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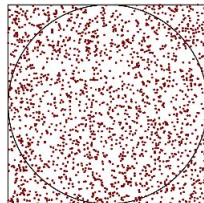
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# Let's Estimate $\pi$ with MC sampling

Write a program to estimate the area  $C$  of the unit circle using MC sampling.

$$C = \iint_{x^2+y^2 \leq 1} dx dy$$



- Let's consider a quarter of the area  
 $0 \leq x \leq 1, 0 \leq y \leq 1$
- extract  $N$  points in there ( $\mathbf{N}$ )
- count how many of them fall in (**inside**)
- $4 \mathbf{inside} / \mathbf{N}$  gives an estimate of  $\pi$

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*hints ...*

- ask user for **N**
- Repeat the following steps **N** times:
  - ① assign  $x$  and  $y$  random numbers in the range  $[0, 1)$
  - ② If  $(x^2 + y^2 \leq 1)$ , increment *inside*
- print your estimate of  $\pi$
  
- Try many different values of **N** and check MC error
- check range values for variable types to handle **N**
- Use `rand()` and `RAND_MAX` from `stdlib.h`

```

const double rand_norm = 1.0 / (RAND_MAX + 1.0);
...
x = rand_norm * rand();
  
```

# Finding Roots With Bisection

Write a program that implements root finding with bisection and apply it to a known function (E.g. one from `math.h`).

- Bisection method works if we are able to confine a root of  $f(x)$  in an interval between  $a$  and  $b$ , so that  $f(a)f(b) < 0$ .
- Bisection follows an iterative search:
  - 1 find the middle point  $c$  of  $a, b$
  - 2 evaluate  $p = f(a)f(c)$
  - 3 if  $p = 0$ , you are really lucky!
    - 1  $c$  is the root
  - 4 if  $p > 0$ , root is in the interval  $c, b$ 
    - 1 set  $a = c$
  - 5 if  $p < 0$ , root is in the interval  $a, c$ 
    - 1 set  $b = c$
  - 6 repeat from 1 until  $|b - a| < \epsilon$ , where  $\epsilon$  is a threshold

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Use the following elements:

- **while** and **if/else** controls
- **fabs ()**

Remember to make your program robust:

- choose appropriate  $\epsilon$  to reflect the precision of the C types in use
- handle errors and exit in a controlled way

Try it with:

- a known function from **math.h**
- the **double mysteriousf(double x)** function provided in the **libmysterious.a** library, check intervals  $[0, 10]$ ,  $[10, 0]$  and  $[0, 5]$

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Write a simple program that:

- asks the user for an integer number  $N$
- finds and prints out all prime numbers up to  $N$

A *prime number* is a natural number which has exactly *two distinct* natural number divisors: 1 and itself

program outline:

- get upper limit  $N$  from user
- for each number  $2 < n < N$ 
  - check if an exact divisor  $b < n$  of  $n$  exists
  - if no  $b$  is found, then  $n$  is prime

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- Use the following elements:
  - `printf()` and `scanf()`
  - `for` construct
  - `while` construct on  $b < n$  and
  - `if` construct on  $n$
- Remember to make your program robust:
  - check for proper input from the user ( $N < 0$  ??)
  - check type limits
  - handle errors and exit in a controlled way



# Function Integration

Write a simple program that computes the integral from 0 to 1 of the function  $f(x) = \frac{4}{(1+x^2)}$

Use the Riemann definition of an integral, that is

$$\int_a^b f(x) dx = \lim_{N \rightarrow \infty} \sum_{i=1}^N f(x_i) \Delta x, \text{ with } \Delta x = \frac{b-a}{N}$$

Program outline:

- Split  $[a, b]$  into  $N$  subintervals of  $\Delta x$  width
- compute the function  $f(x)$  in the middle point  $x_i$  of each interval and multiply for  $\Delta x$
- sum up all contributions
- print the result and find out if it is correct

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# Let's Build An Histogram

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- Is **rand** as uniform as they say? Let's test...
- Write a program that:
  - Generates random numbers in the range 0, 1
  - Builds an histogram and computes their average
- Use **rand()** and **RAND\_MAX** from **stdlib.h**
- Initialize to 0 an array of *ninterv* **ints** that holds the histogram; then, at each iteration:
  - Generate a random number
  - Find out the bin it belongs to (i.e. its index in the array)
  - Increment the corresponding array element and accumulate a sum to compute the average

# Array Transformation

Write a program that computes the difference between each element of an array and its successive element.

$$A[x_j] \rightarrow A[x_j] - A[x_{j+1}]$$

- start with an array  $A[20]$  initialized as  $A[i] = i$
- assume periodic boundary conditions
- use % operator in indexing expressions to implement periodic boundary conditions

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# Array Smoothing

Write a program that takes an array and applies  $N$  times a moving average smoothing transformation.

A moving average smoothing is a substitution:

$$A[x_i] \rightarrow \frac{1}{2k+1} \sum_{j=i-k}^{i+k} A[x_j]$$

- assume periodic boundary conditions on data
- iterate for  $N = 1, 2, 5, 10$  times
- check your program with  $k = 1, 2, 16$

*hints*

- start with an array  $A[20]$  initialized as  $\mathbf{A}[\mathbf{i}] = \mathbf{i}$
- check results at each iteration printing smoothed array elements
- Use `%` operator in indexing expressions to implement periodic boundary conditions

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Write functions using VLA to compute:

- matrix-vector product
  - matrix-matrix product
- 
- collect your functions in the source file **`linear_algebra_vla.c`**
  - initialize matrix **`A[i][j]=i*j`**, **`B[i][j]=i+j`**, **`V[i]=i`**
  - start with small squared 3x3 matrix to check results
  - write **`printMatrix()`** and **`printVector()`** functions to check results
  - try with a non-square matrix input too

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Use `qsort`, and `comparedouble` (from Module 7) to sort an array of `n` `double` random numbers in the range 0, 10

But `qsort` can be more powerful!

Initialize an array of `vec3d` variables with random numbers, and sort them by their first component

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Write a comparison function for module of `vect3d` data types and use it to sort a big vector of `vect3d`

- group your `vect3d` definition and functions in `vect3d.c` source
- write a test program to sort a `vect3d A[1000]` array
- initialize each `vect3d` element with random components ranging from 0.0 to 10.0

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Rewrite your `linear_algebra` functions for matrix-vector and matrix-matrix product without VLA, using pointers to **`double`**

- collect your functions in **`linear_algebra.c`**
- remember to cast function arguments appropriately
- check results against your previous version

# BLAS Library

The BLAS library (Basic Linear Algebra Subprograms) contains routines for basic vector and matrix operations.

- Quick Reference:  
<http://www.netlib.org/blas/index.html>
- BLAS are divided into 3 levels:
  - Level 1: vector-vector operations
  - Level 2: matrix-vector operations
  - Level 3: matrix-matrix operations
- widely used in scientific software
- Often provided as a part of architecture optimized Math Libraries:  
ACML(AMD), ESSL(IBM), GotoBLAS, MKL(Intel), Sun Performance Library, etc

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# BLAS C Interface

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- originally written for Fortran77
- BLAS provides a standard C interface
  - ... but include file name is not!
- function names are all lowercase and of the form:  
**`cblas_xname(...)`**
  - *x* denotes the data type:
    - s* for **float**,
    - d* for **double**,
    - c* for **float complex**,
    - z* for **double complex**

# An Example Involving Vectors

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BLAS Level 1:  $op: y \leftarrow \alpha x + y$

`cblas_saxpy (n,  $\alpha$ , x, incx, y, incy)`

- the name says it all!
- **n** is the size of vectors **x** and **y**
- $\alpha$  is the vector **x** multiplier
- **incx**, **incy** are increments to select vector elements

# An Example With Vectors And Matrices

BLAS Level 2:  $op: y \leftarrow \alpha Ax + \beta y$

```
cblas_dgemv (CblasRowMajor, CblasNoTrans,  
m, n,  $\alpha$ , A, lda, x, incx,  $\beta$ , y, incy)
```

- this is a general matrix vector multiply and add
- **CblasRowMajor** selects memory layout of data  
`enum CBLAS_ORDER {CblasRowMajor, CblasColMajor}`
- **CblasNoTrans** is used to transpose matrix  
`enum CBLAS_TRANSPOSE {CblasNoTrans, CblasTrans, CblasConjTrans}`
- **m**, **n** are dimensions of matrix A
- **lda** is the leading dimension of array A
- **incx**, **incy** are increments to select vector elements
- Matrices and vectors are passed as pointers (cast as appropriate!)

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# Level 2 BLAS In Action

Multiply a matrix  $A[20][10]$  by a vector  $x[10]$  and put results into vector  $y[10]$

```
int i, m = 20, n = 10;
double A[m][n], x[n], y[n];
double alpha = 1.0, beta = 0.0;
int lda = n, incx = incy = 1;
double dx = 0.05;

for (i=1; i<=m; i++) {
    for (j=1; j<=n; j++) {
        A[i][j] = (double) i * j + 0.5;
    }
}
for (i=0; i<n; i++) {
    x[i] = cos((double) i*dx);
}

cblas_dgemv (CblasRowMajor, CblasNoTrans,
             m, n, alpha, (double *) A, lda,
             x, incx, beta, y, incy);
```

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# Selecting Elements

From matrix  $A[20][10]$ , Let's extract a submatrix  $subA[8][5]$ ,  
And let's multiply it by even elements of vector  $x[10]$

```
int i, m = 20, n = 10;
int subm = 8, subn = 5;
double A[m][n], x[n], y[subm];
double alpha = 1.0, beta = 0.0;
int lda = n, incx = 2, incy = 1;
double dx = 0.05;

for (i=1; i<=m; i++) {
    for (j=1; j<=n; j++) {
        A[i][j] = (double) i * j + 0.5;
    }
}
for (i=0; i<n; i++) {
    x[i] = cos((double) i*dx);
}

cblas_dgemv (CblasRowMajor, CblasNoTrans,
            subm, subn, alpha, (double *) A, lda,
            x, incx, beta, y, incy);
```

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# Yet Another BLAS Example: Matrices

BLAS Level 3:  $op: C \leftarrow \alpha AB + \beta C$

`cblas_zhemm` (**CblasRight**, **CblasUpper**,  
**m**, **n**,  $\alpha$ , **A**, **lda**, **B**, **ldb**,  $\beta$ , **C**, **ldc**)

- this is an hermitian matrix matrix multiply and add
- **CblasRight** and **CblasUpper** select matrix representation in memory (half the elements is enough for hermitian ones)
- **m**, **n** are sizes of matrix **A**, **B**, **C**
- **lda**, **ldb**, **ldc** are leading dimensions of array **A**, **B**, and **C**
- Matrices and vectors are passed as pointers (cast as appropriate!)

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# Using BLAS library

Use BLAS library to compute matrix-matrix and matrix-vector product

The BLAS functions you need:

- DGEMV: Double precision GEneral Matrix-Vector product (BLAS lev2)
- DGEMM: Double precision GEneral Matrix-Matrix product (BLAS lev3)
- Use GSL (GNU Scientific Library) library `libgslcblas.a` in `lib/`
- include header file `include/gsl_cblas.h`
- do cast your arrays to proper BLAS function parameters

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# Timing Your Function

Use `clock()` function from `time.h` for timing your version of matrix-matrix product function against BLAS GEMM for square matrices of sizes 100, 200, 500, 1000

- `clock_t clock(void);` returns the processor clock time used since the beginning of the program
- divide the returned value by `CLOCKS_PER_SEC` to get the number of seconds
- adapt the following code to measure your functions

```
#include <time.h>
clock_t start, stop;
double t = 0.0;

// Start timer
start = clock();
// call your function
// Stop timer
stop = clock();
t = (double) (stop-start)/CLOCKS_PER_SEC;
```

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Write a program that parses command line and:

- accepts stand alone options (on/off switch)
  - accepts option with a single argument (int, double and string)
  - outputs a report of what it parsed
- 
- use `int argc, char *argv[]` parameters of `main()`
  - use `switch` control
  - use `strto...()`, `strcmp()`

# Parsing a file

Write a function that accepts a string containing a file name as its argument, and parses the file, storing retrieved values into global variables; the file has the format:

- **keyword value**
- empty lines or starting with a # should be ignored

Use main program in `simpleparsermain.c` and the input file `param.dat` to test your function.

Recognized parameters:

- **nx** (int) number of points in the x direction;
- **ny** (int) number of points in the y direction;
- **tol** (double) some kind of tolerance or threshold;

Of course feel free to add more keys if you want! Hints:

- Use `fgets()` to retrieve input lines, and test its return value;
- Parse input lines with `sscanf()`;

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# Parsing a file II

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After implementing and testing a very simple version:

- Find a way to check that values found in the file have the expected type and correct domain range ( $n_x < 0$  is nonsense)
- check for multiple parameter definitions
- Return an error message and exit if you find an unrecognized key;
- What if a line starts with white spaces? Did you already handle this?

Consider using `strtok()` or similar to implement more flexible and complicated parsing.



# Parse a structured ASCII file

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Write a program that reads protein coordinates from a .pdb file format

- .pdb file format files are wide used in bioinformatic
- coordinates begins with **ATOM** tag

```
ATOM 1 N PRO A 1 8.316 21.206 21.530 1.00 17.44 N ATOM 2 CA PRO A 1 7.608 20.729 20.3
1.00 17.44 C ATOM 3 C PRO A 1 8.487 20.707 19.092 1.00 17.44 C ATOM 4 O PRO A 1 9.466
21.457 19.005 1.00 17.44 O
```

# Seek in your file

Use seek I/O functionality to collect elements from a binary file

- open the **binaryfile.dat** file from course package
- read elements using the following steps
  - 8 bytes 128 bytes bakward from end of file, set bookmark **A** here
  - 8 bytes 32 bytes from the beginnig, set bookmark **B** here
  - 4 bytes 32 bytes from bookmark **A**
  - 16 bytes 64 bytes from bookmark **B**
- convert read elements to chars and print them

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- Write a program that:
  - Initializes an array of 900000 **doubles** with random numbers in the range 0, 1
  - Writes the array 10 times to an ASCII file.
  - Uses **time** and **difftime** from **time.h** to time the writing operation
- Remember to print enough decimal digits, to recover exact binary form of your data
- Try writing array elements on one line with no white spaces in between
- Try writing one element per line
- How big is your output file?

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- Modify your program so that it writes to a binary file with **`fwrite`**
- Try different solutions:
  - Write one element at a time: pointer arithmetic will help;
  - Write the array in chunks of 1000 elements;
  - Write the whole array with a single call to **`fwrite`**.
  - In any case, check the value returned by **`fwrite`**.
- What about output file dimensions?
- And what about time?

# Walking Around In Our File

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- Our output file now contains 10 copies of our array
- Let's read the first element of each copy in the file
- Let's print it together with its position
  - Let's use `fseek` to reach the right position
  - And `ftell` to have the current position returned
  - Remember to `fopen` the file with all the necessary modes

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# Big Array Transformation

Rewrite your Array Transformation program so that the transformation is performed by a function which takes the array to be processed as an argument.

- use VLA array in your first version
- check you program with  $size = 1000, 10000, 100000$
- does this work with automatic array declarations?
- after you checked, use `malloc` to dynamically allocate the array
- remember to use `free` on dynamically allocated variables

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# Array Transformation With Unknown Dimensions

Rewrite your array transformation program so that it reads input data from the file

- write a file containing a floating point number on each line
- let the first line contains the number of subsequent lines in the file (int)
- Once you read the first line, you can call `calloc` to allocate enough space to hold data
- Don't forget to check if `calloc` succeeded

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Rewrite your linear algebra functions so to allocate your matrices with `malloc`.

- remove printing functions
- use BLAS library to check results
- cast your argument appropriately