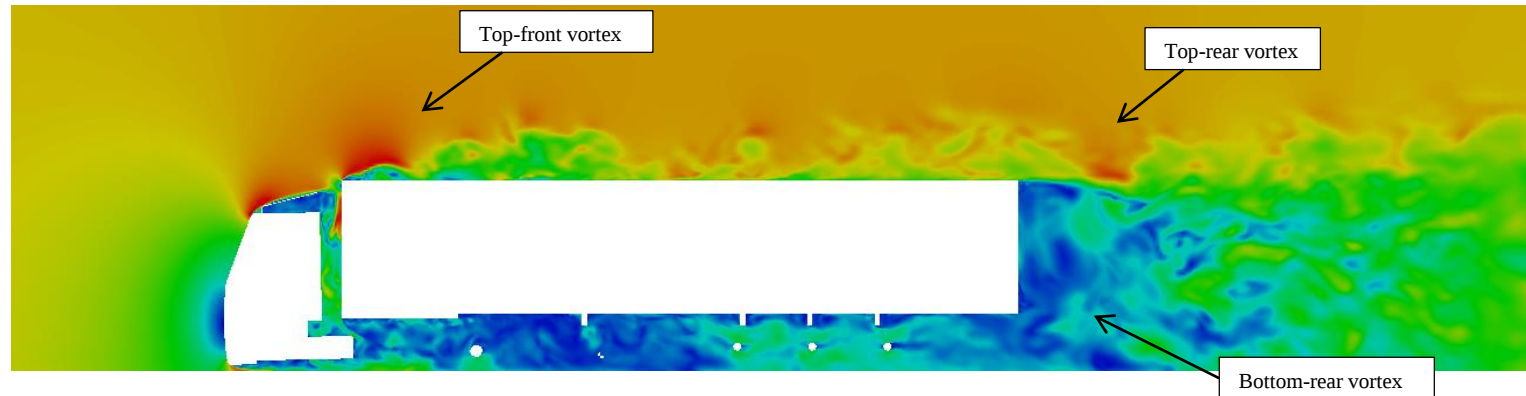
LIFT

yaw angle	C_l RANS	% C_l reduction RANS	C_l DES	% C_l reduction DES
0	-0,116	-8,473%	-0,085	19,628%
5	-0,017	70,650%	-0,023	51,738%
10	0,196	-3,777%	0,187	-2,118%

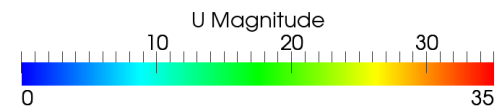
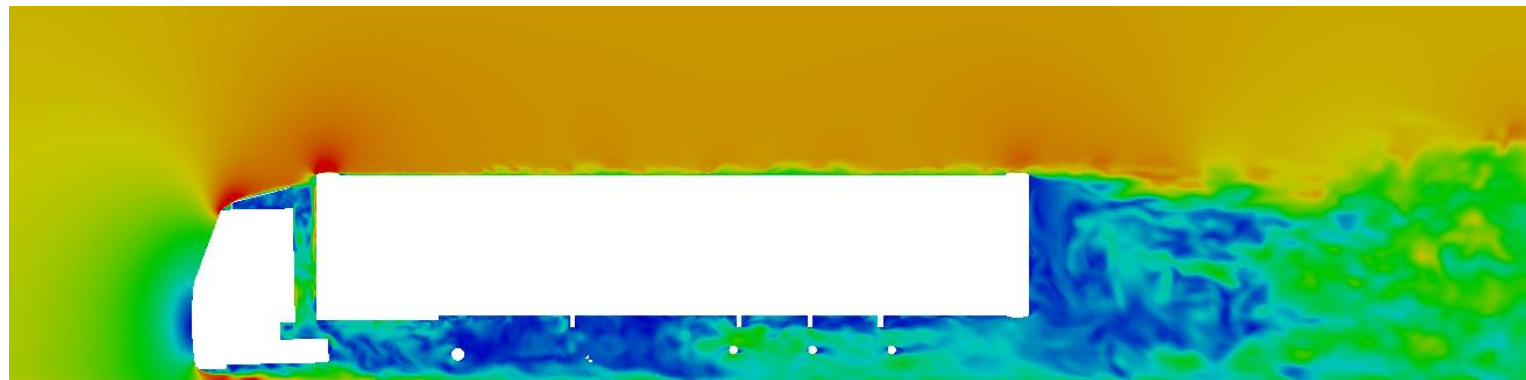


Contourplot $y=0$ m

No device



Front-rear trailer device

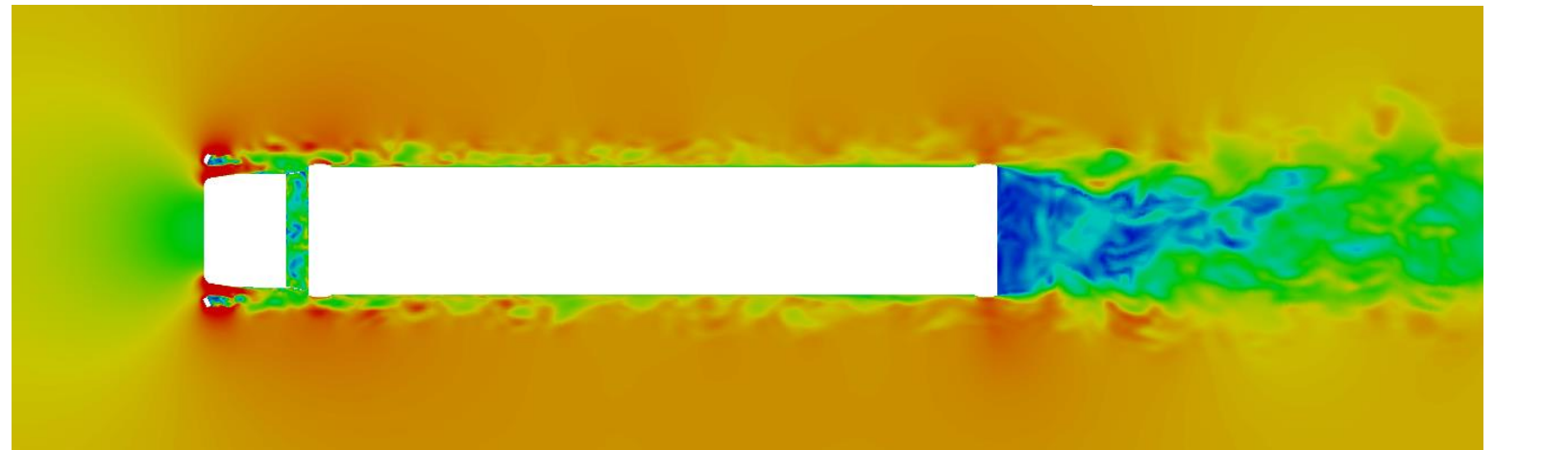


Contourplot $z=2,6$ m

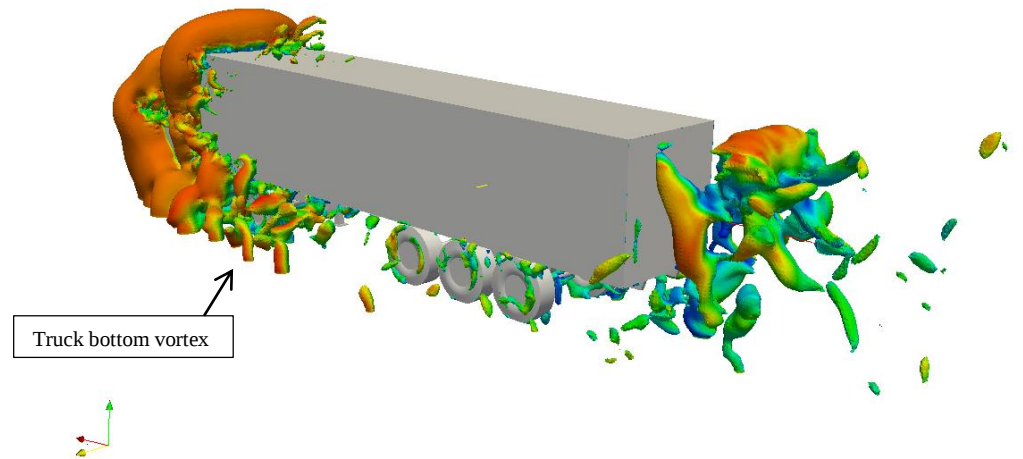
No device



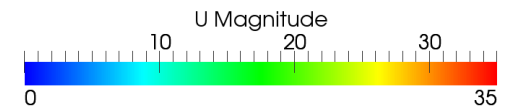
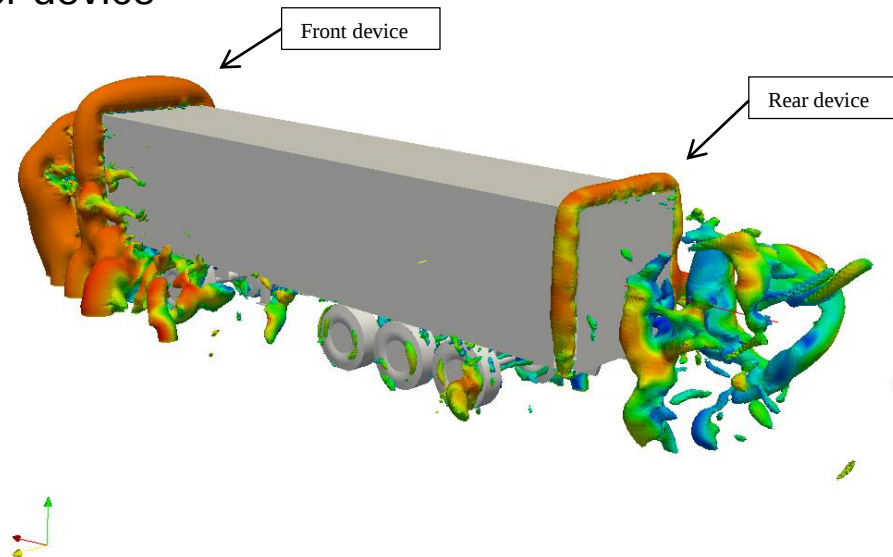
Front-rear trailer device



Isovorticity:
No device



Front-rear trailer device



Contourplot $z=2,6$ m

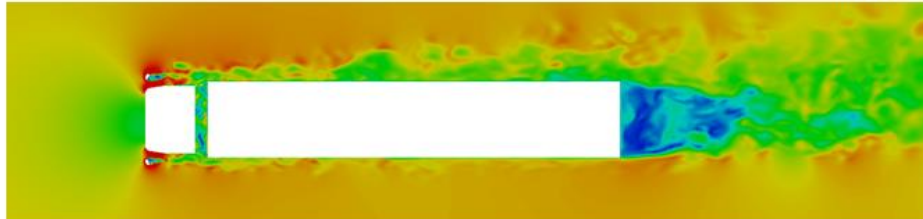
Target vehicle



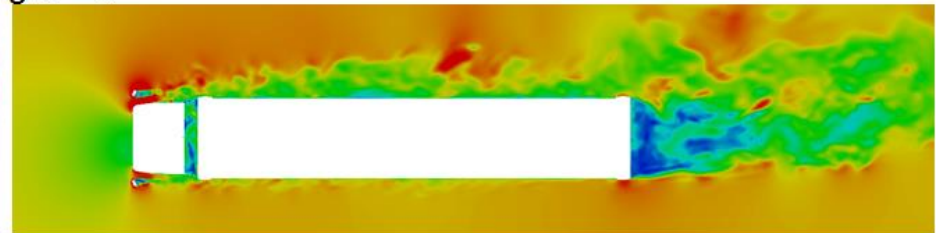
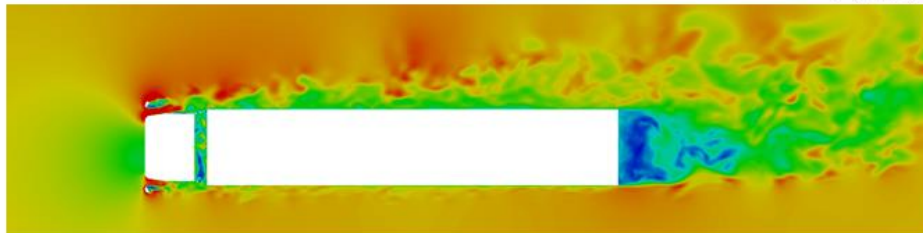
Front-rear trailer device



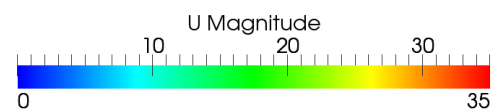
Yaw angle = 0°



Yaw angle = 5°

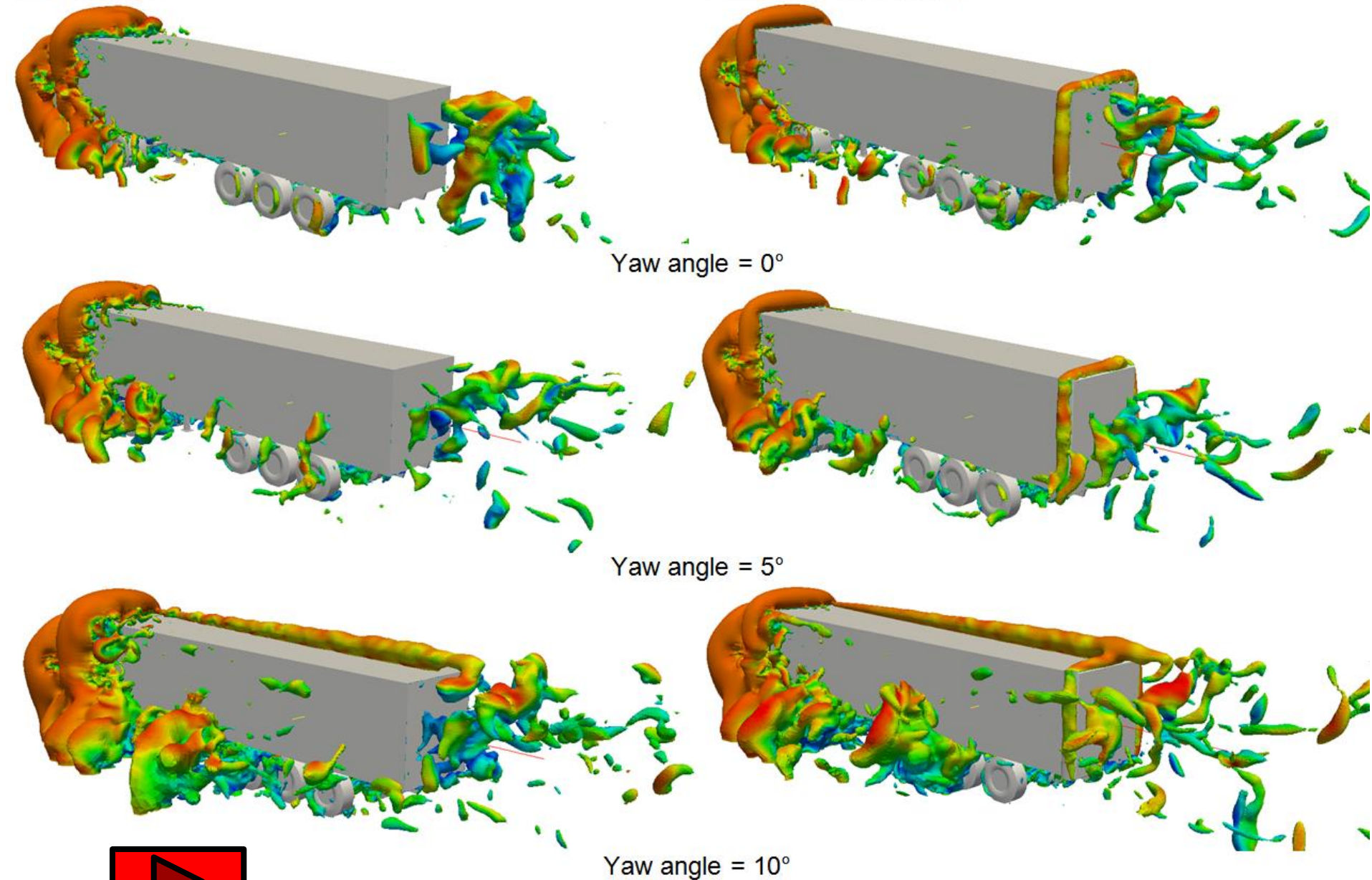


Yaw angle = 10°



Target vehicle

Front-rear trailer device



Advantages:

- 15% of drag reduction (around 5 % less in fuel consumption);
- No change in the current shape of the truck and trailer;
- No impact to the logistic center and to the shipping system (easy install/uninstall on the truck);
- Low development costs;
- These device can be mounted on every truck (next, current, previous truck generation);
- No safety issue.



THANK YOU FOR YOUR ATTENTION

Paolo Schito – Luigi Salati – Federico Cheli

We acknowledge the CINECA and the Regione Lombardia award under the LISA initiative, for the availability of high performance computing resources and support for Project D4TRUCKS

Italian patent application n. MI2014A002044, entitled “DISPOSITIVO AERODINAMICO PER LA RIDUZIONE DEL DRAG DI VEICOLI TERRESTRI” filed on November 27, 2014

Third Symposium on OpenFOAM® in Wind Energy



Politecnico di Milano

June 15, 2015 – June 17, 2015

MAJOR TOPICS

- + Atmospheric Flows (including flow over complex terrains and sea)
- + HAWT Wind Turbine Aerodynamics and Wakes
- + Vertical Axis Wind turbines
- + Small scale and urban wind energy applications
- + Site Assessment and Wind Plant Aerodynamics
- + Offshore Wind Aerodynamics and Hydrodynamics
- + Other (including meshing, algorithms, post-processing, parallel performance, etc.)



<https://www.eko.polimi.it/index.php/sowe2015/SOWE2015>