Introduction to Standard C++

Lecture 03: Class Hierarchies and Dynamic Polymorphism

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Necessity for class specialization: a classic example

Consider a program dealing with people employed by a firm:

```
class Employee {
  string name_, surname_;
  Date hiring_date_;
  /* ... */
};
```

Consider further the necessity of representing a manager:

```
class Manager {
   Employee record_;
   set < Employee *> group_;
   /* ... */
}; // Use composition as a first guess
```

Necessity for class specialization: a classic example

```
/* Prints name, surname and hiring date */
void printStatus(const Employee& emp);
/* The previous function should
  work with Manager objects */
class Manager : public Employee {
  set < Employee*> group_;
 /* ... */
```

- From a software design perspective a Manager is an Employee
- This kind of relationship is expressed in C++ through inheritance
- **Employee** is referred to as the base class
- Manager is called the derived class

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Derived classes (§10)

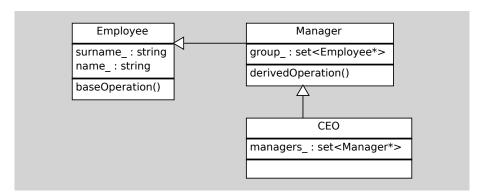
Consider the following definition:

```
class Manager : public Employee {
  /* ... */
};
```

- Employee is a direct base class of Manager
- In general, A is a base class of B if:
 - it is a direct base class of B
 - it is a direct base class of one of B base classes
- Unless redeclared in the derived class, members of a base class are also considered to be members of the derived class
- The base class members are said to be inherited by the derived class
- Inherited members can be referred to in expressions, unless their names are hidden or ambiguous

Derived classes (§10)

A class hierarchy can be represented by a directed acyclic graph:



- An arrow means "directly derived from"
- 2 A graph of this kind is often referred to as subobject lattice

Derived classes (§10)

An object may have multiple levels of inheritance:

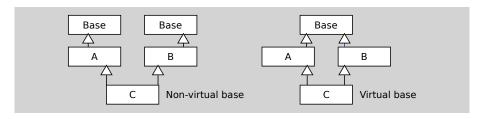
```
struct Base {
   int a, b, c;
};
struct DerivedL1 : Base {
   int b;
};
struct DerivedL2 : DerivedL1 {
   int c;
};
```

- 1 In this example, Base is:
 - a direct base class of DerivedL1
 - an indirect base class of DerivedL2

Multiple base classes (§10.1): subobject lattices

```
class X { };
class Y : public X, public X {
}; // ill -formed
struct L {
 int next:
class A : public L { };
class B : public L { };
class C : public A, public B {
 void f();
}; // well-formed
class D : public A, public L {
 void f();
}; // well-formed
```

Multiple base classes ($\S10.1$): virtual base classes



- A base class specifier that:
 - does not contain the keyword virtual, specifies a non-virtual base class
 - contains the keyword virtual, specifies a virtual base class
- 2 For each distinct occurrence of a non-virtual base class:
 - the derived object contains a distinct base class subobject of that type
 - explicit qualification can be used to specify which subobject is meant

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Q: Can you draw the subobject lattice of A, B and C?

```
class V{};
class L : public V{};
class M : public virtual V{};
class N : public virtual V{};
class O : public M {};

class A : public M, public N {};
class B : public L, public M , public N {};
class C : public L, public N , public O {};
```

Member name lookup (§10.2)

- Member name lookup:
 - determines the meaning of a name in a class scope
 - can result in an ambiguity, in which case the program is ill-formed
- The scope in which name lookup begins is: non-qualified expression class scope of this qualified expression scope of the nested name specifier
- The lookup-set for a name f in class C consists of: declaration set a set of members named f subobject set a set of subobjects where declarations were found

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Member name lookup (§10.2)

```
struct A { int f(); };
struct B { int f(); };
struct C : A, B {
  int f() { return A::f() + B::f(); }
struct V {int v;};
struct A {int a; static int s; enum {e};};
struct B : A, virtual V {};
struct C : A, virtual V {};
struct D : B, C {};
D* pd; // Are pd \rightarrow \{v, s, e, a\} ambiguous?
```

- Ambiguities can often be resolved by qualifying a name
- A static member, a nested type or an enumerator defined in a base class can be found unambiguously

Q: Which names are ambiguous? ($\S10.2$)

```
struct V { int f(); int x; };
struct W { int g(); int y; };
struct B : virtual V, W {
 int f(); int x;
 int g(); int y;
struct C : virtual V, W { };
struct D : B, C { void glorp(); };
void D::glorp() {
 x++; // ??
 f(); // ??
 y++; // ??
 g(); // ??
```

Q: Which conversion triggers an ambiguous name look-up?

```
struct V { };
struct A { };
struct B : A, virtual V { };
struct C : A, virtual V { };
struct D : B, C { };
void g() {
 D d:
 B* pb = \&d; // ??
 A* pa = \&d; // ??
 V* pv = \&d; // ??
```

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Virtual functions (§10.3)

- A polymorphic class declares or inherits a virtual function
- 2 If a virtual member function vf:
 - is declared in a class Base
 - is declared in a class Derived, derived directly or indirectly from Base
 - Derived::vf prototype is exactly the same as Base::vf

then Derived::vf is also virtual and it overrides Base::vf

- A virtual member function is a final overrider unless the most derived class of which Base is a base declares or inherits a function that overrides it
- In a derived class, if a virtual member function of a base class subobject has more than one final overrider the program is ill-formed
- Seven though destructors are not inherited, a destructor in a derived class overrides a base class destructor declared virtual

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Example (§10.3.2): final overrider

```
struct A { virtual void f(); };
struct B : virtual A {
 virtual void f();
struct C : B , virtual A {
  using A:: f;
};
void foo() {
 C c:
 c.f(); // calls B::f (final overrider)
 c.C.:f(); // calls A::f (using-declaration)
```

Virtual functions (§10.3)

A virtual member function does not have to be visible to be overridden:

```
struct B {
    virtual void f();
};
struct D : B {
    void f(int);
};
struct D2 : D {
    void f();
};
```

- In the previous snippet:
 - the function **f(int)** in class **D** hides the virtual function **f()**
 - D::f(int) is not a virtual function
 - f() in class D2 has the same name and parameter list as B::f()
- ② D2::f() is a virtual function that overrides the function B::f()

Return type of overriding functions (§10.3.7)

- 1 The return type of a function D::f overriding B::f shall be either:
 - identical to the return type of the overridden function
 - covariant with the classes of the functions
- The return types of the functions are covariant if:
 - both are pointers or references to classes
 - the class in the return type of B::f
 - is the same class as the class in the return type of D::f
 - is an unambiguous and accessible base class of the return type of D::f
 - both pointers or references have the same cv-qualification
 - the class type in the return type of D::f has the same cv-qualification
 as or less cv-qualification than the class type in the return type of B::f

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Virtual functions (§10.3.8): example

```
class B { };
class D : private B { friend class Derived; };
struct Base {
  virtual void vf1();
 virtual void vf2();
 virtual void vf3();
 virtual B* vf4();
 virtual B* vf5();
struct No_good : public Base {
 D* vf4(); // error: B is inaccessible
struct Derived : public Base {
 void vf1(); // virtual and overrides Base::vf1()
 void vf2(int); // not virtual, hides Base::vf2()
 char vf3(); // error: invalid return type
 D* vf4(); // OK: returns pointer to derived class
```

Q: Is there a difference between case 1 and 2?

```
class Transaction {
public:
  Transaction();
  virtual void logTransaction() const;
};
class BuyTransaction: public Transaction {
public:
  virtual void logTransaction() const;
  BuyTransaction();
/* 1 */
Transaction::Transaction() { logTransaction(); }
BuyTransaction :: BuyTransaction(){}
/* 2 */
Transaction::Transaction() {}
BuyTransaction :: BuyTransaction(){ logTransaction();}
```

Abstract classes (§10.4)

```
class point {
 /* ... */
class shape { // abstract class
  point center;
public:
  point where() { return center; }
  void move(point p) { center=p; draw(); }
  virtual void rotate(int) = 0; // pure virtual
  virtual void draw() = 0; // pure virtual
```

- An abstract class defines an interface, therefore:
 - it can be used only as a base class of some other class
 - has at least one pure virtual function
- Derived classes provide a variety of implementations

Abstract classes (§10.4)

```
shape x; // error: object of abstract class
shape* p; // OK
shape f(); // error
void g(shape); // error
shape& h(shape&); // OK
```

- An abstract class shall not be used as
 - a parameter type
 - a function return type
 - the type of an explicit conversion
- 2 Pointers and references to an abstract class can instead be declared
- From these rules it follows that:
 - an abstract class can be derived from a class that is not abstract
 - a pure virtual function may override a non-pure virtual function

Abstract classes (§10.4)

A class is abstract if it inherits at least one pure virtual function:

```
class ab_circle : public shape {
 int radius;
public:
 void rotate(int) { }
 // ab_circle::draw() is a pure virtual
class circle : public shape {
 int radius:
public:
 void rotate(int) { }
 // a definition is required somewhere
 void draw();
```

Accessibility of base classes (§11.2)

The keywords **public**, **protected** and **private**:

```
class B { };
class D1 : private B { };
class D2 : public B { };
class D3 : B { }; // B private by default
struct D4 : public B { };
struct D5 : private B { };
struct D6 : B { }; // B public by default
class D7 : protected B { };
struct D8 : protected B { };
```

may be used to set access properties of base classes

Accessibility of base classes (§11.2)

A member of a private base class:

```
struct B { int mi; // non-static member
     static int si; // static member };
class D : private B {};
class DD : public D { void f(); };
void DD::f() {
 mi = 3; // error: mi is private in D
 si = 3; // error: si is private in D
 ::B b;
 b.mi = 3; // OK ( b.mi is different from this->mi)
 b.si = 3; // OK ( b.si is different from this->si)
  ::B::si = 3: // OK
  ::B* bp1 = this; // error: B is a private base class
  ::B* bp2 = (::B*) this; // OK with cast
 bp2->mi = 3; // OK: access through a pointer to B.
```

might be inaccessible as an inherited member name, but accessible directly

Q: Which of the following expressions are ill-formed?

```
class B { protected: int i; };
class D1 : public B {};
class D2 : public B {
  friend void fr(B*,D1*,D2*); void mem(B*,D1*);
};
void fr (B* pb, D1* p1, D2* p2) {
pb->i = 1; p1->i = 2; p2->i = 3; // ??
int B::* pmi_B = &B::i; int B::* pmi_B2 = &D2::i; // ??
void D2::mem(B* pb, D1* p1) {
pb->i = 1; p1->i = 2; i = 3; B::i = 4;//??
void g(B* pb, D1* p1, D2* p2) {
 pb->i = 1; p1->i = 2; p2->i = 3; // ??
```

Access to virtual functions (§11.5)

```
struct B {
virtual int f();
class D : public B {
private:
int f();
void f() {
D d;
B* pb = \&d;
D* pd = &d:
pb \rightarrow f(); // OK: B:: f() is public
pd->f(); // error: D::f() is invoked (private)
```

- The access rules for a virtual function:
 - are determined by its declaration
 - are not affected by the rules for a function that later overrides it

Derived classes: member inizialization (§12.6.2.10)

- 1 The initialization of a class object proceeds in the following order:
 - virtual base classes initialized in the order they appear (depth-first left-to-right traversal)
 - direct base classes initialized in declaration order non-static data members initialized in declaration order constructor body executed after member initialization
- The declaration order is mandated to ensure that base and member subobjects are destroyed in the reverse order of initialization
- Member functions (including virtual member functions) can be called for an object under construction
- However, if these operations are performed in an initializer the result of the operation is undefined

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Dynamic cast (§5.2.7)

The result of the expression:

```
dynamic_cast<T>(v)
```

- Converts the expression v to type T
- T shall be a pointer or reference to a complete class type or void *
- The dynamic_cast operator shall not cast away constness
- If the type of v is the same as T the result is v
- If v is a null pointer value, the result is the null pointer value of type T
- If T is pointer to B and v has type pointer to D such that B is a base class of D, the result is a pointer to the unique B subobject of the D object pointed to by v
- Otherwise, v shall be a pointer to or an Ivalue of a polymorphic type

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Dynamic cast (§5.2.7)

```
class A { virtual void f(); };
class B { virtual void g(); };
class D : public virtual A, private B { };
void g() {
 D d:
 B* bp = (B*) \&d; // cast needed to break protection
 A* ap = \&d; // public derivation, no cast needed
 D\& dr = dynamic_cast < D\&>(*bp); // fails
 ap = dynamic_cast<A*>(bp); // fails
 bp = dynamic_cast < B*>(ap); // fails
 ap = dynamic_cast <A*>(&d); // succeeds
 bp = dynamic_cast < B*>(&d); // ill -formed
```

Static cast (§5.2.9)

The result of the expression:

```
static_cast <T>(v)
```

- Converts the expression v to type T
- The static_cast operator shall not cast away constness
- \odot If the declaration **T** $\mathbf{t}(\mathbf{e})$ is well-formed, \mathbf{e} is converted to type **T**
- The effect of such an explicit conversion is the same as:
 - performing the declaration and initialization
 - using the temporary variable as the result of the conversion
- An Ivalue of type B can be cast to D& when:
 - D is a class derived from B
 - a valid standard conversion from pointer to D to pointer to B exists
 - B is not a virtual base class of D

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DISALLOW WHAT YOU DON'T WANT (PART 2)

A class **Uncopyable** that barely can't be copied or assigned:

```
class Uncopyable {
protected:
  Uncopyable() {};
  ~Uncopyable(){};
private:
  Uncopyable (const Uncopyable &);
  Uncopyable& operator=(const Uncopyable&);
};
```

can be used as a policy to propagate the behavior in derived classes:

```
class Derived : private Uncopyable {
 // This class will fail at compile-time in case
 // copy-constructor or assignment are generated
};
```

Destructor in Polymorphic base classes

```
class TimeKeeper {
public:
 TimeKeeper();
  virtual ~TimeKeeper();
/* ... */
class AtomicClock: public TimeKeeper { /* ... */ };
class WaterClock: public TimeKeeper { /* ... */ };
```

As many clients will access a dynamic object through a pointer or reference to its polymorphic base, the use of a virtual destructor is mandatory:

```
// Get dynamically allocated object
TimeKeeper *ptk = getTimeKeeper();
/* ... */
delete ptk;
// What if a non-virtual destructor is used here?
```

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Make interfaces easy to use correctly

Developing effective interfaces requires that you consider the kinds of mistakes that clients might make:

```
class Date {
public:
  Date(int month, int day, int year);
};
```

At a first glance this may seem reasonable, but:

```
Date d(30, 3, 2013); // should be d(3,30,2013)
Date d(30,30, 2013); // should be d(3,30,2013)
```

These client errors may be prevented by the introduction of new types:

```
struct Day {
  explicit Day(int d) : val_(d) {}
  int val_; };
```

Make interfaces easy to use correctly

The new definition of **Date** would be:

```
class Date {
public:
 Date (const Month& month,
       const Day& day.
       const Year& year);
/* · · · · */
Date d(30, 3,2013); // error
Date d(Day(30), Month(3), Year(2013)); // error
Date d(Month(3), Day(30), Year(2013)); // OK
```

Once the right types are in place, it is reasonable to:

- restrict the values of those types
- restrict the set of operations that are allowed on those types
- ensure a behavior that is as compatible as possible with built-in types

CLASS DESIGN IS TYPE DESIGN

Good class have natural syntax and intuitive semantics:

- How should objects of your new type be created and destroyed?
- Mow should object initialization differ from object assignment?
- What does it mean for objects to be passed by value?
- What are the restrictions on legal values for your new type?
- Does your new type fit into an inheritance graph?
- What kind of type conversions are allowed for your new type?
- What operators and functions make sense for the new type?
- What standard functions should be disallowed?
- Who should have access to the members of your new type?
- What is the "undeclared interface" of your new type?

Prefer non-member non-friend functions

Object oriented principles dictate encapsulation, but usually it is misunderstood how the principle should be put into practice:

```
class WebBrowser {
public:
    void clearCache();
    void clearHistory();
    void removeCookies();
};
```

There are at least two alternatives to perform these actions together:

```
/* Member function */
void WebBrowser:: clearAll() {
/* ... */
}
/* External function */
void clearBrowser(WebBrowser& browser);
```

Prefer non-member non-friend functions

In C++ the best solution to this problem is the use of convenience functions with a common namespace, but defined is separate translation units:

```
/* header "webbrowser.h" */
namespace WebBrowserStuff {
   class WebBrowser { /* ... */ };
}
/* header "webbrowsercookies.h" */
namespace WebBrowserStuff {
   // Cookies related convenience functions
}
```

This approach effectively implements three basic OO principles:

- encapsulation
- packaging flexibility
- functional extensibility

Convert all the parameters of a function

Consider the following snippet:

```
class Rational {
public:
   Rational(int numerator = 0, int denominator = 1);
   /* ... */
};
```

The correct way to support mixed-mode arithmetic operations for a class of this kind is through non-member functions:

```
const Rational operator*(const Rational& Ihs, const Rational& rhs);
```

as it allows compilers to perform implicit type conversions on all arguments.

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Public inheritance models "IS-A"

The equivalence of public inheritance and "is-a" relationship sounds simple, but sometimes your intuition can mislead you:

```
class Bird {
public:
  virtual void fly() = 0;
};
class Penguin : public Bird {
  /* Can they fly?!? */
};
```

To implement an "is-a" relationship you must ensure that:

everything that applies to base classes must also apply to derived classes

because every derived class object is a base class object.

AVOID HIDING INHERITED NAMES

Consider the following snippet:

```
class Base {
public:
   void mf3(double& in); };
class Derived: public Base {
public:
   void mf3(int& in); };
```

In this case **Derived**::mf3 hides **Base**::mf3. This is never desirable in case of public inheritance. The correct way to extend the look-up set of a name is through a **using** declaration:

```
class Derived: public Base {
public:
    using Base::mf3;
    void mf3(int& in);
};
```

INHERITANCE OF INTERFACES AND IMPLEMENTATIONS

Consider the following class hierarchy:

```
class Shape {
public:
    virtual void draw() const = 0;
    virtual void error(const std::string& msg);
    int objectID() const;
};
class Rectangle: public Shape { /* ... */ };
class Ellipse : public Shape { /* ... */ };
```

There is clearly a difference in the semantic of the three declarations:

pure virtual function derived classes inherit a function interface only

virtual function derived classes inherit a function interface as well as a default implementation

non-virtual function derived classes inherit a function interface as well as a mandatory implementation

COMPOSITION MODELS "HAS-A"

Composition is the relationship between types that arises when objects of one type contain objects of another type:

```
class Address { /* ... */ };
class PhoneNumber { /* ... */ };
class Person {
public:
    /* ... */
private:
    std::string name;
    Address address;
    PhoneNumber voiceNumber;
    PhoneNumber faxNumber;
};
```

It's meaning is completely different from that of public inheritance:

application domain models an "has-a" relationship implementation domain models an "is implemented in terms of" relationship

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USE OF PRIVATE INHERITANCE

An implementation detail can be coded using private inheritance:

```
class Widget: private Timer {
private:
  virtual void onTick() const; };
```

Private inheritance can usually be avoided resorting to private classes:

```
class Widget {
private:
   class WidgetTimer: public Timer {
   public:
     virtual void onTick() const; };
   WidgetTimer timer; };
```

Composition is to be preferred to this approach, though it makes sense:

- when a derived class needs access to protected members
- when a derived class needs to redefine inherited virtual functions

USE OF MULTIPLE INHERITANCE

```
class IPerson { // Interface to be implemented
public:
  virtual ~Iperson(){}
  virtual std::string name() const = 0; };
class PersonInfo { // Helps in implementing an IPerson
public:
  const char * theName() const; };
class CPerson: public IPerson, private PersonInfo {
public:
virtual std::string name() const {
   std::string name(theName);
  return name;
} };
```

One of the most common use case of multiple inheritance is:

public inheritance from an interface

private inheritance from a class that helps with implementation

The one slide summary of the lecture

Class hierarchies and polymorphism

- A class may inherit from multiple base classes
- Virtual functions may be overridden to obtain a polymorphic behavior
- Abstract classes define an interface and cannot be instantiated

Best practices

- Destructors in polymorphic base classes must be virtual
- Public inheritance models the is-a relationship
- Composition or private inheritance model the has-a relationship
- Avoid hiding inherited names, use multiple inheritance judiciously

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 - A Member look-up set

Member look-up set (§10.2): definition and calculation

The following steps define how the look-up set S(f, C) is constructed:

- if C contains a declaration of f: declaration set contains every declaration of f in C subobject set contains C
- otherwise S(f, C) is initially empty
- if C has direct base classes B_i i = 1, ..., n
 - calculate $S(f, B_i)$ for i = 1, ..., n
 - 2 merge all the $S(f, B_i)$ into S(f, C)

Member look-up set ($\S10.2$): definition and calculation

The following steps define the result merging process:

- - each of the subobject members of $S(f, B_i)$ is a base class subobject of at least one of the subobject members of S(f, C)
 - $S(f, B_i)$ is empty
- 2 S(f, C) is a copy of $S(f, B_i)$ if:
 - each of the subobject members of S(f,C) is a base class subobject of at least one of the subobject members of $S(f, B_i)$
 - S(f,C) is empty
- S(f,C) is ambiguous (invalid declaration set) if:
 - $S(f, B_i)$ and S(f, C) differ

An invalid declaration set is considered different from any other

• Otherwise, the new S(f,C) is a lookup set with the shared set of declarations and the union of the subobject sets

Member look-up set ($\S10.2.7$): example

```
struct A { int x; };// S(x,A) = \{\{A::x\}, \{A\}\}
struct B { float x; \}; // S(x,B) = \{\{B::x\}, \{B\}\}
// S(x,C) = \{invalid, \{ A in C, B in C \}\}
struct C: public A, public B { };
// S(x,D) = S(x,C)
struct D: public virtual C { };
// S(x,E) = \{\{E::x\}, \{E\}\}\
struct E: public virtual C { char x; };
// S(x,F) = S(x,E)
struct F: public D, public E { };
int main() {
 F f:
  f.x = 0; // OK, lookup finds E::x
```