



INTRODUCTION TO MPI – COLLECTIVE COMMUNICATIONS AND COMMUNICATORS



Introduction to Parallel Computing with MPI and OpenMP







Part I: Collective communications





WHAT ARE COLLECTIVE COMMUNICATIONS?



Communications involving a group of processes

They are called by all the ranks involved in a communicator (or a group)

Collectives can be divided in three types:

- Synchronization collectives
- Message passing collectives
- Reduction collectives





PROPERTIES OF COLLECTIVE



- . All processes (in a communicator) call the collective function
- All collective communications are blocking (not true from MPI 3.0)
 No tags are required
- · Receive buffers must match in size (number of bytes)



It's a safe communication mode!!







A SMALL EXAMPLE

Write a program that initializes an array of two elements as (2.0,4.0) only on task 0, and than sends it to all the other tasks

How can you do that with the knowledge you got so far?



POINT-TO-POINT SOLUTION SuperComputing Applications and Innovatio

```
PROGRAM broad_cast_p2p
INCLUDE 'mpif.h'
INTEGER ierr, myid, nproc, root, i
INTEGER status(MPI STATUS SIZE)
REAL A(2)
CALL MPI INIT(ierr)
CALL MPI COMM_SIZE(MPI_COMM_WORLD,&
nproc, ierr)
CALL MPI COMM RANK(MPI COMM WORLD,&
myid, ierr)
IF(myid .EQ. 0) THEN
  a(1) = 2.0
  a(2) = 4.0
IF(myid .EQ. 0) THEN
 DO i=1.nproc-1
    CALL MPI ISEND(a,2,MPI REAL,i,0,&
          MPI COMM WORLD, ierr)
 FNDDO
ELSE
 CALL MPI RECV(a,2,MPI REAL,0,0,&
       MPI COMM WORLD, status, ierr)
ENDIF
WRITE(6,*) myid, ': a(1)=', a(1), 'a(2)=', a(2)
CALL MPI FINALIZE(ierr)
END PROGRAM
```

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```
#include <mpi.h>
#include <stdio.h>
int main (int argc, char **argv) {
 int myid, nproc, root, i;
 MPI Status status;
 float a[2]:
 MPI Init(&argc,&argv);
 MPI Comm size(MPI COMM WORLD, &nproc);
 MPI Comm rank(MPI COMM WORLD,&myid);
 if (myid == 0) {
   a[0] = 2.0;
   a[1] = 4.0;
 if (myid == 0) then {
  for (i=1;i<nproc;i++)
     MPI Isend(a,2,MPI FLOAT,i,0,
          MPI COMM WORLD);
 else {
   MPI Recv(a,2,MPI FLOAT,0,0,
        MPI COMM WORLD,&status);
 printf("%d : a[0]=, %f, a[1]=, %f\n",myid,a[0],a[1]);
 MPI Finalize();
 return 0;
```



MPI BROADCAST



C : int MPI_Bcast (void *buf, int count, MPI_Datatype datatype, int root, MPI_Comm comm)

FORTRAN : MPI_BCAST(BUFFER, COUNT, DATATYPE, ROOT, COMM, IERROR) <type> BUFFER(*) INTEGER COUNT, DATATYPE, ROOT, COMM, IERROR

Root process sends the buffer to all other processes with just one command! Note that all processes must specify the same root and the same communicator







COLLECTIVE SOLUTION

PROGRAM broad_cast INCLUDE 'mpif.h' INTEGER ierr, myid, nproc, root INTEGER status(MPI_STATUS_SIZE) REAL A(2) CALL MPI_INIT(ierr) CALL MPI_COMM_SIZE (MPI_COMM_WORLD,& nproc, ierr) CALL MPI_COMM_RANK(MPI_COMM_WORLD,& myid, ierr)

IF(myid .EQ. 0) THEN a(1) = 2.0 a(2) = 4.0 END IF

```
CALL MPI_BCAST(a, 2, MPI_REAL, 0, &
MPI_COMM_WORLD, ierr)
WRITE(6,*) myid, ': a(1)=', a(1), 'a(2)=', a(2)
CALL MPI_FINALIZE(ierr)
END PROGRAM
```

#include <mpi.h>
#include <stdio.h>

```
int main (int argc, char **argv) {
    int myid, nproc, root, i;
    MPI_Status status;
    float a[2];
    MPI_Init(&argc,&argv);
    MPI_Comm_size(MPI_COMM_WORLD, &nproc);
    MPI_Comm_rank(MPI_COMM_WORLD,&myid);
```

```
if ( myid ==0 ) {
a[0] = 2.0;
a[1] = 4.0;
}
```



MPI GATHER



C: int MPI_Gather(void *sendbuf, int sendcnt, MPI_Datatype sendtype, void *recvbuf, int recvcnt, MPI_Datatype recvtype, int root, MPI_Comm comm)

FORTRAN:

MPI_GATHER(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, RECVCOUNT, RECVTYPE, ROOT, COMM, IERROR) <type> SENDBUF(*), RECVBUF(*) INTEGER SENDCOUNT, SENDTYPE, RECVCOUNT, RECVTYPE, ROOT, COMM, IERROR

Each process, root included, sends the content of its send buffer to the root process. The root process receives the messages and stores them in the rank order.





GATHER EXAMPLE (C)



#include <mpif.h>
#include <stdio.h>

```
int main (int argc, char** argv) {
    int myid, nproc, count, i;
    float A[16], B[2];
    MPI_Init(ierr);
    MPI_Comm_size(MPI_COMM_WORLD, &nproc);
    MPI_Comm_rank(MPI_COMM_WORLD, &myid);
```

```
b[0] = (float) myid;
b[1] = (float) myid;
count = 2;
MPI_Gather(b, count, MPI_FLOAT, a, count, MPI_FLOAT, 0, MPI_COMM_WORLD);
```

```
if ( myid == 0 ) {
   for (i=0; i<count*nproc; i++)
        printf("%d : a[%d]=%f \n", myid, i, a[i]");
}</pre>
```

```
MPI_Finalize();
return 0;
```





MPI SCATTER



C :

int MPI_Scatter(void *sendbuf, int sendcnt, MPI_Datatype sendtype, void *recvbuf, int recvcnt, MPI_Datatype recvtype, int root, MPI_Comm comm)

Fortran :

MPI_SCATTER(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, RECVCOUNT, RECVTYPE, ROOT, COMM, IERROR) <type> SENDBUF(*), RECVBUF(*) INTEGER SENDCOUNT, SENDTYPE, RECVCOUNT, RECVTYPE, ROOT, COMM, IERROR

The root sends a message. The message is split into *n* equal segments, the *i*-th segment is sent to the *i*-th process in the group and each process receives this message.







SCATTER EXAMPLE (FORTRAN)



PROGRAM scatter INCLUDE ' mpif.h'

INTEGER ierr, myid, nproc, count, i REAL A(16), B(2) CALL MPI_INIT(ierr) CALL MPI_COMM_SIZE(MPI_COMM_WORLD, nproc, ierr) CALL MPI_COMM_RANK(MPI_COMM_WORLD, myid, ierr)

```
IF( myid .eq. 0 ) THEN
DO i = 1, 16
a(i) = REAL(i)
END DO
END IF
```

```
count = 2
CALL MPI_SCATTER(a, count, MPI_REAL, b, count, MPI_REAL, root, &
MPI_COMM_WORLD, ierr)
WRITE(6,*) myid, ': b(1)=', b(1), 'b(2)=', b(2)
```

```
CALL MPI_FINALIZE(ierr)
END
```





SCATTERV & GATHERV

What if the message that has to be scattered/gathered should not be split equally among processes?

C :

*int MPI_Scatterv(void *sendbuf, int *sendcnt, int *displs, MPI_Datatype sendtype, void *recvbuf, int recvcnt, MPI_Datatype recvtype, int root, MPI_Comm comm)*

Fortran :

MPI_GATHERV(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, RECVCOUNTS, DISPLS, RECVTYPE, ROOT, COMM, IERROR) <type> SENDBUF(*), RECVBUF(*) INTEGER SENDCOUNT, SENDTYPE, RECVCOUNTS(*), DISPLS(*), RECVTYPE, ROOT, COMM, IERROR

sendcounts/recvcounts is an array of integers stating how many elements should be considered for each process

displs is an array of integers stating the position of the starting element for each process





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SCATTERV & GATHERV

GATHERV recvcounts=(5,3,2,4) displs=(0,5,9,12)

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COLLECTIVE COMBINATIONS SuperComputing Applications and Innovatio

There are functions that combine the effects of two collective functions! For example, **MPI Allgather** is a combination of a gather + a broadcast

C:

int MPI Allgather(void *sendbuf, int sendcount, MPI Datatype sendtype, void *recvbuf, int recvcount, MPI_Datatype recvtype, MPI_Comm comm)

Fortran :

MPI_ALLGATHER(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, RECVCOUNT, RECVTYPE, COMM, IERR) <type> SENDBUF(*), RECVBUF(*) INTEGER SENDCOUNT, SENDTYPE, RECVTYPE, COMM, IERROR













MPI ALLTOALL

This function makes a redistribution of the content of each process in a way that each process knows the buffer of all others. It is a way to implement the matrix data transposition.



*int MPI_Alltoall(void *sendbuf, int sendcount, MPI_Datatype sendtype, void *recvbuf, int recvcount, MPI_Datatype recvtype, MPI_Comm comm)*

FORTRAN :

MPI_ALLTOALL(SENDBUF, SENDCOUNT, SENDTYPE, RECVBUF, RECVCOUNT, RECVTYPE, COMM, IERROR)

<type> SENDBUF(*), RECVBUF(*)

INTEGER SENDCOUNT, SENDTYPE, RECVCOUNT, RECVTYPE, COMM, IERROR









REDUCTION OPERATIONS



Reduction operations permit to:

- Collect data from each process
 - Reduce the data to a single value
- Store the result on the root process (MPI_Reduce) or
- Store the result on all processes (MPI_Allreduce)

C :

int MPI_Reduce(void* sendbuf, void* recvbuf, int count, MPI_Datatype datatype, MPI_Op op, int root, MPI_Comm comm)

FORTRAN :

MPI_ALLREDUCE(SENDBUF, RECVBUF, COUNT, DATATYPE, OP, COMM, IERROR) <type> SENDBUF(*), RECVBUF(*) INTEGER COUNT, DATATYPE, OP, COMM, IERROR



LIST OF REDUCTIONS



MPI op	Function
MPI_MAX	Maximum
MPI_MIN	Minimum
MPI_SUM	Sum
MPI_PROD	Product
MPI_LAND	Logical AND
MPI_BAND	Bitwise AND
MPI_LOR	Logical OR
MPI_BOR	Bitwise OR
MPI_LXOR	Logical exclusive OR
MPI_BXOR	Bitwise exclusive OR
MPI_MAXLOC	Maximum and location
MPI_MINLOC	Minimum and location





EXAMPLE: SUM REDUCTION (FORTRAN)

```
PROGRAM reduce
INCLUDE 'mpif.h'
INTEGER ierr, myid, nproc, root
REAL A(2), res(2)
CALL MPI INIT(ierr)
CALL MPI_COMM_SIZE(MPI_COMM_WORLD, nproc, ierr)
CALL MPI COMM RANK(MPI COMM WORLD, myid, ierr)
root = 0
a(1) = 2.0
a(2) = 4.0
CALL MPI REDUCE(a, res, 2, MPI REAL, MPI SUM, root, &
MPI COMM WORLD, ierr)
IF(myid .EQ. 0) THEN
WRITE(6,*) myid, ': res(1)=', res(1), 'res(2)=', res(2)
END IF
CALL MPI FINALIZE(ierr)
END PROGRAM
```







It stops all processes within a communicator until they are synchronized

int MPI_Barrier(MPI_Comm comm); CALL MPI_BARRIER(COMM,IERROR)









Part II: MPI communicators and groups







Many users are familiar with the mostly used communicator: **MPI_COMM_WORLD**

A communicator can be thought as a handle to a group.

- a group is a ordered set of processes
- each process is associated with a rank
- ranks are contiguous and start from zero

Groups allow collective operations to be operated on a subset of processes





DEFINITIONS & PROPERTIES



Intracommunicators are used for communications within a single group **Intercommunicators** are used for communications between two disjoint groups

Group management:

- All group operations are local
- Groups are not initially associated with communicators
- Groups can only be used for message passing within a communicator
- We can access groups, construct groups, destroy groups

Group accessors:

- **MPI_GROUP_SIZE** This routine returns the number of processes in the group

MPI_GROUP_RANK

This routine returns the rank of the calling process inside a given group





GROUP CONSTRUCTORS



Group constructors are used to create new groups from existing ones (initially from the group associated with MPI_COMM_WORLD; you can use mpi_comm_group to get this).

Group creation is a local operation: no communication is needed

After the creation of a group, no communicator has been associated to this group, and hence no communication is possible within the new group





GROUP CONSTRUCTORS



- MPI_COMM_GROUP(comm,group,ierr)
- This routine returns the group associated with the communicator comm
 - **MPI_GROUP_UNION**(group_a, group_b, newgroup, ierr)
- This returns the ensemble union of group_a and group_b
- **MPI_GROUP_INTERSECTION**(group_a, group_b, newgroup, ierr)
- This returns the ensemble intersection of group_a and group_b
- MPI_GROUP_DIFFERENCE(group_a, group_b, newgroup, ierr)
- This returns in newgroup all processes in group_a that rare not in group_b, ordered as in group_a





GROUP CONSTRUCTORS

MPI_GROUP_INCL(group, n, ranks, newgroup, ierr)



This routine creates a new group that consists of all the n processes with ranks ranks[0]... ranks[n-1]

```
Example:
group = {a,b,c,d,e,f,g,h,i,j}
n = 5
ranks = {0,3,8,6,2}
newgroup = {a,d,i,g,c}
```

MPI_GROUP_EXCL(group,n,ranks,newgroup,ierr)

This routine returns a newgroup that consists of all the processes in the group after removing processes with ranks: ranks[0]..ranks[n-1]

```
Example:
group = {a,b,c,d,e,f,g,h,i,j}
n = 5
ranks = {0,3,8,6,2}
newgroup = {b,e,f,h,j}
```





Communicator access operations are local, not requiring interprocess communication

Communicator constructors are collective and may require interprocess communications

We will cover in depth only intracommunicators, giving only some notions about intercommunicators.



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MPI_COMM_SIZE(comm,size,ierr)

Returns the number of processes in the group associated with the comm

MPI_COMM_RANK(comm,rank,ierr)

Returns the rank of the calling process within the group associated with the comm

MPI_COMM_COMPARE(comm1,comm2,result,ierr)

Returns:

- MPI_IDENT if comm1 and comm2 are the same handle
- MPI_CONGRUENT if comm1 and comm2 have the same group attribute
- MPI_SIMILAR if the groups associated with comm1 and comm2 have the same members but in different rank order
- MPI_UNEQUAL otherwise





MPI_COMM_DUP(comm, newcomm,ierr)
 This returns a communicator newcomm identical to the communicator comm

 MPI_COMM_CREATE(comm, group, newcomm,ierr)
 This collective routine must be called by all the process involved in the group associated with comm. It returns a new communicator that is associated with the group.
 MPI_COMM_NULL is returned to processes not in the group.

Note that the new group must be a subset of the group associated with comm!





EXAMPLE (C)



```
#include "mpi.h"
#include <stdio.h>
int main(int argc,char **argv) {
  int rank, new rank, nprocs, sendbuf, recvbuf, ranks1[4]={0,1,2,3}, ranks2[4]={4,5,6,7};
  MPI Group orig group, new group;
  MPI Comm new comm;
  MPI Init(&argc,&argv);
  MPI Comm size(MPI COMM WORLD, &nprocs);
  MPI_Comm_rank(MPI_COMM_WORLD, &rank);
  sendbuf = rank;
  MPI Comm group(MPI COMM WORLD, & orig group);
  if (rank < nprocs/2)
    MPI_Group_incl(orig_group, nprocs/2, ranks1, &new_group);
  else MPI Group incl(orig group, nprocs/2, ranks2, &new group);
  MPI_Comm_create(MPI_COMM_WORLD, new_group, &new_comm);
  MPI Allreduce(&sendbuf, &recvbuf, 1, MPI INT, MPI SUM, new comm);
  MPI Group rank (new group, &new rank);
  printf("rank= %d newrank= %d recvbuf= %d\n",rank,new_rank,recvbuf);
  MPI Finalize();
  return 0;
```

Hypothesis: nprocs=8 credits: http://static.msi.umn.edu



MPI COMM SPLIT



MPI_COMM_SPLIT(comm, color, key, newcomm, ierr)

This routine creates as many new groups and communicators as there are distinct values of color.

- comm is the old communicator
- *color* is an array of integers specifying on which group should a process belong to in the new communicator
- key is an array of integer that defines the rank that the process will get in the new communicator, that will be ssigned in increasing order depending on the associated key value
- newcomm is the new communicator

The rankings in the new groups are determined by the value of the key.

MPI_UNDEFINED is used as a color when the process shouldn't be included in any of the new groups





MPI COMM SPLIT



Rank	0	1	2	3	4	5	6	7	8	9	10
Proc ess	а	b	С	d	е	f	g	h	i	j	k
Color	U	3	1	1	3	7	3	3	1	U	3
Key	0	1	2	3	1	9	3	8	1	0	0

Both process a and j are returned MPI_COMM_NULL 3 new groups are created

 $\begin{array}{l} \{i,\,c,\,d\} \\ \{k,\,b,\,e,\,g,\,h\} \\ \{f\} \end{array}$



```
if(myid%2==0){
    color=1;
    }else{
        color=2;
    }
    MPI_COMM_SPLIT(MPI_COMM_WORLD,color,myid,&subcomm);
    MPI_COMM_RANK(subcomm,mynewid);
    printf("rank in MPICOMM_WORLD %d",myid,"rank in Subcomm %d",mynewid);
```

I am rank 2 in MPI_COMM_WORLD, but 1 in Comm 1. I am rank 7 in MPI_COMM_WORLD, but 3 in Comm 2. I am rank 0 in MPI_COMM_WORLD, but 0 in Comm 1. I am rank 4 in MPI_COMM_WORLD, but 2 in Comm 1. I am rank 6 in MPI_COMM_WORLD, but 3 in Comm 1. I am rank 3 in MPI_COMM_WORLD, but 3 in Comm 2. I am rank 5 in MPI_COMM_WORLD, but 2 in Comm 2. I am rank 1 in MPI_COMM_WORLD, but 0 in Comm 2.





DESTRUCTORS



The communicators and groups from a process' viewpoint are just handles.

Like all handles, there is a limited number available: you could (in principle) run out!

MPI_GROUP_FREE(group, ierr) MPI_COMM_FREE(comm,ierr)

Remember to free your handles after they are no longer needed, it is always a good practice (like with allocatable arrays)





INTERCOMMUNICATORS



Intercommunicators are associated with 2 groups of disjoint processes.

Intercommunicators are associated with a remote group and a local group

The target process (destination for send, source for receive) is its rank in the remote group

A communicator is either intra or inter, never both






INTRODUCTION TO MPI – VIRTUAL TOPOLOGIES



Introduction to Parallel Computing with MPI and OpenMP





VIRTUAL TOPOLOGY



Topology:

- extra, optional attribute that can be given to an intra-communicator; topologies cannot be added to inter-communicators.
 - can provide a convenient naming mechanism for the processes of a group (within a communicator), and additionally, may assist the runtime system in mapping the processes onto hardware.

A process group in MPI is a collection of n processes:

 each process in the group is assigned a rank between 0 and n-1.
 in many parallel applications a linear ranking of processes does not adequately reflect the logical communication pattern of the processes (which is usually determined by the underlying problem geometry and the

numerical algorithm used).





VIRTUAL TOPOLOGY



Virtual topology:

 logical process arrangement in topological patterns such as 2D or 3D grid; more generally, the logical process arrangement is described by a graph.

Virtual process topology .vs. topology of the underlying, physical hardware:

-virtual topology can be exploited by the system in the assignment of processes to physical processors, if this helps to improve the communication performance on a given machine.
-the description of the virtual topology depends only on the application, and is machine-independent.













RING

2D-GRID





A grid of processes is easily described with a cartesian topology

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- each process can be identified by cartesian coordinates
 - periodicity can be selected for each direction
- communications are performed along grid dimensions only



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EXAMPLE: 2D DOMAIN DECOMPOSITION



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SCAI CARTESIAN CONSTRUCTOR

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IN comm_old: input communicator (handle)

IN ndims: number of dimensions of Cartesian grid (integer)

IN dims: integer array of size ndims specifying the number of

processes in each dimension

IN periods: logical array of size ndims specifying whether the grid is

periodic (true) or not (false) in each dimension

IN reorder: ranking may be reordered (true) or not (false)

OUT comm_cart: communicator with new Cartesian topology (handle)

Returns a handle to a new communicator to which the Cartesian topology information is attached.

Reorder:

- false: the rank of each process in the new group is identical to its rank in the old group.
 - True: the processes may be reordered, possibly so as to choose a good embedding of the virtual topology onto physical machine.

If cart has less processes than starting communicator, left over processes have MPI_COMM_NULL as return







#include <mpi.h>



MPI_Init(&argc, &argv);

MPI_Cart_create(MPI_COMM_WORLD, 2, dim, period, reorder, &cart_comm);







CARTESIAN TOPOLOGY UTILITIES



MPI_Dims_Create: compute optimal balanced distribution of processes per coordinate direction with respect to: a given dimensionality the number of processes in a group optional constraints

MPI_Cart_coords:given a rank, returns process's coordinates

MPI_Cart_rank:given process's coordinates, returns the rank

MPI_Cart_shift:

- get source and destination rank ids in SendRecv operations





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MPI DIMS CREATE



MPI_DIMS_CREATE(nnodes, ndims, dims)

IN nnodes: number of nodes in a grid (integer)

IN ndims: number of Cartesian dimensions (integer)

IN/OUT dims: integer array of size ndims specifying the number of

nodes in each dimension

Help user to select a balanced distribution of processes per coordinate direction, depending on the number of processes in the group to be balanced and optional constraints that can be specified by the user





IN/OUT OF "DIMS"

MPI_DIMS_CREATE(nnodes, ndims, dims)



IN nnodes: number of nodes in a grid (integer)

IN ndims: number of Cartesian dimensions (integer)

IN/OUT dims: integer array of size ndims specifying the number of

nodes in each dimension

dims before call	Function call	dims on return	
(0, 0) (0, 0) (0, 3, 0) (0, 3, 0)	MPI_DIMS_CREATE(6, 2, dims) MPI_DIMS_CREATE(7, 2, dims) MPI_DIMS_CREATE(6, 3, dims) MPI_DIMS_CREATE(7, 2, dims)	(3, 2) (7, 1) (2, 3, 1) erroneous call	
			CIN

SCAI USING MPI_DIMS_CREATE SuperComputing Applications and Innovation (FORTRAN)

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integer :: dim(3), period(3), reorder, cube comm, ierr

CALL MPI COMM SIZE (MPI COMM WORLD, nprocs, ierr)

dim(1) = 0 ! let MPI arrange dim(2) = 0 ! let MPI arrange dim(3) = 3 ! I want exactly 3 planes

CALL MPI DIMS CREATE (nprocs, 3, dim, ierr)

if (dim(1)*dim(2)*dim(3) .LE. nprocs) then print *, "WARNING: some processes are not in use!" endif

> period = (1, 1, 0)reorder = 0

CALL MPI CART CREATE (MPI COMM WORLD, 3, dim, period, reorder, cube comm,ierr)





FROM COORDINATE TO RANK



MPI CART RANK (comm, coords, rank)

IN comm: communicator with Cartesian structure

IN coords: integer array (of size ndims) specifying the Cartesian

coordinates of a process

OUT rank: rank of specified process

- translation of the logical process coordinates to process ranks as they are used by the point-to-point routines
- if dimension i is periodic, when i-th coordinate is out of range, it is shifted back to the interval 0<coords(i)<dims(i) automatically
- out-of-range coordinates are erroneous for non-periodic dimensions





FROM RANK TO COORDINATE



• For each MPI process in Cartesian communicator, the coordinate whitin the cartesian topology are returned





MAPPING OF COORDINATES (C)



int cart_rank;

MPI_Comm_rank(cart_comm, &cart_rank);

int coords[2];

MPI_Cart_coords(cart_comm, cart_rank, 2, coords);

// set linear boundary values on bottom/left-hand domain
 if (coords[0] == 0 || coords[1] == 0) {
 SetBoundary(linear(min, max), domain);
 }
}

Computing Applications and Innovation Computing Applications and Innovation A 1D CARTESIAN SHIFT:

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Circular shift is another tipical MPI communication pattern:

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each process communicate only with its neighbors along one direction

periodic boundary conditions can be set for letting first and last processes partecipate in the communication

such a pattern is nothing more than a 1D cartesian grid topology with optional periodicity







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MPI CART SHIFT



Depending on the periodicity of the Cartesian group in the specied coordinate direction, MPI_CART_SHIFT provides the identifiers for a circular or an end-o shift.

In the case of an end-o shift, the value MPI_PROC_NULL may be returned in rank_source or rank_dest, indicating that the source or the destination for the shift is out of range.

provides the calling process the ranks of source and destination processes for an MPI_SENDRECV with respect to a specified coordinate direction and step size of the shift





CALL MPI_CART_CREATE(MPI_COMM_WORLD, 1, dim, period, 0, ring_comm, ierr)

CALL MPI CART SHIFT(ring comm, 0, 1, source, dest, ierr)

CALL MPI_SENDRECV(right_bounday, n, MPI_INT, dest, rtag, left_boundary, n, MPI_INT, source, ltag, ring_comm, status, ierr)

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PARTITIONING OF CARTESIAN STRUCTURES



It is often useful to partition a cartesian communicator into subgroups that form lower dimensional cartesian subgrids

- new communicators are derived

- lower dimensional communicators cannot communicate among them (unless inter-communicators are used)





MPI CART SUB

MPI_CART_SUB(comm, remain_dims, newcomm)

IN comm: communicator with Cartesian structure

IN remain_dims: the i-th entry of remain_dims specifies whether the

i-th dimension is kept in the subgrid (true) or is dropped (false)

(logical vector)

OUT newcomm: communicator containing the subgrid that includes the calling process

int dim[] = {2, 3, 4};

int remain_dims[] = {1, 0, 1}; // 3 comm with 2x4 processes 2D
 grid







INTRODUCTION TO MPI – MPI DATATYPES



Introduction to Parallel Computing with MPI and OpenMP





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DERIVED DATATYPE



What are?

Derived datatypes are datatypes that are built from the basic MPI datatypes (e.g. MPI_INT, MPI_REAL, ...)

Why datatypes?

Since all data is labeled by type, an MPI implementation can support communication between processes on machines with very different memory representations and lenghts of elementary datatypes (heterogeneous communication) Specifying application-oriented layout of data in memory can reduce memory-to memory copies in the implementaion allows the use of special hardware (scatter/gather) when available Specifying application-oriented layout of data on a file can reduce systems calls and physical disk I/O





DERIVED DATATYPE



You may need to send messages that contain:

1. non-contiguous data of a single type (e.g. a sub-block of a matrix)

2. contiguous data of mixed types (e.g., an integer count, followed by a sequence of real numbers)

3. non-contiguous data of mixed types

Possible solutions:

1. make multiple MPI calls to send and receive each data element

 \rightarrow If advantegeous, copy data to a buffer before sending it

2. use MPI_pack/MPI_Unpack to pack data and send packed data (datatype MPI_PACKED)

3. use MPI_BYTE to get around the datatype-matching rules. Like MPI_PACKED, MPI_BYTE can be used to match any byte of storage (on a byte-addressable machine), irrespective of the datatype of the variable that contains this byte.

> Additional latency costs due to multiple calls Additional latency costs due to memory copy Not portable to a heterogeneous system using MPI_BYTE or





DERIVED DATATYPE



Datatype solution:

- 1. The idea of MPI derived datatypes is to provide a simple, portable, elegant and efficient way of communicating non-contiguous or mixed types in a message.
 - During the communication, the datatype tells MPI system where to take the data when sending or where to put data when receiving.
 - 2. The actual performances depend on the MPI implementation
 - 3. Derived datatypes are also needed for getting the most out of MPI-I/O.







DEFINITION



A general datatype is an opaque object able to describe a buffer layout in memory by specifing:

- A sequence of basic datatypes
- A sequence of integer (byte) displacements.

Typemap = {(type 0, displ 0), ... (type n-1, displ n-1)} – pairs of basic types and displacements (in byte)

Type signature = {type 0, type 1, ... type n-1}

- list of types in the typemap

- gives size of each elements

- tells MPI how to interpret the bits it sends and received

Displacement:

- tells MPI where to get (when sending) or put (when receiving)





TYPEMAP



Example: Basic datatype are particular cases of a general datatype, and are predefined:

MPI_INT = {(int, 0)}

General datatype with typemap

Typemap = {(int,0), (double,8), (char,16)}





HOW TO USE



General datatypes (differently from C or Fortran) are created (and destroyed) at run-time through calls to MPI library routines.

Implementation steps are:

1. Creation of the datatype from existing ones with a datatype constructor.

2. Allocation (committing) of the datatype before using it.

3. Usage of the derived datatype for MPI communications and/or for MPI-I/O

4. Deallocation (freeing) of the datatype after that it is no longer needed.





MPI_TYPE_COMMIT (datatype) INOUT datatype: datatype that is committed (handle)

Before it can be used in a communication or I/O call, each derived datatype has to be committed

MPI_TYPE_FREE (datatype)

INOUT datatype: datatype that is freed (handle)

Mark a datatype for deallocation

Datatype will be deallocated when all pending operations are finished







MPI_TYPE_CONTIGUOUS (count, oldtype, newtype) IN count: replication count (non-negative integer) IN oldtype: old datatype (handle) OUT newtype: new datatype (handle)

MPI_TYPE_CONTIGOUS constructs a typemap consisting of the replication of a datatype into contiguous locations.
 newtype is the datatype obtained by concatenating count copies of oldtype.





MPI TYPE CONTIGUOUS

count = 4; MPI_Type_contiguous(count, MPI_FLOAT, &rowtype);

1.0	2.0	3.0	4.0
5.0	6.0	7.0	8.0
9.0	10.0	11.0	12.0
13.0	14.0	15.0	16.0

MPI_Send(&a[2][0], 1, rowtype, dest, tag, comm);



1 element of row type

a[4][4]





MPI TYPE VECTOR



MPI_TYPE_VECTOR (count, blocklength, stride, oldtype, newtype) IN count: Number of blocks (non-negative integer) IN blocklen: Number of elements in each block (non-negative integer) IN stride: Number of elements (NOT bytes) between start of each block (integer) IN oldtype: Old datatype (handle) OUT newtype: New datatype (handle)

Consists of a number of elements of the same datatype repeated with a certain stride







count = 4; blocklength = 1; stride = 4; MPI_Type_vector(count, blocklength, stride, MPI_FLOAT, &columntype);

1.0	2.0	3.0	4.0	a[4][4]
5.0	6.0	7.0	8.0	
9.0	10.0	11.0	12.0	
13.0	14.0	15.0	16.0	

MPI_Send(&a[0][1], 1, columntype, dest, tag, comm);



1 element of columnty pe





MPI TYPE HVECTOR



MPI_TYPE_CREATE_HVECTOR (count, blocklength, stride, oldtype, newtype)

IN count: Number of blocks (non-negative integer) IN blocklen: Number of elements in each block (non-negative integer) IN stride: Number of bytes between start of each block (integer) IN oldtype: Old datatype (handle) OUT newtype: New datatype (handle)

It's identical to MPI_TYPE_VECTOR, except that stride is given in bytes, rather than in elements . "H" stands for heterogeneous









MPI_TYPE_INDEXED (count, array_of_blocklengths, array_of_displacements, oldtype, newtype) IN count: number of blocks – also number of entries in array_of_blocklengths and array_of_displacements (non-negative integer) IN array_of_blocklengths: number of elements per block (array of non-negative integers) IN array_of_displacements: displacement for each block, in multiples of oldtype extent (array of integer) IN oldtype: old datatype (handle) OUT newtype: new datatype (handle)

Creates a new type from blocks comprising identical elements The size and displacements of the blocks can vary



count=3, array_of_blocklenghths=(/2,3,1/), array_of_displacements=(/0,3,8/)









MPI_Type_indexed(count, blocklengths, displacements, MPI_FLOAT, &indextype);

MPI_Send(&a, 1, indextype, dest, tag, comm);



1 element of indextype





MPI TYPE INDEXED EXAMPLE (FORTRAN)



! upper triangular matrix real, dimension(100,100) :: a integer, dimension(100) :: displ, blocklen integer :: i, upper, ierr

! compute start and size of the rows do i=1,100 displ(i) = 100*i+i

blocklen(i) = 100-i

end do

! create and commit a datatype for upper triangular matrix CALL MPI_TYPE_INDEXED (100, blocklen, disp, MPI_DOUBLE, upper,ierr) CALL MPI_TYPE_COMMIT (upper,ierr) ! ... send it ...

CALL MPI_SEND (a, 1, upper, dest, tag, MPI_COMM_WORLD, ierr) **MPI_Type_free (upper, ierr)**




MPI TYPE HINDEXED



MPI_TYPE_CREATE_HINDEXED (count, array_of_blocklengths, array_of_displacements, oldtype, newtype)

IN count: number of blocks – also number of entries in array_of_blocklengths and array_of_displacements (non-negative integer) IN array_of_blocklengths: number of elements in each block (array of non-negative integers) IN array_of_displacements: byte displacement of each block (array of integer) IN oldtype: old datatype (handle) OUT newtype: new datatype (handle)

This function is identical to MPI_TYPE_INDEXED, except that block displacements in array_of_displacements are specified in bytes, rather that in multiples of the oldtype extent



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MPI_TYPE_CREATE_INDEXED_BLOCK (count, blocklengths, array_of_displacements, oldtype, newtype)

IN count: length of array of displacements (non-negative integer) IN blocklengths: size of block (non-negative integer) IN array_of_displacements: array of displacements (array of integer) IN oldtype: old datatype (handle) OUT newtype: new datatype (handle)

Similar to MPI_TYPE_INDEXED, except that the block-length is the same for all blocks.

There are many codes using indirect addressing arising from unstructured grids where the blocksize is always 1 (gather/scatter). This function allows for constant blocksize and arbitrary displacements.





MPI TYPE SUBARRAY



MPI_TYPE_CREATE_SUBARRAY (ndims, array_of_sizes, array_of_subsizes, array_of_starts, order, oldtype, newtype)

IN ndims: number of array dimensions (positive integer) IN array_of_sizes: number of elements of type oldtype in each dimension of the full array (array of positive integers) IN array_of_subsizes: number of elements of type oldtype in each dimension of the subarray (array of positive integers) IN array_of_starts: starting coordinates of the subarray in each dimension (array of non-negative integers) IN order: array storage order flag (state: MPI_ORDER_C or MPI_ORDER_FORTRAN) IN oldtype: array element datatype (handle) OUT newtype: new datatype (handle)

The subarray type constructor creates an MPI datatype describing an n dimensional subarray of an n-dimensional array. The subarray may be situated anywhere within the full array, and may be of any nonzero size up to the size of the larger array as long as it is confined within this array.





MPI TYPE SUBARRAY EXAMPLE (C)





MPI_TYPE_CREATE_SUBARRAY (ndims, array_of_sizes, array_of_subsizes, array_of_starts, order, oldtype, newtype)

double subarray[100][25]; MPI_Datatype filetype; int sizes[2], subsizes[2], starts[2]; int rank;

MPI_Comm_rank(MPI_COMM_WORLD, &rank);

sizes[0]=100; sizes[1]=100; subsizes[0]=100; subsizes[1]=25; starts[0]=0; starts[1]=rank*subsizes[1];

MPI_Type_create_subarray(2, sizes, subsizes, starts, MPI_ORDER_C, MPI_DOUBLE, &filetype);

MPI_Type_commit(&filetype);





SIZE AND EXTENT



The MPI datatype for structures - MPI_TYPE_CREATE_STRUCT - requires dealing with memory addresses and further concepts:

Typemap: pairs of basic types and displacements

Extent: The extent of a datatype is the span from the lower to the upper bound (including "holes")

Size: The size of a datatype is the net number of bytes to be transferred (without "holes")







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SIZE AND EXTENT



Basic datatypes: size = extent = number of bytes used by the compiler

> Derived datatypes: extent include holes but...

beware of the type vector: final holes are a figment of our imagination



size = 6 x size of "old type"
extent = 10 x extent of "old type"





QUERY SIZE AND EXTENT OF DATATYPE



Returns the total number of bytes of the entry datatype

MPI_TYPE_SIZE (datatype, size)

IN datatype: datatype (handle)

OUT size: datatype size (integer)

Returns the lower bound and the extent of the entry datatype

MPI_TYPE_GET_EXTENT (datatype, lb, extent)

IN datatype: datatype to get information on(handle) OUT lb: lower bound of datatype (integer) OUT extent: extent of datatype (integer)





EXTENT



Extent controls how a datatype is used with the count field in a send and similar MPI operations

Consider

call MPI_Send(buf,count,datatype,...)

What actually gets sent?

do i=0,count-1 call MPI_Send(bufb(1+i*extent(datatype)),1,datatype,...) enddo

where *bufb* is a byte type like *integer*1*





MPI TYPE STRUCT



MPI_TYPE_CREATE_STRUCT (count, array_of_blocklengths, array_of_displacements, array_of_oldtypes, newtype) IN count: number of blocks (non-negative integer) -- also number of entries the following arrays IN array_of_blocklenghts: number of elements in each block (array of non-negative integer) IN array_of_displacements: byte displacement of each block (array of integer) IN array_of_oldtypes: type of elements in each block (array of handles to datatype objects) OUT newtype: new datatype (handle)

This subroutine returns a new datatype that represents count blocks. Each block is defined by an entry in array_of_blocklengths, array_of_displacements and array_of_types.

Displacements are expressed in bytes (since the type can change!)

To gather a mix of different datatypes scattered at many locations in space into one datatype that can be used for the communication.







USING EXTENT (NOT SAFE)

struct { float x, y, z, velocity; int n, type; } Particle;

Particle particles[NELEM];

int count, blockcounts[2]; MPI_Aint displ[2]; MPI_Datatype particletype, oldtypes[2];

count = 2; blockcounts[0] = 4; blockcount[1] = 2; oldtypes[0]= MPI_FLOAT; oldtypes[1] = MPI_INT;

MPI_Type_extent(MPI_FLOAT, &extent); displ[0] = 0; displ[1] = 4*extent;

MPI_Type_create_struct (count, blockcounts, displ, oldtypes, &particletype);

MPI_Type_commit(&particletype);

MPI_Send (particles, NELEM, particletype, dest, tag, MPI_COMM_WORLD);

MPI_Free(&particletype);



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C struct may be automatically padded by the compiler, e.g.



Using extents to handle structs is not safe! Get the addresses

MPI_GET_ADDRESS (location, address)

IN location: location in caller memory (choice)

OUT address: address of location (integer)

• The address of the variable is returned, which can then be used to determine the correct relative dispacements

Using this function helps with portability





USING DISPLACEMENTS

struct PartStruct {
 char class;
 double d[6];
 int b[7];
} particle[100];

MPI_Datatype ParticleType; int count = 3; MPI_Datatype type[3] = {MPI_CHAR, MPI_DOUBLE, MPI_INT}; int blocklen[3] = {1, 6, 7}; MPI_Aint disp[3];

> MPI_Get_address(&particle[0].class, &disp[0]); MPI_Get_address(&particle[0].d, &disp[1]); MPI_Get_address(&particle[0].b, &disp[2]); /* Make displacements relative */

disp[2] -= disp[0]; disp[1] -= disp[0]; disp[0] = 0;

MPI_Send(particle,100,ParticleType,dest,tag,comm); MPI_Type_free (&ParticleType);





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FORTRAN TYPES

According to the standard the memory layout of Fortran derived data is much more liberal

An array of types, may be implemented as 5 arrays of scalars!

type particle real :: x,y,z,velocity integer :: n end type particle type(particle) :: particles(Np)



type particle sequence real :: x,y,z,velocity integer :: n end type particle type(particle) :: particles(Np)

The memory layout is guaranteed using sequence or bind(C) type attributes Or by using the (old style) commons...

With Fortran 2003, MPI_Type_create_struct may be applied to common blocks, sequence and bind(C) derived types

it is implementation dependent how the MPI implementation computes the alignments (sequence, bind(C) or other)

The possibility of passing **particles** as a type depends on MPI implementation: try **particle%x** and/or study the MPI standard and Fortran 2008 constructs





PERFORMANCE



Performance depends on the datatype - more general datatypes are often slower

- some MPI implementations can handle important special cases: e.g., constant stride, contiguous structures
 - Overhead is potentially reduced by:
 - Sending one long message instead of many small messages
 - Avoiding the need to pack data in temporary buffers
 - Some implementations are slow





Credits...



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