

Cloud-based Simulation of Aerodynamics of Light Aircraft

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Nejc Bat

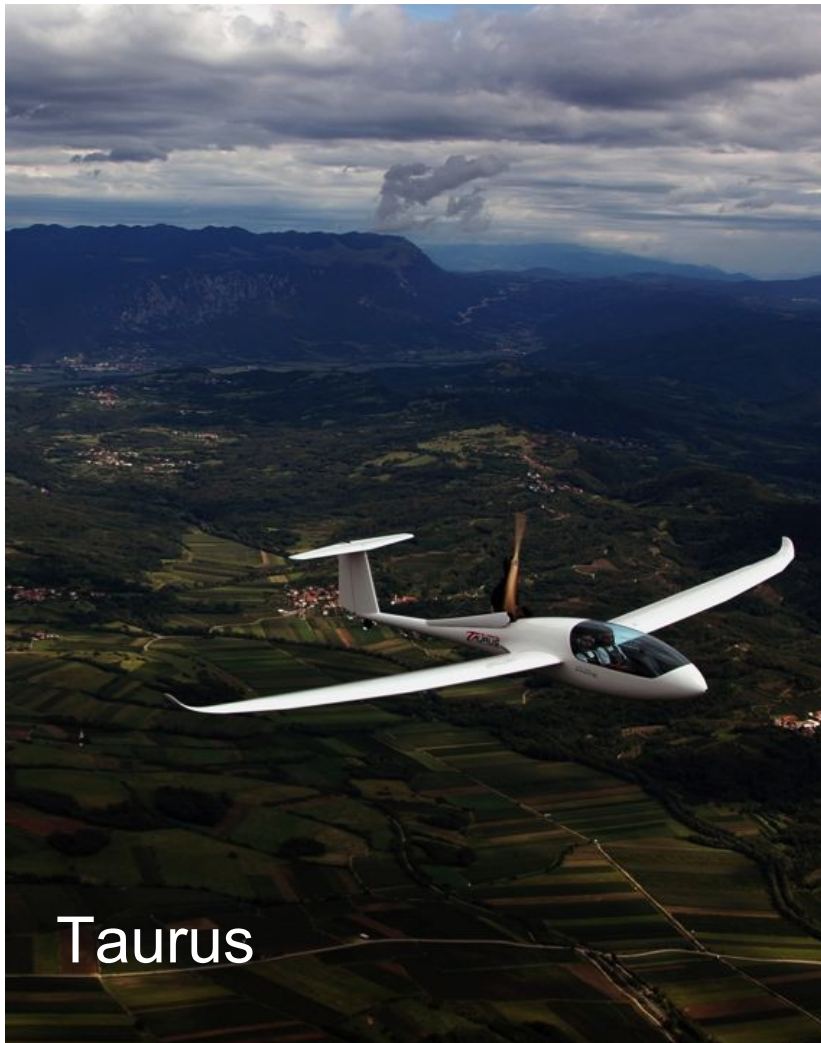
Arctur d.o.o., Slovenia

Milan, 17th June

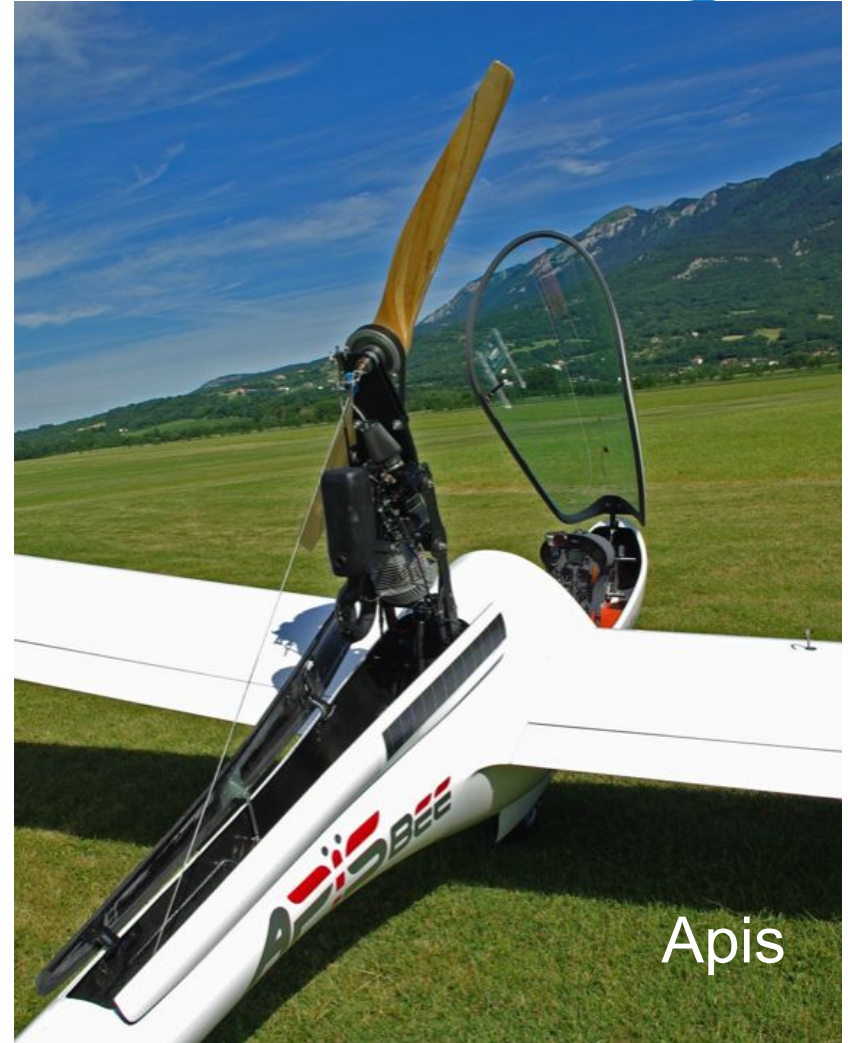
Workshop HPC Methods for
Engineering



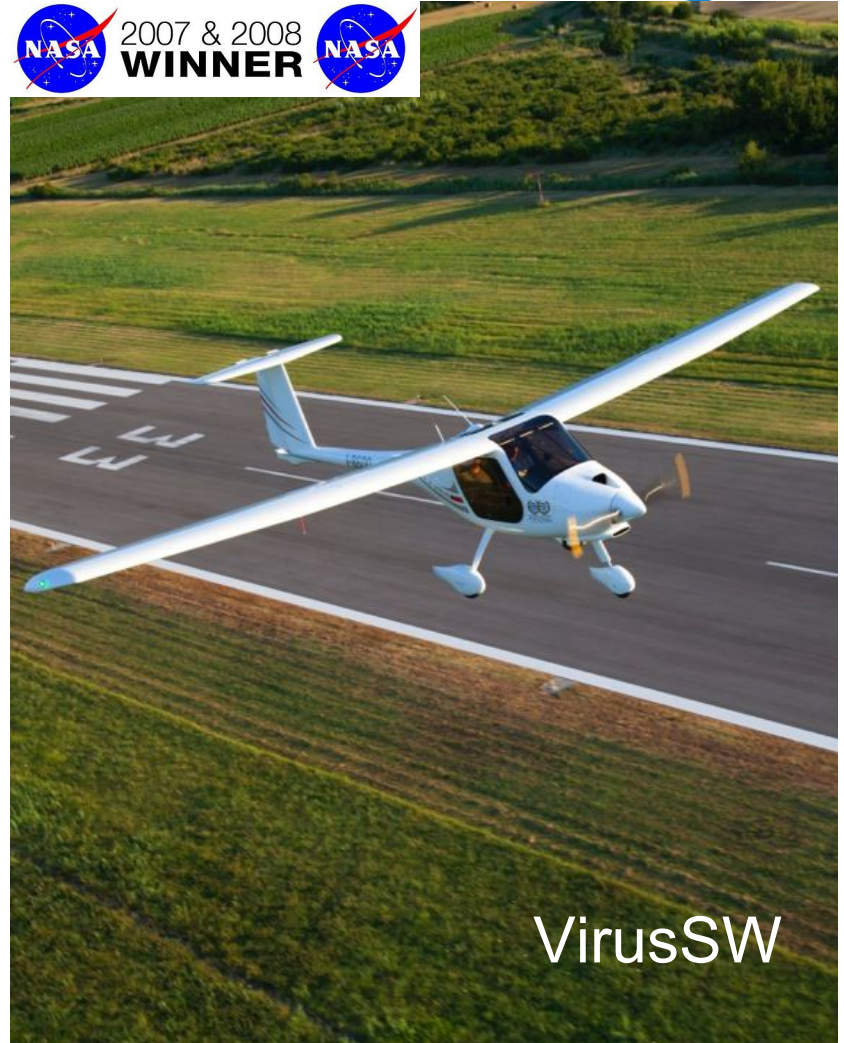
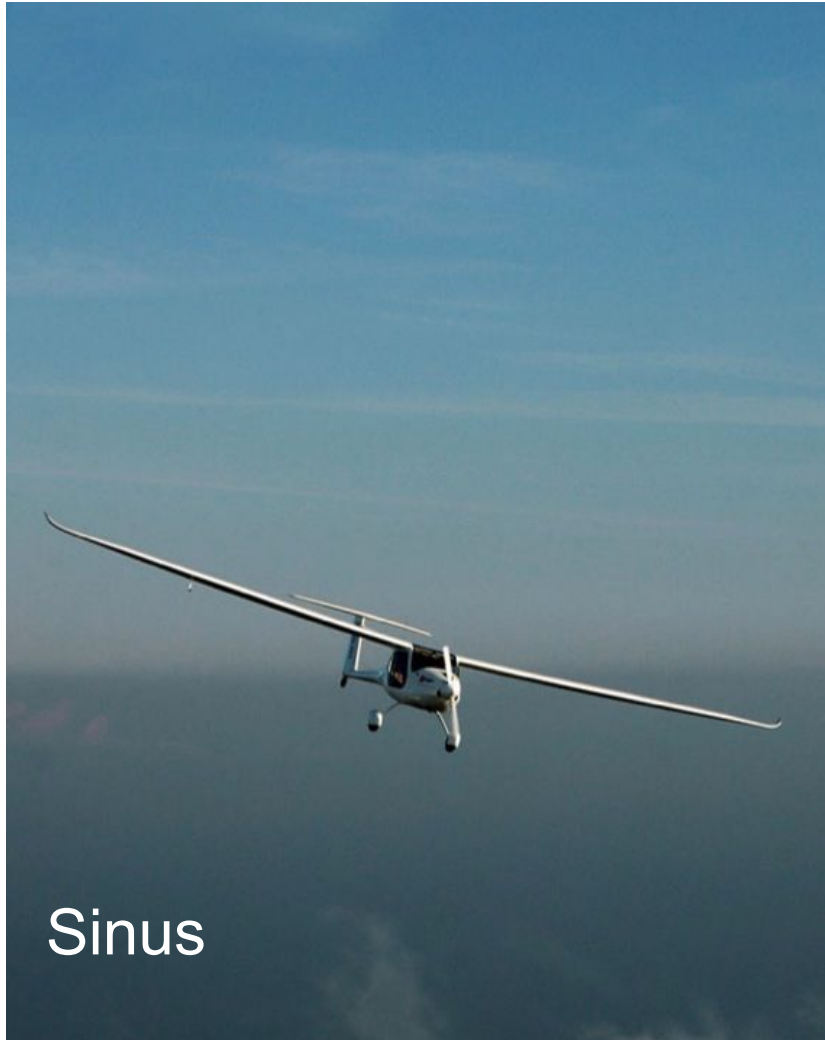
- Pipistrel
- Fortissimo
- Motivation
- Experiment
- Simulation
- Mesh
- Results
- Lessons learned, Successes and Impact



Taurus



Apis





Taurus Electro



Alpha Electro



Taurus G4



Panthera



- Fortissimo



- rbf4aero



- Mikelangelo



- Hypstair



I4MS ICT Innovation for Manufacturing SMEs (within Factories of the Future initiative)



- Fortissimo



FORTISSIMO

- Experiment:

Cloud-based simulation of aerodynamics
of light aircraft

- Partners:

End User: PIPISTREL
HPC Expert: XLAB
HPC Provider: ARCTUR

- Application:

OpenFOAM

- Pipistrel cluster (2014): 2 x (8 cores, 66GB RAM)
- Typical simulations:
 - fully turbulent RANS simulations
 - low-Re airfoil simulations
 - 5M (15M max) cells mesh
- Arctur's HPC (2014):
 - 84 x (12 cores, 32GB RAM)
 - high performance node: 144GB RAM
 - visualization node: 66GB RAM



- Experiment:
 - OpenFOAM 2.2.0
 - laminar-turbulent transition modeling
with RANS simulations: $k - k_L$ - *omega* turbulence model
 - complete Panthera aircraft at cruise speed ($Re=5.7e6$)
- Validation and performance criteria
 - successful scale up from local cluster to HPC
 - working remote visualization directly on HPC (TurboVNC)
 - this routine runs smoothly and completely remote on HPC
 - the same convergence time for much larger cases

Course of action:

- Simple test cases with turbulent model $k - k_L - \omega$
- A wing at smaller velocities
- A wing at cruise velocity
- Complete Panthera aircraft at smaller velocities
- Complete Panthera aircraft at cruise speed

	<u>In house cluster</u>	<u>Arctur's HPC</u>
mesh size	5 -10M cells	115M cells
thinnest layer	~ 0.1mm	~ 0.006mm
No. cores	8	60 - mesh 180 - simul.
simulation time	1-2 days	2-3 days

$k - k_L - \omega$ turbulence model ¹

- low-Re model
- Three additional transport equations:
 - k - turbulent kinetic energy
 - k_L - laminar kinetic energy = pretransitional (nonturbulent) velocity fluctuations
 - ω - specific dissipation rate
- RASProperties:
RASModel kkLOmega;

¹Walters, D. K., and Cokljat, D., "A Three-Equation Eddy-Viscosity Model for Reynolds-Averaged Navier-Stokes Simulations of Transitional Flow," *J. Fluids Eng.*, Vol. 130, Iss. 12, 2008, pp. 1-14, doi:10.1115/1.2979230

```
kl
{
  inlet
  {
    type      fixedValue;
    value     uniform 0;
  }
  outlet
  {
    type      zeroGradient;
  }
  symmetry
  {
    type      symmetryPlane;
  }
  body_patch0
  {
    type      fixedValue;
    value     uniform 0;
  }
}

kt
{
  inlet
  {
    type      fixedValue;
    value     uniform 1.5e-8;
  }
  outlet
  {
    type      zeroGradient;
  }
  symmetry
  {
    type      symmetryPlane;
  }
  body_patch0
  {
    type      fixedValue;
    value     uniform 0;
  }
}

omega
{
  inlet
  {
    type      fixedValue;
    value     uniform 0.771;
  }
  outlet
  {
    type      zeroGradient;
  }
  symmetry
  {
    type      symmetryPlane;
  }
  body_patch0
  {
    type      zeroGradient;
  }
}
```

```
U
{
  inlet
  {
    type      fixedValue;
    value     uniform (1 0 0);
  }
  outlet
  {
    type      zeroGradient;
  }
  symmetry
  {
    type      symmetryPlane;
  }
  body_patch0
  {
    type      fixedValue;
    value     uniform (0 0 0);
  }
}
```

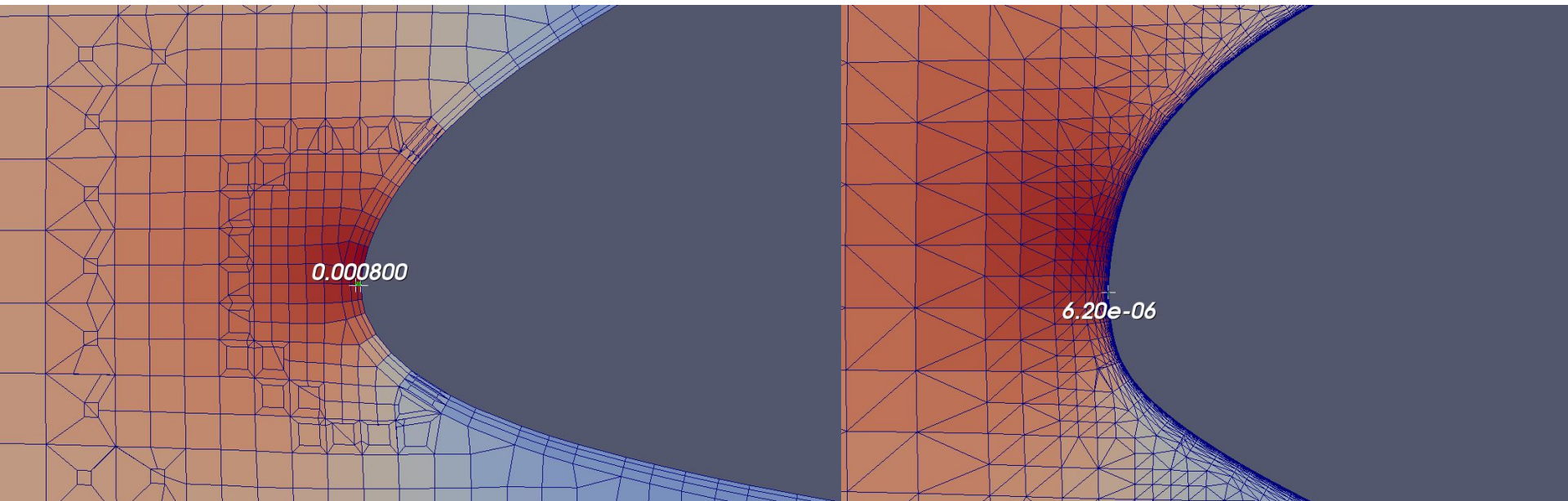
```
p
{
  inlet
  {
    type      zeroGradient;
  }
  outlet
  {
    type      fixedValue;
    value     uniform 0;
  }
  symmetry
  {
    type      symmetryPlane;
  }
  body_patch0
  {
    type      zeroGradient;
  }
}
```

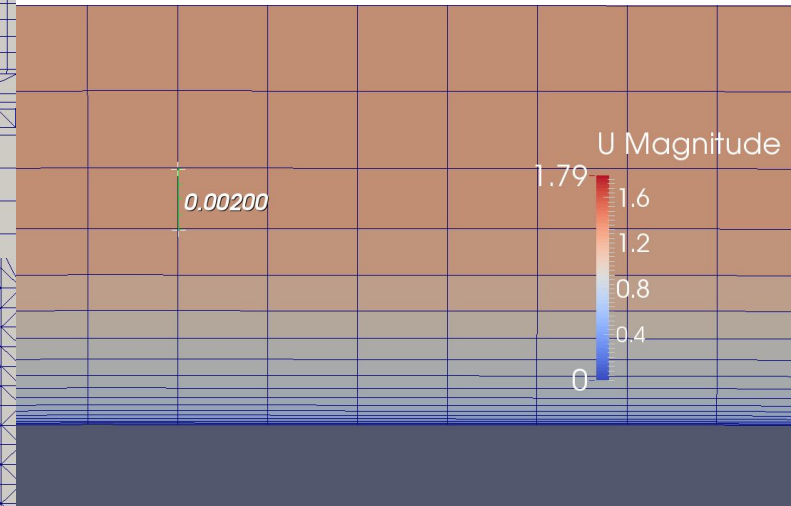
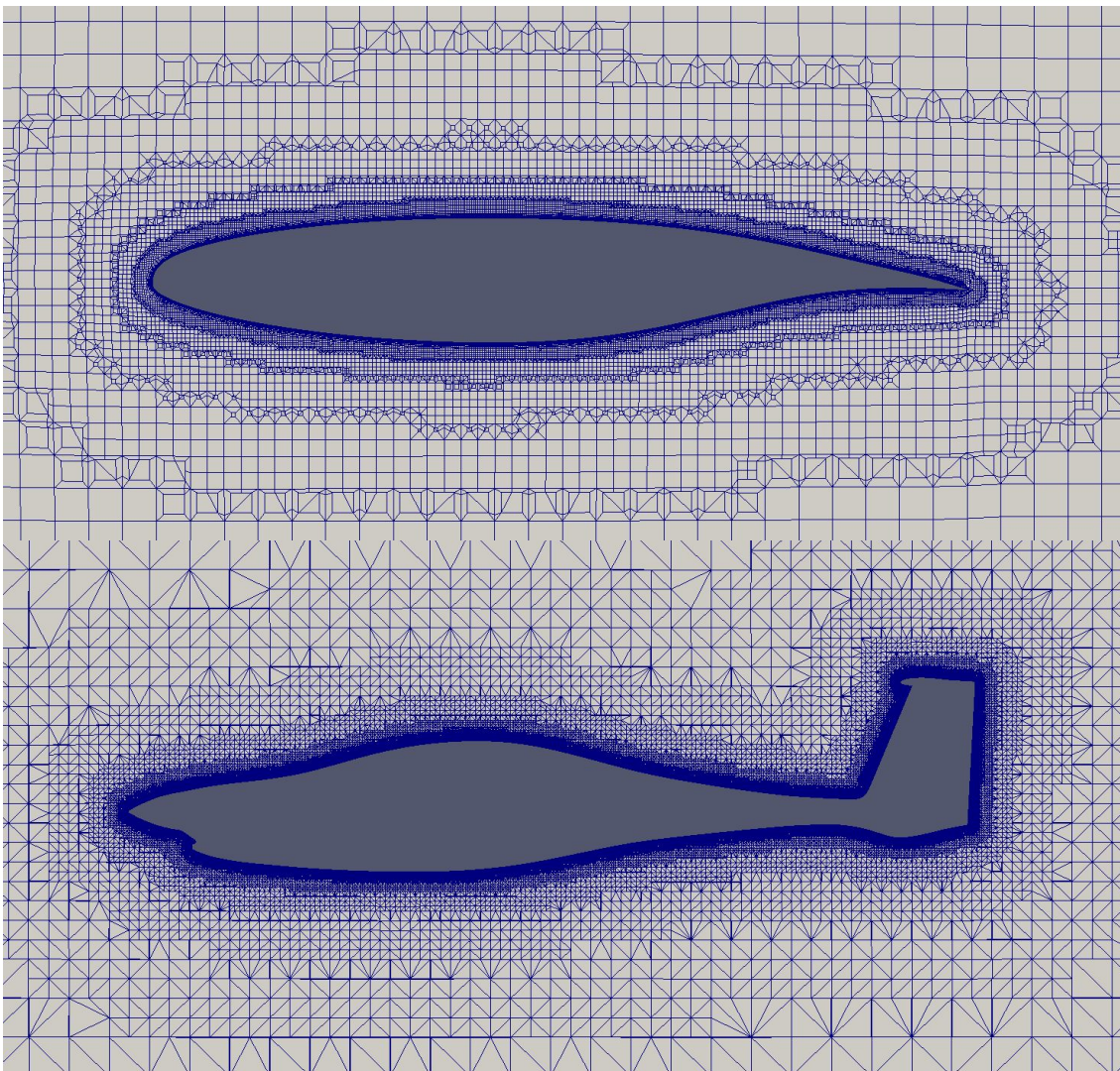

fvSchemes

```
ddtSchemes
{
  default    steadyState;
}
gradSchemes
{
  default    Gauss linear;
}
divSchemes
{
  div(phi,U)          Gauss linearUpwind grad(U);
  div(phi,kt)         Gauss linearUpwind grad(turb);
  div(phi,kl)         Gauss linearUpwind grad(turb);
  div(phi,omega)      Gauss upwind;
  div((nuEff*dev(grad(U).T()))) Gauss linear;
  div((nuEff*dev(T(grad(U)))) Gauss linear;
}
laplacianSchemes
{
  default          none;
}
interpolationSchemes
{
  default    linear;
}
```

fvSolution

```
solvers
{
  p
  {
    solver    GAMG;
  }
  ("U,kl,kt,omega")
  {
    solver    smoothSolver;
  }
}
SIMPLE
{
  nNonOrthogonalCorrectors 1;
}
relaxationFactors
{
  p          0.5;
  U          0.2;
  nuTilda    0.3;
  kt         0.5;
  kl         0.5;
  omega      0.5;
}
```





snappyHexMeshDict:

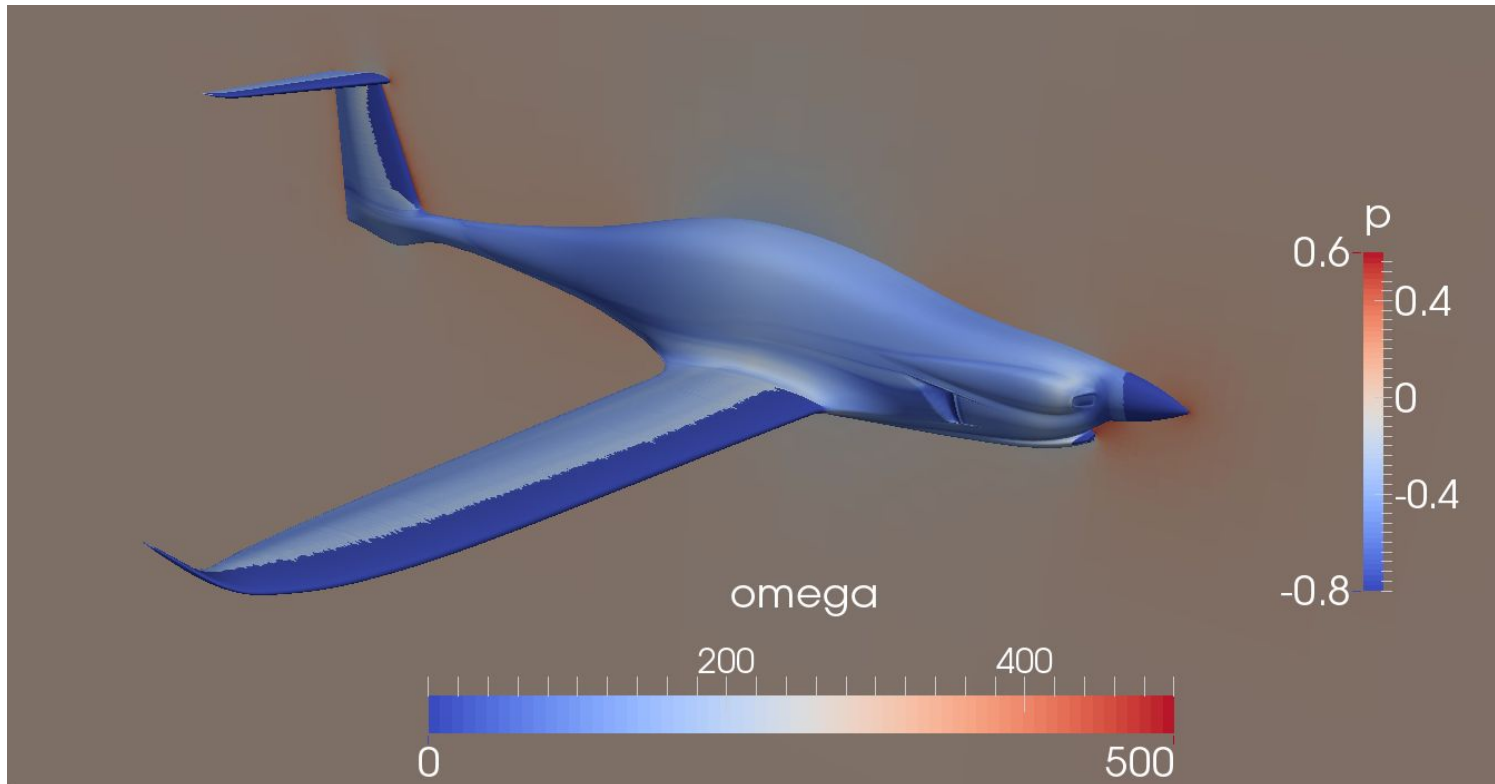
```
addLayersControls
{
    relativeSizes false;
    layers
    {
        "(body).*"
        {
            nSurfaceLayers 13;
        }
    }
    expansionRatio 1.5;
    finalLayerThickness 0.0008;

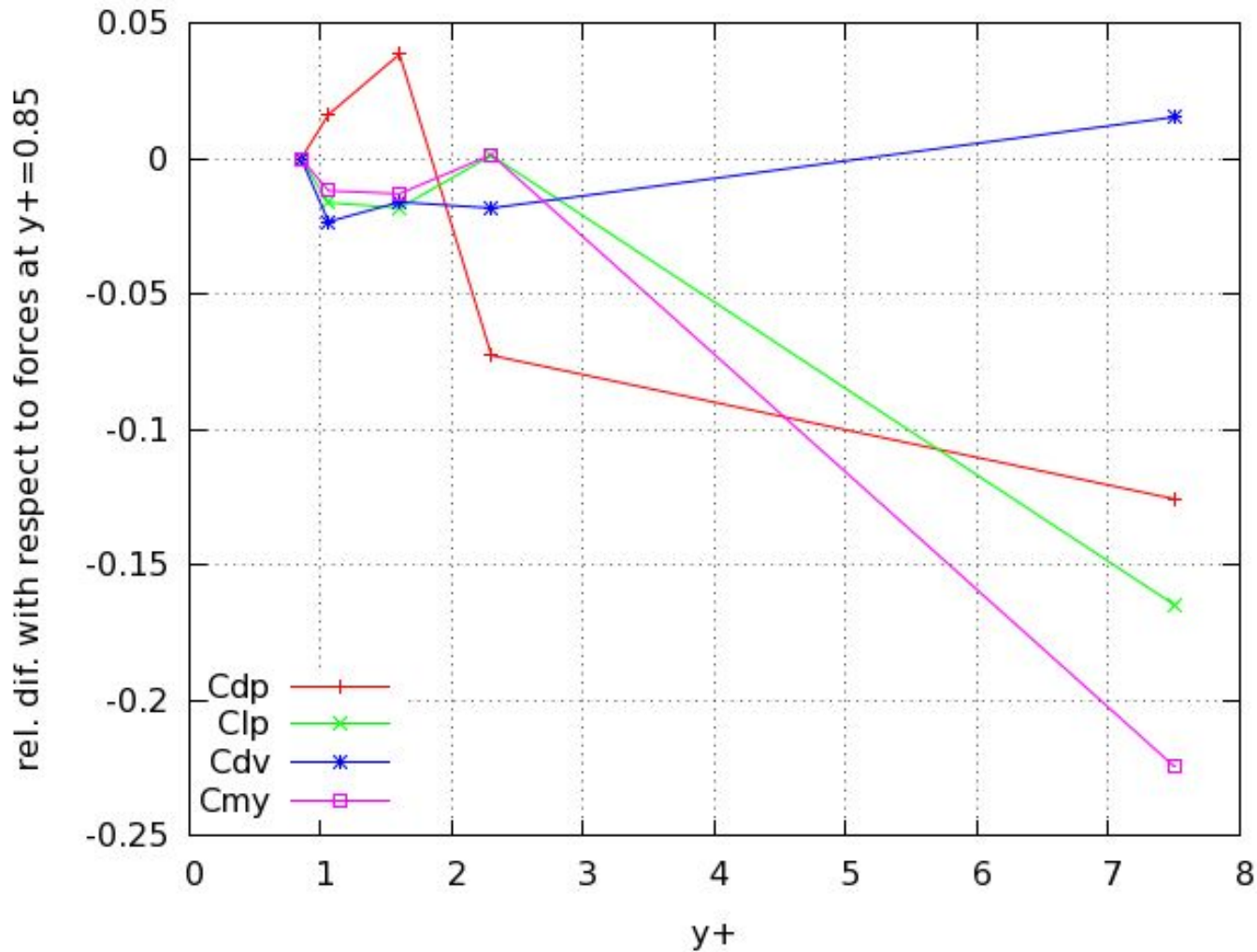
    featureAngle 30;
    slipFeatureAngle 0;
}
```

```
meshQualityControls
{
    maxNonOrtho 65;

    maxBoundarySkewness -20;
    maxInternalSkewness -4;

    minDeterminant 1e-6;
}
```







Learn how to:

- make a proper mesh - such a fine mesh at the surface
- use symmetry plane
- preview the decomposed case – reconstruction takes a lot of time
- extract only necessary data and preview it with paraView
- automatically consecutively run all steps of the simulation process
- how to run, handle and postprocess such big cases
- persuade HPC provider to increase RAM

- Deeper knowledge of running, handling and postprocessing very big cases
- Better estimate of the time and the cost
- Deeper knowledge of CFD simulations, what are its boundaries and capabilities
- Better designs and faster design cycles

Thank you!!!

Any questions or comments?

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